

# Gmunu: Toward multigrid based Einstein field equations solver for general-relativistic hydrodynamics simulations

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Gmunu: Multigrid methods for solving Einstein field equations

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# Outline

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# Introduction

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- ▶ Implementation details of Gmunu (P. C. K. CHEONG et al., in prep.)
- ▶ Why numerical simulations
- ▶ Introduction of CCSNe and its gravitational waves
- ▶ Develop a code for:
  - ▶ Core-collapse supernovae
  - ▶ Isolated Neutron stars

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# Supernovae

- ▶ Type II, Ib, Ic
- ▶ Iron core of a Massive star ( $\sim 10 \sim 100M_{\odot}$ )
- ▶  $O(10^{53})$  ergs released in gravitational collapse
- ▶  $\sim 99\%$  of the energy is radiated in neutrinos
- ▶ Neutron star or black hole remanant

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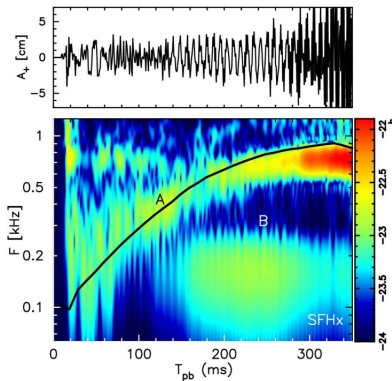
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# Why we need simulations

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We need numerical simulations!



T. Kuroda+ 2016

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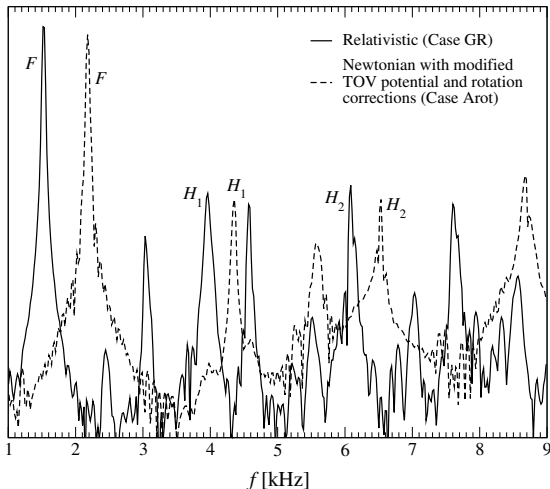
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B. Muller, et al. 2008

General relativistic simulations is needed!

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## Different ways to solve Einstein equations

- ▶ “free-evolution” formulations
- ▶ constrained formulation
  - ▶ elliptic sector and hyperbolic sector

Conformally fatness approximation (CFC) is applied successfully in various astrophysical problems even in spherical-polar coordinate

However...

- ▶ high computational cost for elliptic equations
- ▶ on the fly simulation?

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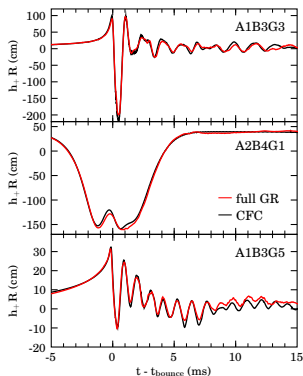
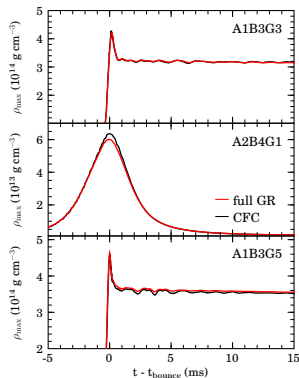
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# Conformally flatness approximation

## CFC approximation

$$g_{\mu\nu} = \begin{bmatrix} -\alpha^2 + \beta_i\beta^i & \beta_1 & \beta_2 & \beta_3 \\ \beta_1 & \varphi^4 & 0 & 0 \\ \beta_2 & 0 & \varphi^4 r^2 & 0 \\ \beta_3 & 0 & 0 & \varphi^4 r^2 \sin^2 \theta \end{bmatrix}$$





