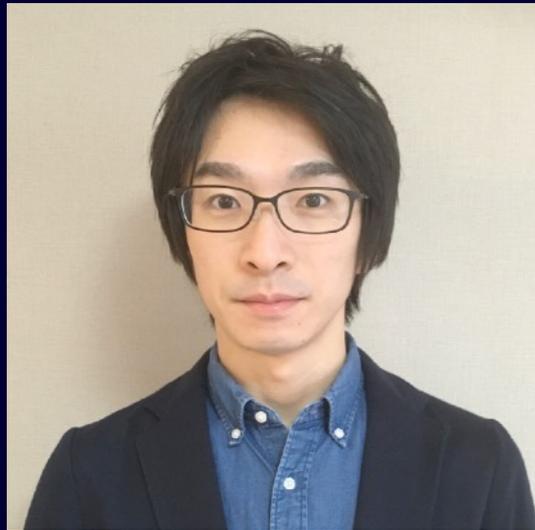


Progress of observation in LIGO and challenge with Taiwanese gravitational physics research facility for future R&D

National Central University & Academia Sinica
Yuki Inoue



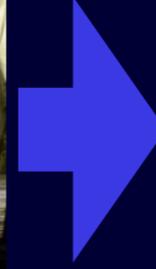
Introduce myself



Yuki Inoue

Assistant professor in National Central University
Adjunct Assistant research fellow in Academia Sinica

- Research history:
 - 2011-2016: POLARBEAR/Simons Array (Cosmic Microwave Background)
 - 2016-2021: KAGRA (Gravitational Wave experiment in Japan)
 - Calibration and Reconstruction
 - 2021-: LIGO(Gravitational Wave experiment in US) + Future R&D