# Hydro

## The 3+1 "Valencia" formulation

$$\partial_t(\sqrt{\gamma}\vec{U}) + \partial_i(\sqrt{\gamma}\vec{F}^i) = \vec{S}$$

where

$$U = \begin{bmatrix} D \\ S_j \\ \tau \end{bmatrix} = \begin{bmatrix} \rho W \\ \rho h W^2 v_j \\ \rho h W^2 - p - D \end{bmatrix},$$

$$F^i = \begin{bmatrix} D(v^i - \beta^i/\alpha) \\ S_j(v^i - \beta^i/\alpha) + \delta_j^i D \\ \tau(v^i - \beta^i/\alpha) + P v^i \end{bmatrix},$$

$$Q = \begin{bmatrix} 0 \\ T^{\mu\nu} \left( \frac{\partial g_{\nu j}}{\partial x^\mu} - \Gamma_{\mu\nu}^\lambda g_{\lambda j} \right) \\ \alpha \left( T^{\mu 0} \frac{\partial \ln \alpha}{\partial x^\mu} - T^{\mu\nu} \Gamma_{\mu\nu}^0 \right) \end{bmatrix}$$

Plus EOS

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Cordero-Carrion et al. (2009)

$$\tilde{\Delta} X^i + \frac{1}{3} \tilde{\nabla}^i (\tilde{\nabla}_j X^j) = 8\pi \tilde{S}^i$$

$$\tilde{A}^{ij} \approx \tilde{\nabla}^i X^j + \tilde{\nabla}^j X^i - \frac{2}{3} \tilde{\nabla}_k X^k f^{ij}$$

$$\tilde{\Delta} \psi = -2\pi \tilde{E} \psi^{-1} - \frac{1}{8} f_{ik} f_{jl} \tilde{A}^{kl} \tilde{A}^{ij} \psi^{-7}$$

$$\tilde{\Delta} (\alpha \psi) = (\alpha \psi) \left[ 2\pi (\tilde{E} + 2\tilde{S}) \psi^{-2} + \frac{7}{8} f_{ik} f_{jl} \tilde{A}^{kl} \tilde{A}^{ij} \psi^{-8} \right]$$

$$\tilde{\Delta} \beta^i + \frac{1}{3} \tilde{\nabla}^i (\tilde{\nabla}_j \beta^j) = 16\pi \alpha \psi^{-6} f^{ij} \tilde{S}_i + 2\tilde{A}^{ij} \tilde{\nabla}_j (\alpha \psi^{-6})$$

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# Boundary condition

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Robin B. C.

$$\left. \frac{\partial \psi}{\partial r} \right|_{r_{\max}} = \frac{1 - \psi}{r}$$

$$\left. \frac{\partial \alpha}{\partial r} \right|_{r_{\max}} = \frac{1 - \alpha}{r}$$

$$\left. \beta^i \right|_{r_{\max}} = 0$$

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# Elliptic solvers

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Table: Elliptic solvers

Method	Complexity (accuracy $\epsilon$ )
Gauss Elimination	$O(N^2)$
Jacobi iteration	$O(N^2) \log(\epsilon)$
Gauss-Seidel iteration	$O(N^2) \log(\epsilon)$
SOR	$O(N^{3/2}) \log(\epsilon)$
Conjugate Gradient	$O(N^{3/2}) \log(\epsilon)$
ADI	$O(N \log(N)) \log(\epsilon)$
FFT	$O(N \log(N))$
Multigrid (iterative)	$O(N) \log(\epsilon)$
Multigrid (FMG)	$O(N)$