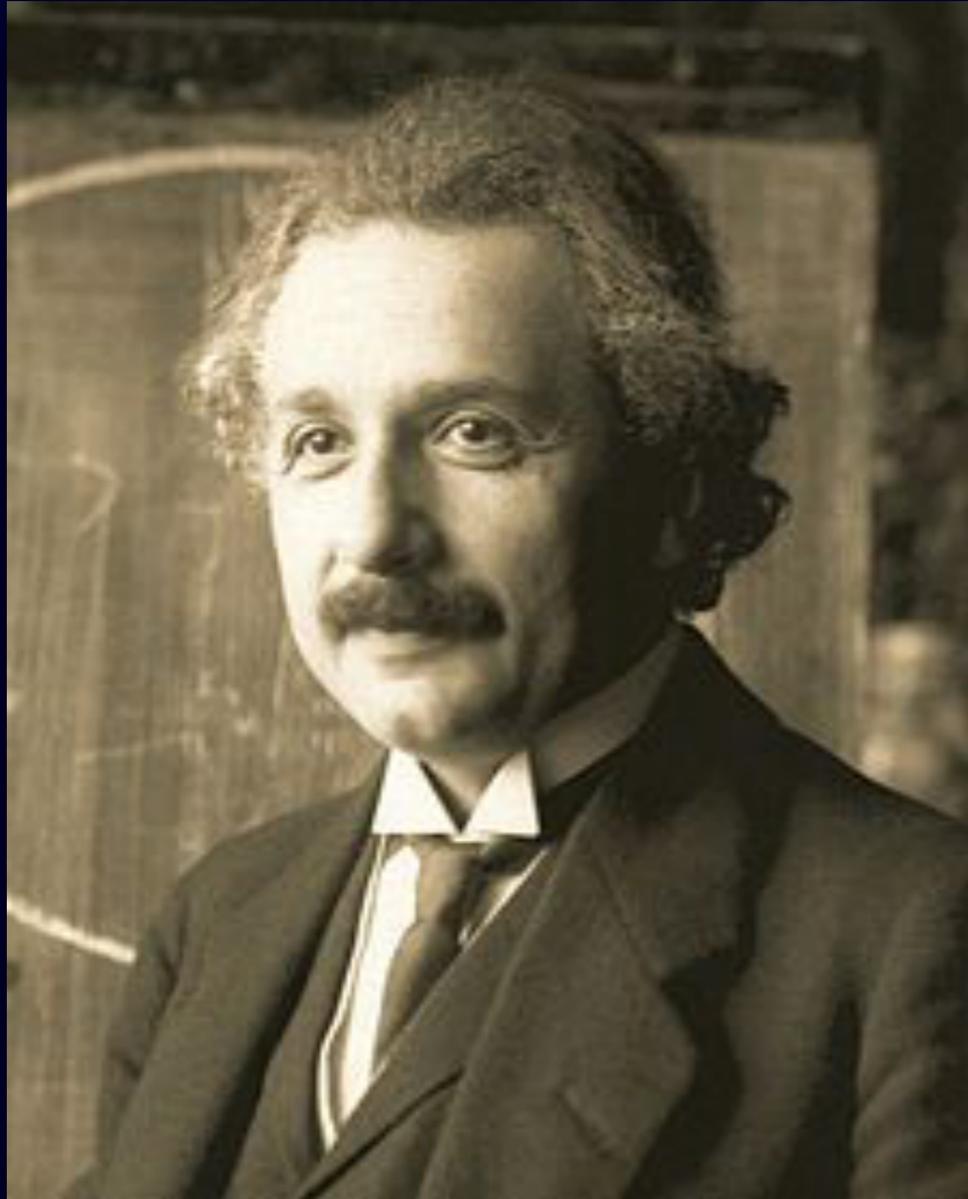
Outline

- Introduction
 - LIGO
 - Contribution of Taiwan
 - ASGRAF and CHRONOS
 - Progress of ASGRAF construction
 - Summary
-



Introduction

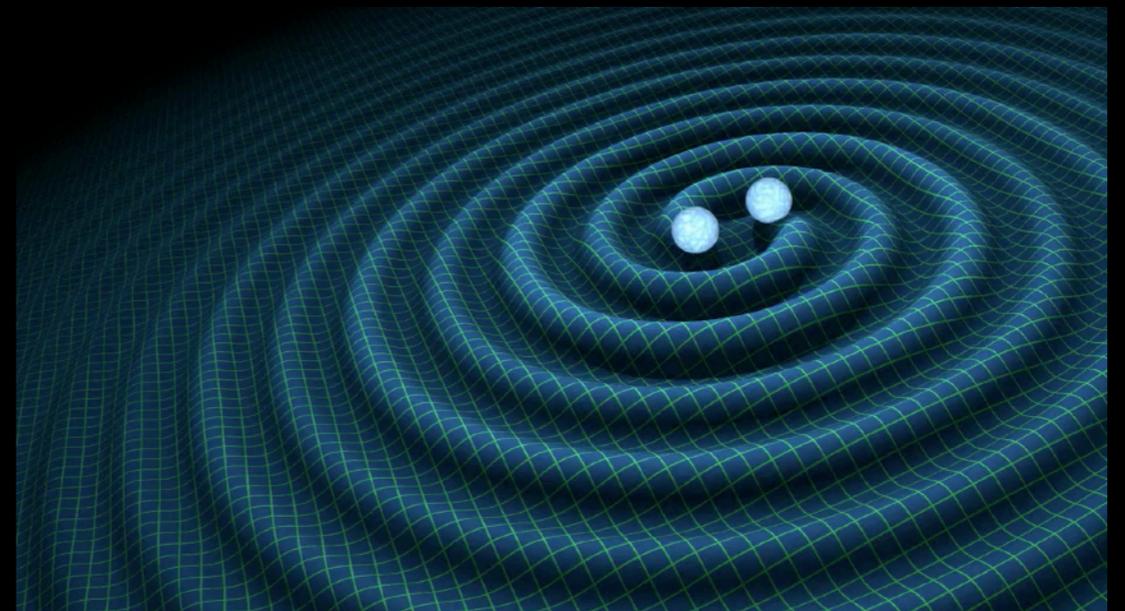
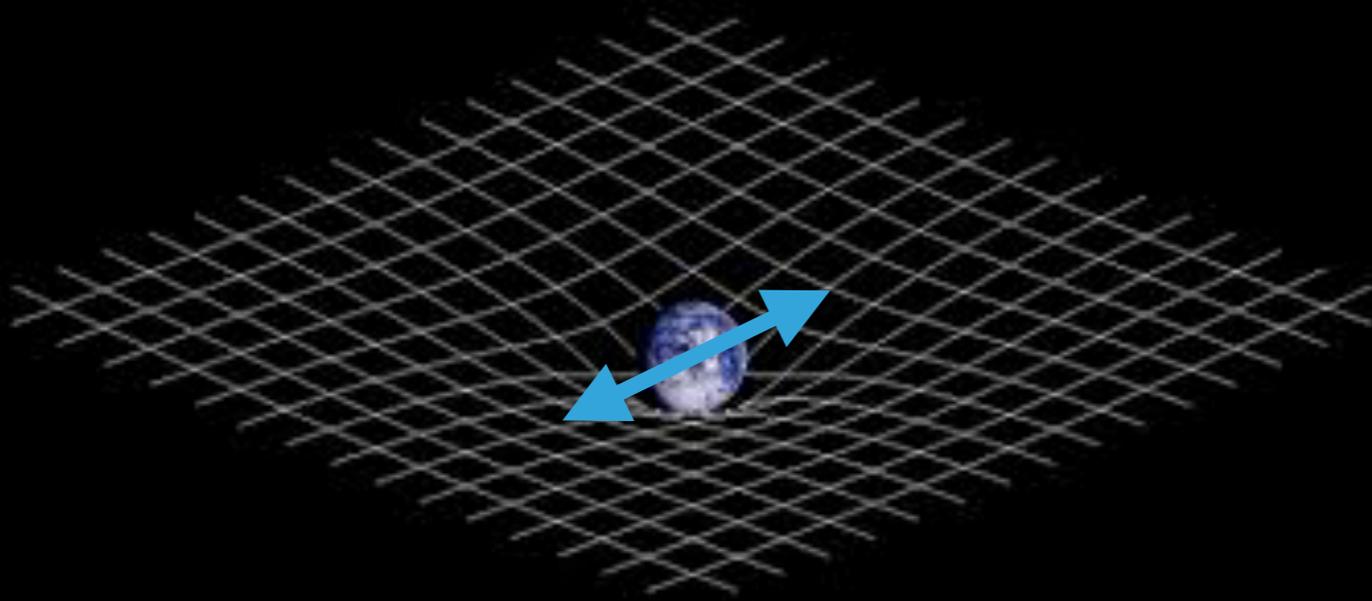
Introduction