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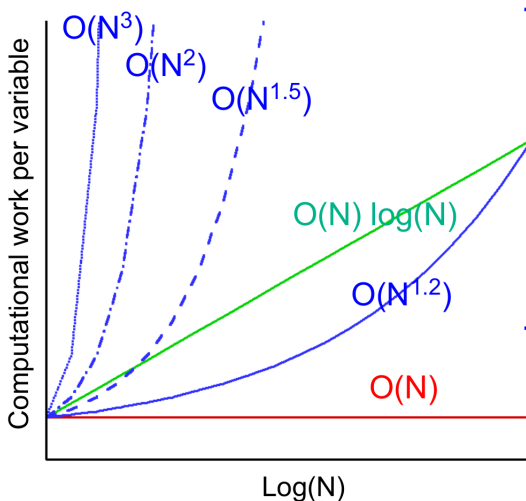
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# Elliptic solvers



credit: Klaus Stuben

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# Elliptic solvers

- ▶ LORENE using spectral methods for CFC
- ▶ require accurate grid communication

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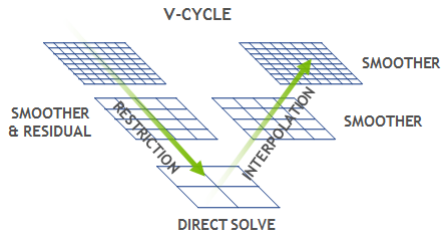
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# Multigrid Method

- ▶ A strategy, not a single method
- ▶ various possible implementation
- ▶ fast and efficient
- ▶ suitable for non-linear problems
- ▶ no grid communication is needed



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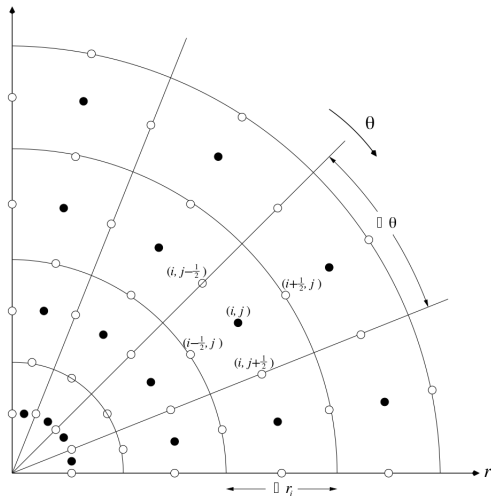
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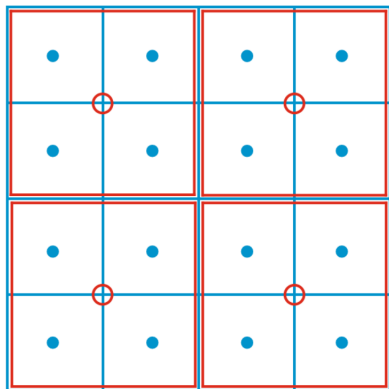
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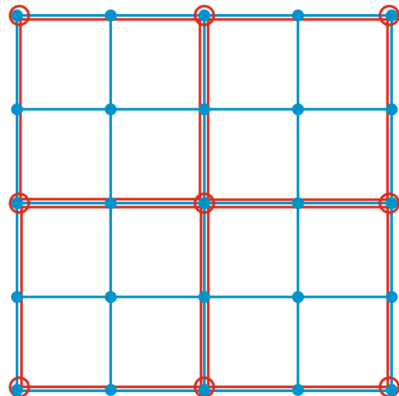
cell-centered grid  
Dimmelmeier et al. (2002)

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(a) Cell-Centered Grid



(b) Vertex-Centered Grid

credit: Hooshyar (2014)

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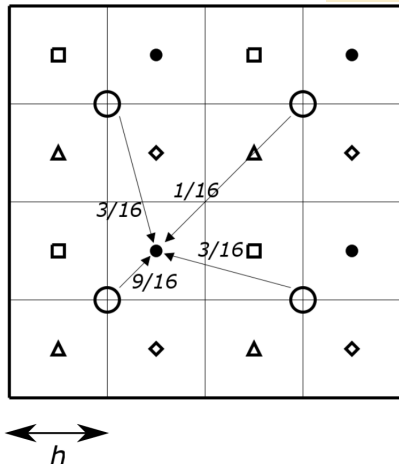
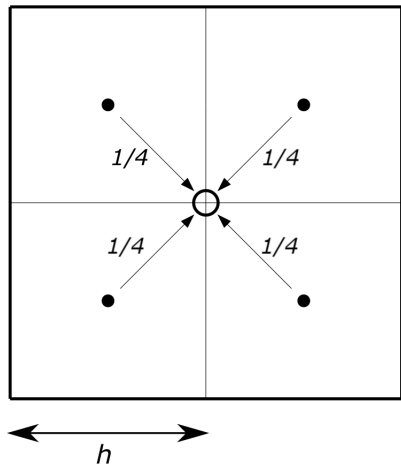
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# Multigrid Method