- Albert Einstein
- 1916 General Relativity
 - ‘Distortion of Space and Time’
- One of the most important predictions:

Gravitational Wave!

How to generate Gravitational Waves



- GW is generated by the oscillation of the massive object.
 - Binary system is one of the candidate of it.
-

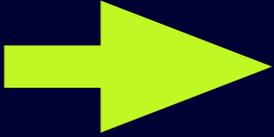
Metric

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu$$

Metric

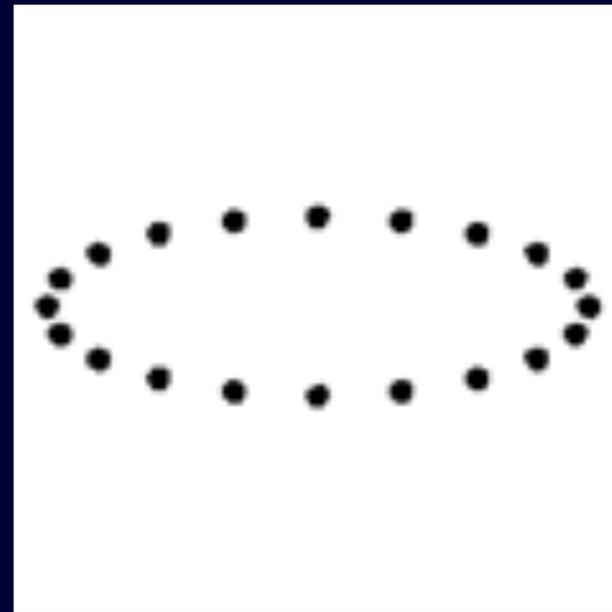
$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$$

Perturbation


$$\left(\frac{\partial^2}{\partial x^2} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) h = 0$$

$$h_{ij} = A_{ij} \times \exp [i(\omega t - kz)]$$

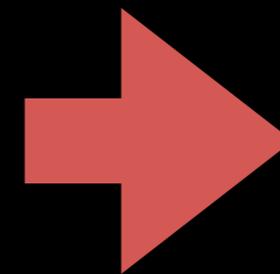
$$A_{ij} = \begin{bmatrix} h_+ & h_\times & 0 \\ h_\times & -h_+ & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



Typical gravitational wave strain sensitivity

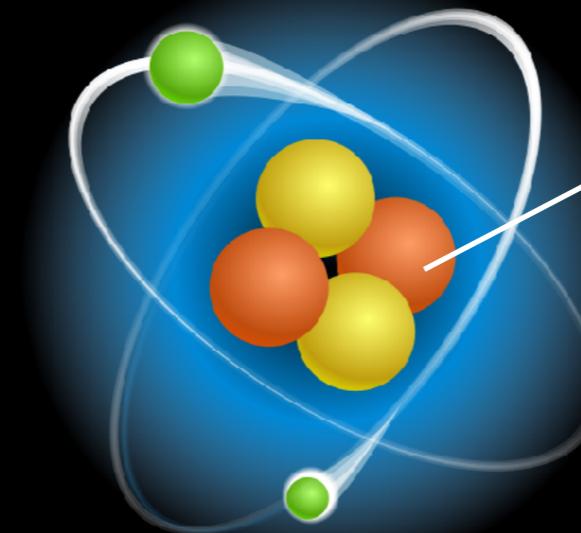
$$h \sim \frac{2G}{c^4 R} \ddot{I} \sim \frac{r_g}{R} = \frac{\text{Schwarzschild radius}}{\text{Distance from the source}}$$

Solar mass NS-NS: $r_g \sim 3\text{km}$
 Typical distance: 100Mpc



$$h \sim \delta L / L \sim 10^{-21}$$

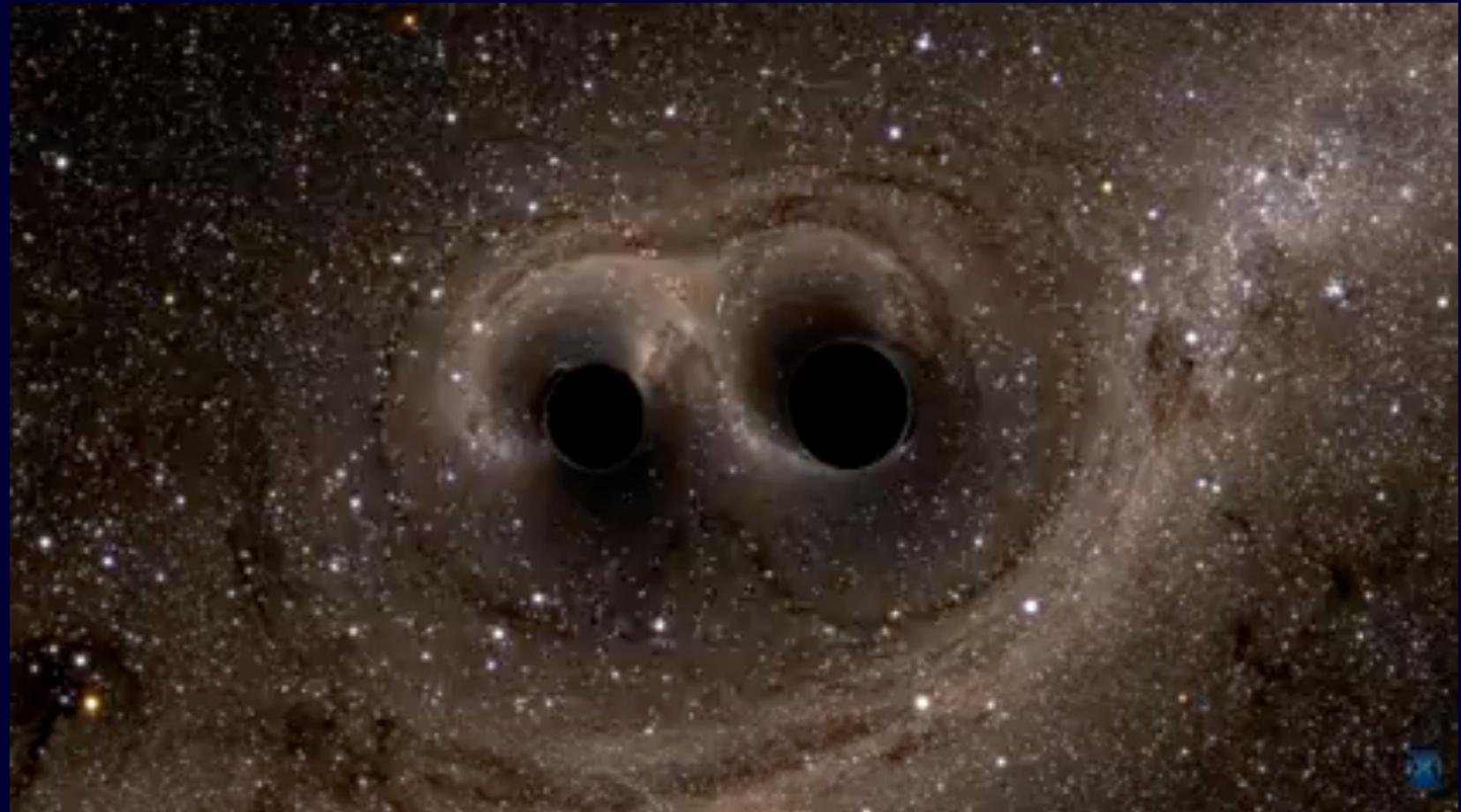
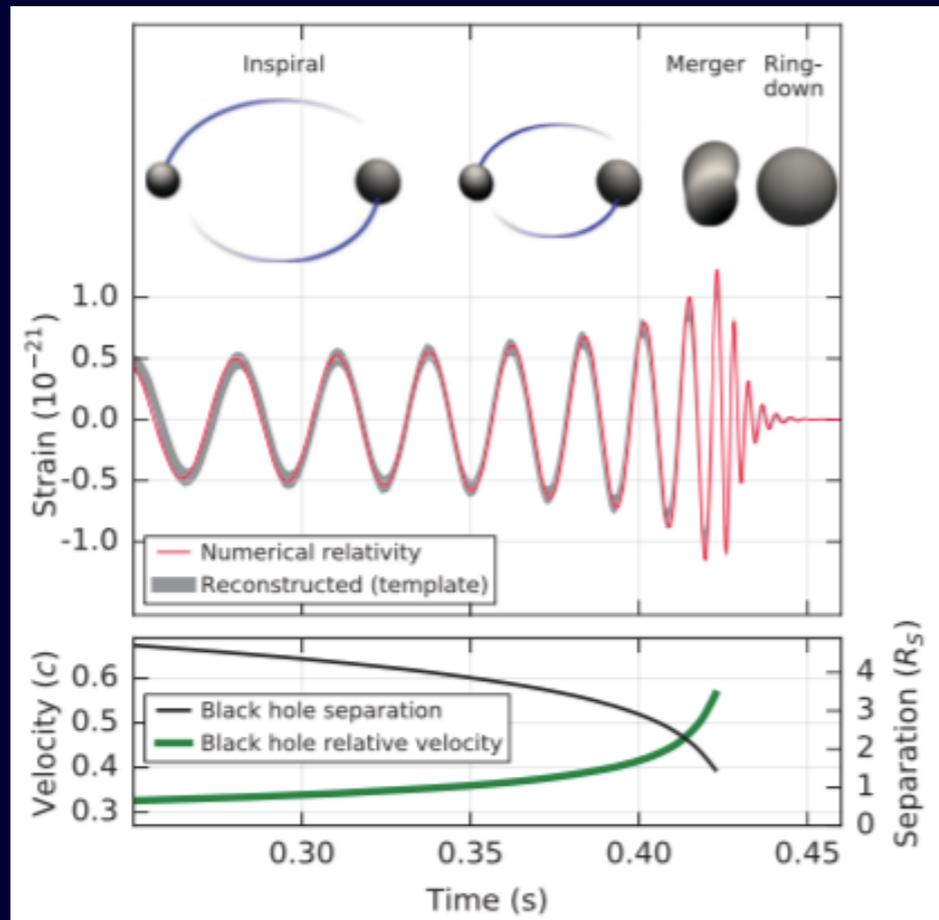
$$\delta L \sim 2000\text{km} \times 10^{-21} \\ \sim 10^{-15}\text{m} \sim 1\text{fm}$$