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- ▶ Restriction (Left): piecewise constant
- ▶ Prolongation (Right): bi-linear



credit: F. W. Yang et al. (2015)

# Code features

Gmunu (General-relativistic multigrid numerical Einstein solver)

- ▶ 3+1 in Spherical polar coordinates (1,2,3-D)
- ▶ Hydro: high-resolution shock-capturing (HRSC) methods
  - ▶ Reconstruction method: Piecewise-Constant (PC), TVD, (5-th order)WENO, MP5
  - ▶ Riemann solver: HLL, HLLC, Marquina
  - ▶ Time update: RK3 methods
  - ▶ Conserved variables to Primitive variables: Regula-Falsi method
- ▶ Conformally flatness condition(CFC) metric evolution:
  - ▶ extended CFC (xCFC) scheme (Cordero-Carrion et al. (2009))
  - ▶ Multigrid solver for the elliptic non-linear coupled equations

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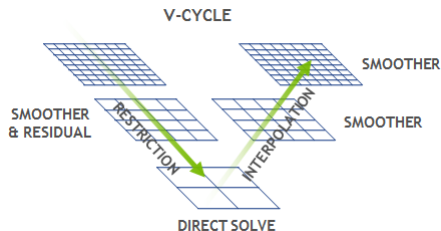
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# Key features of our MG solver

- ▶ Nonlinear FAS (Full Approximation Storage) algorithm
- ▶ Cycles options: V, W and F
- ▶ Cell-Centered discretization (no grid communication is needed)
- ▶ Smoother: Red-Black Gauss-Seidel relaxation
- ▶ Prolongation: bi-linear
- ▶ Restriction: piecewise constant



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$$L(u) = f$$

V-cycle

**if**  $l = 1$  **then**

|  $u_l \leftarrow \text{Solve}(u_l)$

**else**

|  $u_l \leftarrow \text{Smoothing}(u_l, f_l)$  ! Pre-smoothing

|  $r_l \leftarrow f_l - L_l(u_l)$  ! residual

|  $\text{Restriction}(r_l, u_l)$

|  $f_{l-1} \leftarrow r_{l-1} + L_{l-1}(u_{l-1})$

|  $v \leftarrow u_{l-1}$

| ! Recursive call for the coarse grid correction

|  $v \leftarrow \text{MG}(v, f_{l-1})$

|  $u_l \leftarrow u_l + \text{Prolongation}(v - u_{l-1})$

|  $u_l \leftarrow \text{Smoothing}(u_l, f_l)$  ! Post-smoothing

**end**

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# Implementation note

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Define

$$\tilde{U} \equiv \psi^6 U$$

$$\tilde{F}^i \equiv \psi^6 F^i$$

$$\tilde{Q} \equiv \psi^6 Q$$

$$\frac{\partial \tilde{U}}{\partial t} + \frac{1}{r^2} \frac{\partial}{\partial r} \left( \alpha r^2 \tilde{F}^r \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \alpha \sin \theta \tilde{F}^\theta \right) = \alpha \tilde{Q}.$$

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# Models

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**Table:**  $\Gamma = 2$ ,  $K = 100$ , ( $c = G = M_{sun} = 1$ ).

Model	$\rho_c [10^{-3}]$	$\Omega [10^{-2}]$
BU0	1.28	0.000
SU	8.00	0.000
BU2	1.28	1.509
BU8	1.28	2.633

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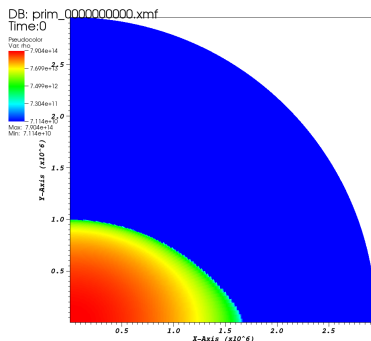
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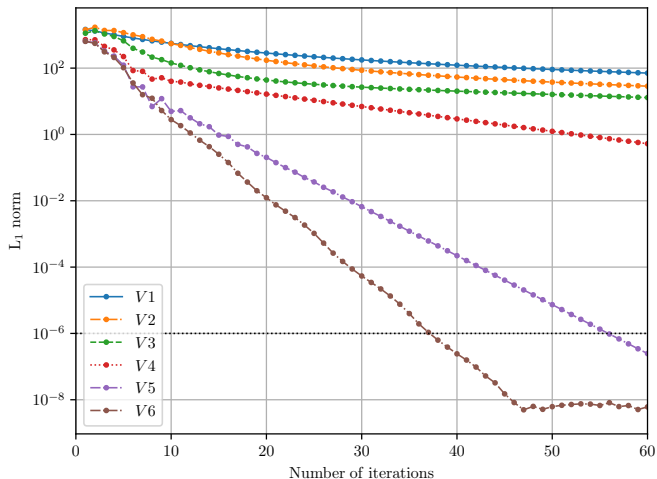
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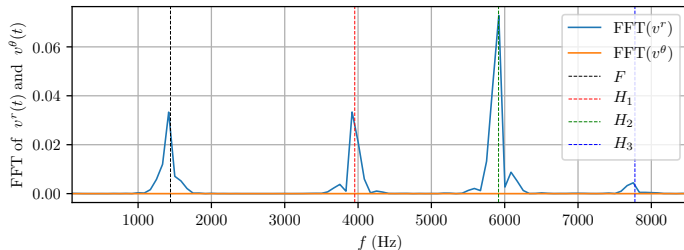
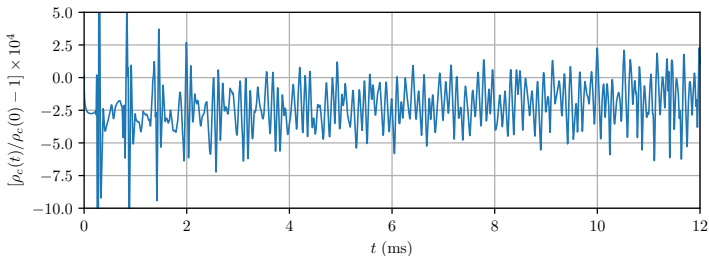
# Convergence properties

- ▶ solving the  $\alpha$  of BU8 with initial guess:  $\alpha = 1$
- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶ Gauss-Seidel ( $\sim 5.3 \times 10^5$ ) to MG ( $\sim 50$ )
- ▶  $O(\text{minus}) \rightarrow O(\text{ms})$



# Model: BU0

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$



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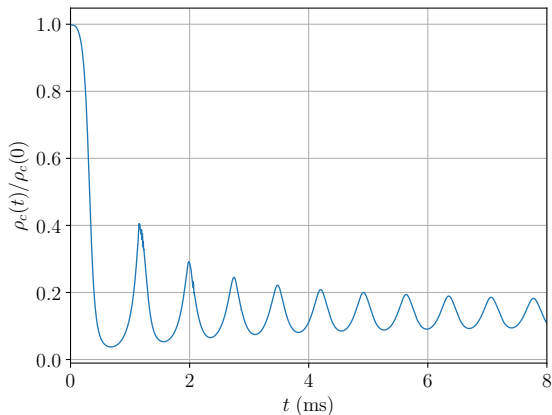
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# Model: SU

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## Migration test: unstable $\rightarrow$ stable NS