Proton radius

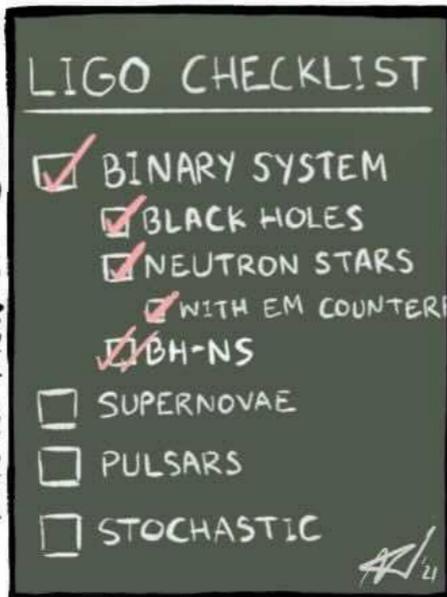
Amplitude of G_W is very tiny

Compact Binary Coalescence



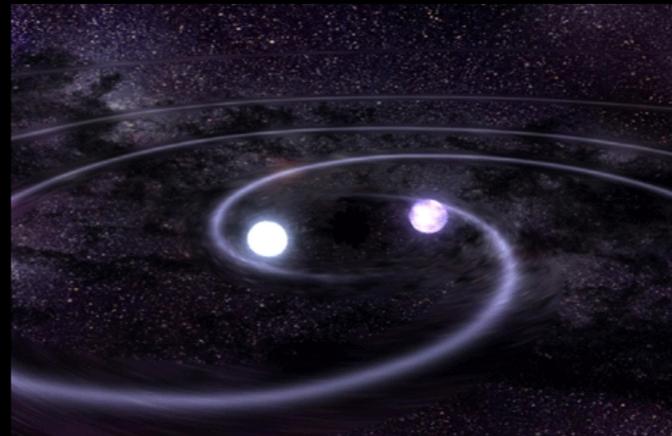
- BH-BH, BH-NS, and NS-NS (BH= Black hole, NS= Neutron Star)
- Observed as Unique Chirp signal
- LIGO and Virgo can observe it every 10 days