- ▶  $n_r \times n_\theta = 1024 \times 1$  (1D simulation)
- ▶  $r = [0, 34]$



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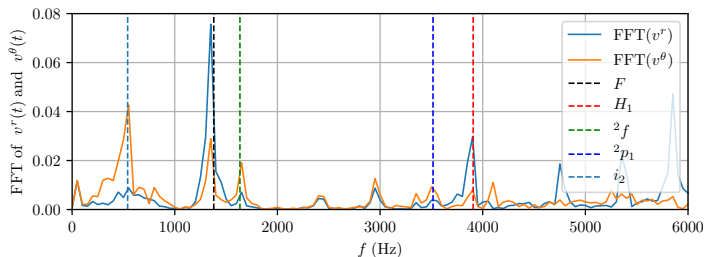
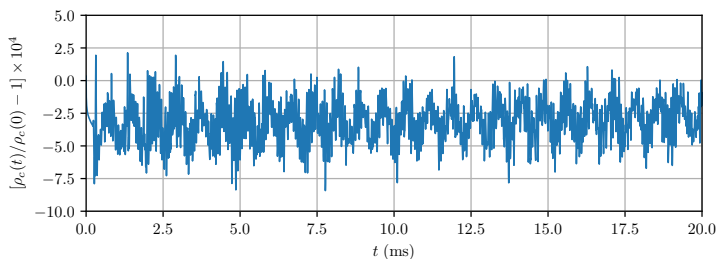
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# Model: BU2

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$



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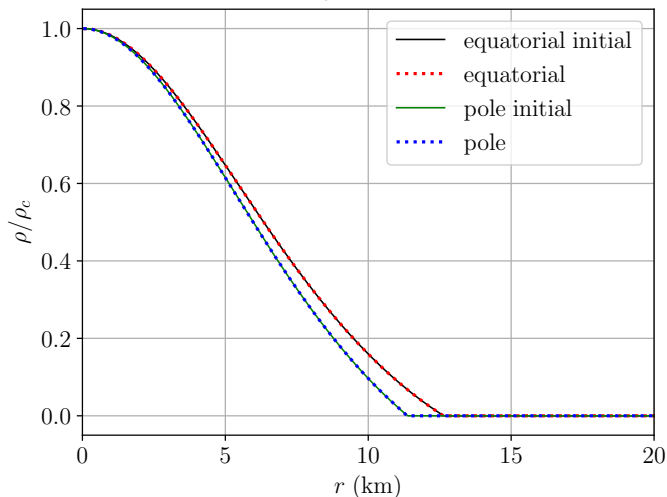
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# Model: BU2

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$

$$T_{\max} = 20 \text{ ms}$$



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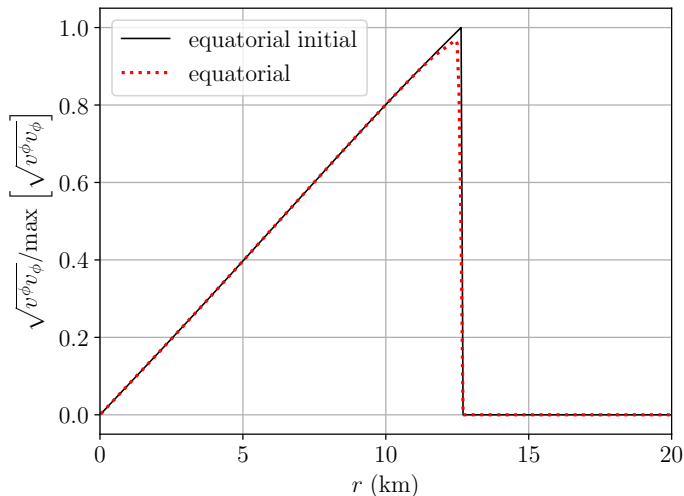
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# Model: BU2

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$

$T_{\max} = 20$  ms



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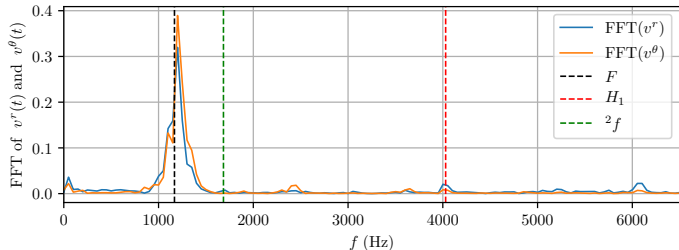
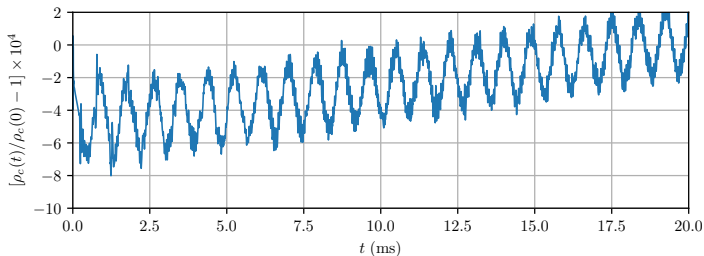
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# Model: BU8

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$



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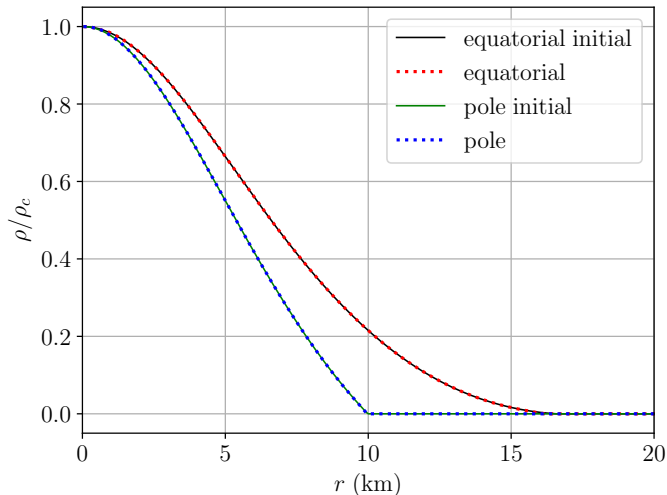
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# Model: BU8

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$

$$T_{\max} = 20 \text{ ms}$$



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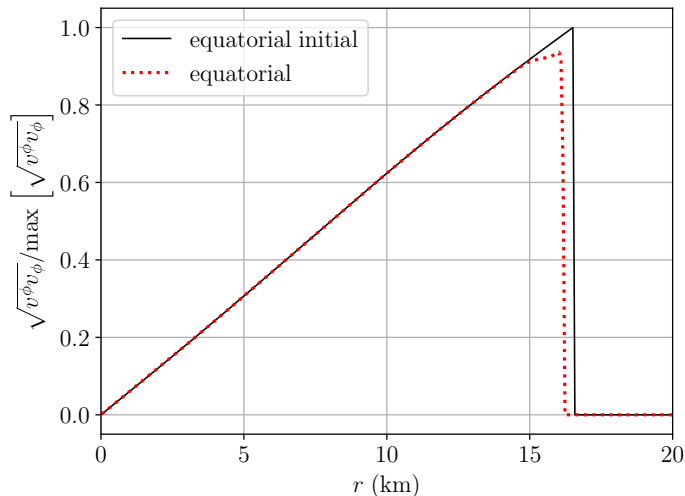
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# Model: BU8

- ▶  $n_r \times n_\theta = 640 \times 64$
- ▶  $r = [0, 30], \theta = [0, \frac{\pi}{2}]$

$$T_{\max} = 20 \text{ ms}$$



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# Conclusions

- ▶ We presented our Multigrid metric solver
- ▶ Fast and accurate!
  - ▶ for  $\epsilon \sim 10^{-7}$
  - ▶  $O(\text{minus}) \rightarrow O(\text{ms})$  per equation
  - ▶ solving the metric  $\sim 5$  to  $10$  hydro steps (stable NS)
  - ▶ no need to solve the metric at every time steps
- ▶ suitable for dynamical simulations

## Future direction

- ▶ extend to FCF (fully-constrained formalism)
- ▶ upgrade and parallelization
- ▶ apply to study astrophysical problems

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