Gravitational wave source



NUTSINEE KIJBUANCHOD © 2020

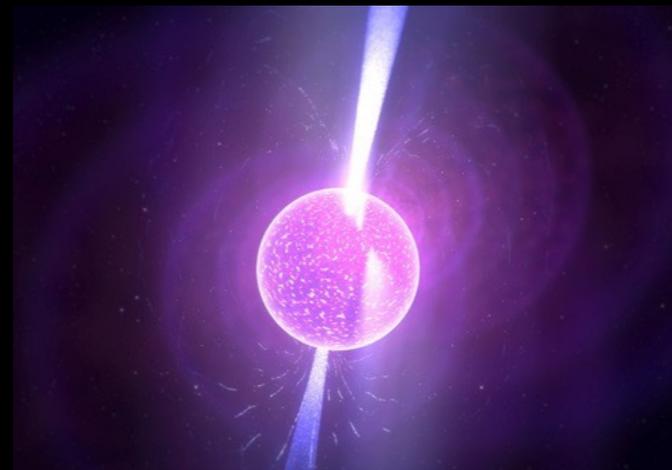
BINARY SYSTEMS



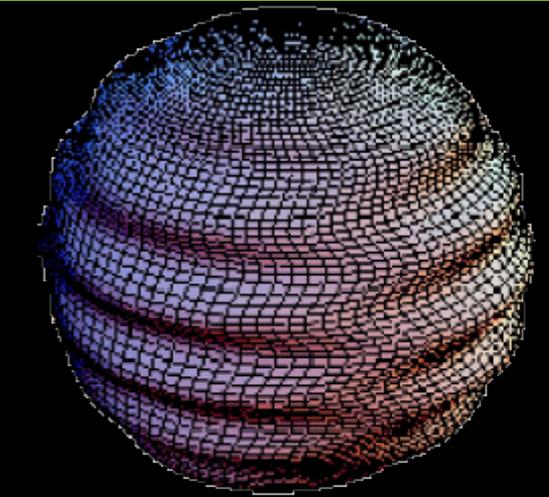
SUPER NOVA



PULSER



STOCHASTIC BACKGROUND

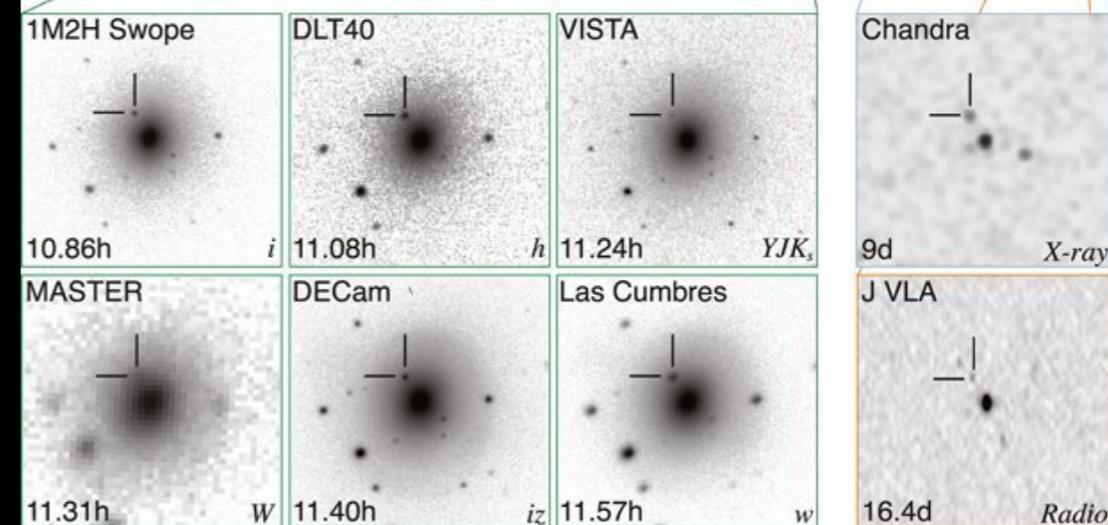
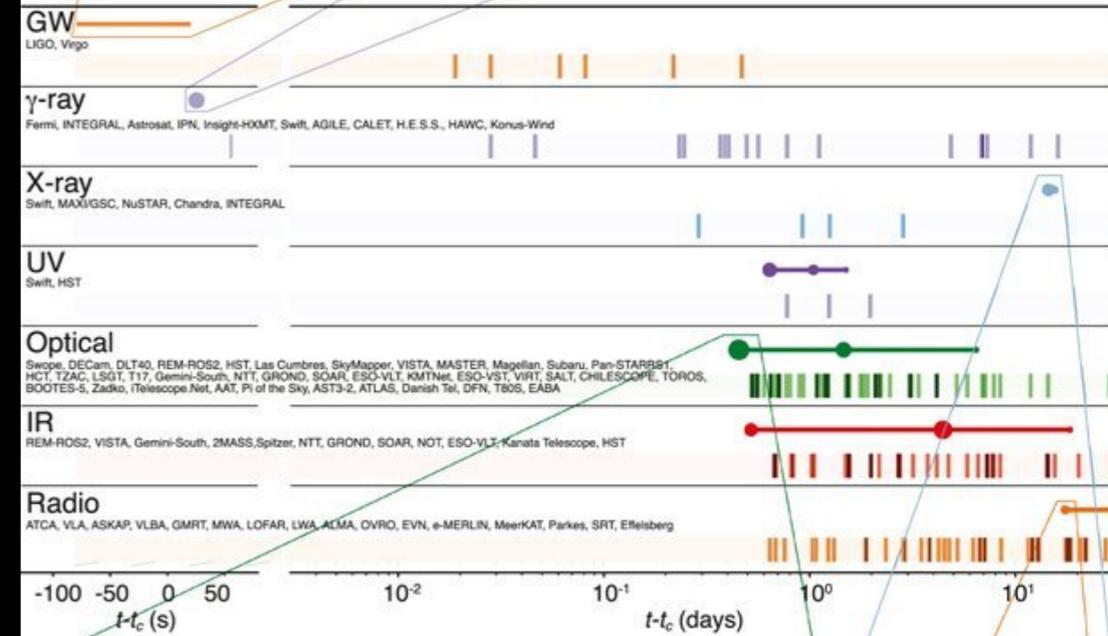
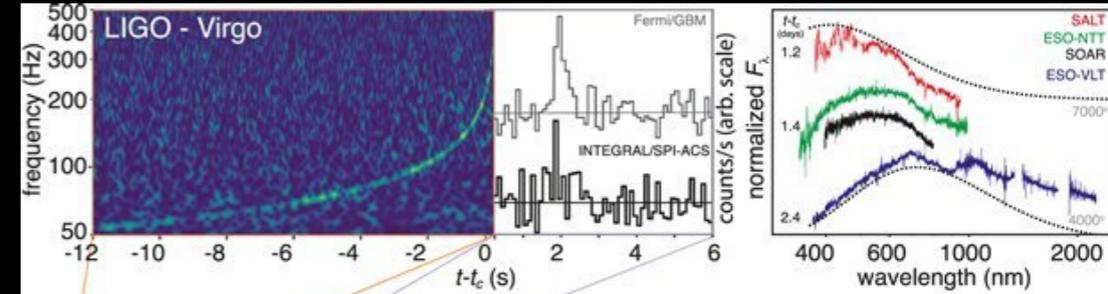


Multimessenger astronomy

GW170817
DECam observation
(0.5–1.5 days post merger)



GW170817
DECam observation
(>14 days post merger)



Element Origins

1 H																	2 He
3 Li	4 Be											5 B	6 C	7 N	8 O	9 F	10 Ne
11 Na	12 Mg											13 Al	14 Si	15 P	16 S	17 Cl	18 Ar
19 K	20 Ca	21 Sc	22 Ti	23 V	24 Cr	25 Mn	26 Fe	27 Co	28 Ni	29 Cu	30 Zn	31 Ga	32 Ge	33 As	34 Se	35 Br	36 Kr
37 Rb	38 Sr	39 Y	40 Zr	41 Nb	42 Mo	43 Tc	44 Ru	45 Rh	46 Pd	47 Ag	48 Cd	49 In	50 Sn	51 Sb	52 Te	53 I	54 Xe
55 Cs	56 Ba	72 Hf	73 Ta	74 W	75 Re	76 Os	77 Ir	78 Pt	79 Au	80 Hg	81 Tl	82 Pb	83 Bi	84 Po	85 At	86 Rn	
87 Fr	88 Ra																
		57 La	58 Ce	59 Pr	60 Nd	61 Pm	62 Sm	63 Eu	64 Gd	65 Tb	66 Dy	67 Ho	68 Er	69 Tm	70 Yb	71 Lu	
		89 Ac	90 Th	91 Pa	92 U												

Merging Neutron Stars
Dying Low Mass Stars

Exploding Massive Stars
Exploding White Dwarfs

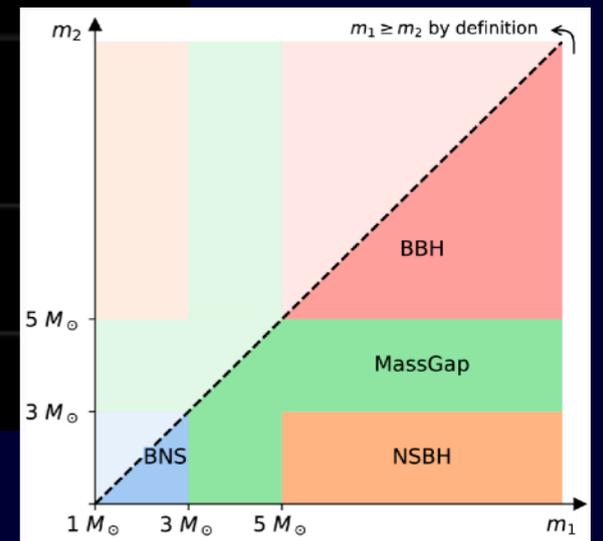
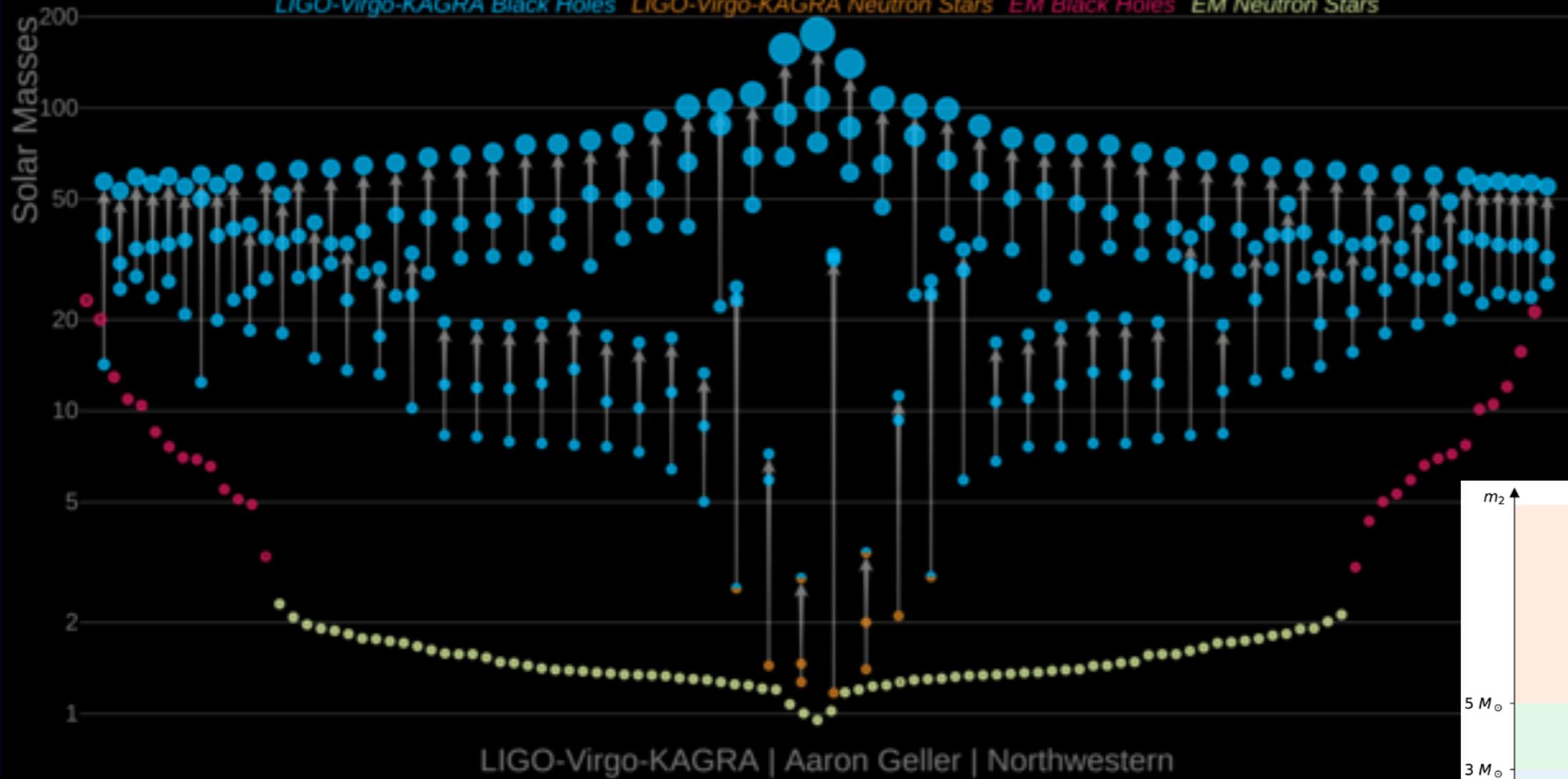
Big Bang
Cosmic Ray Fission

Based on graphic created by Jennifer Johnson

Observation 3 result

Masses in the Stellar Graveyard

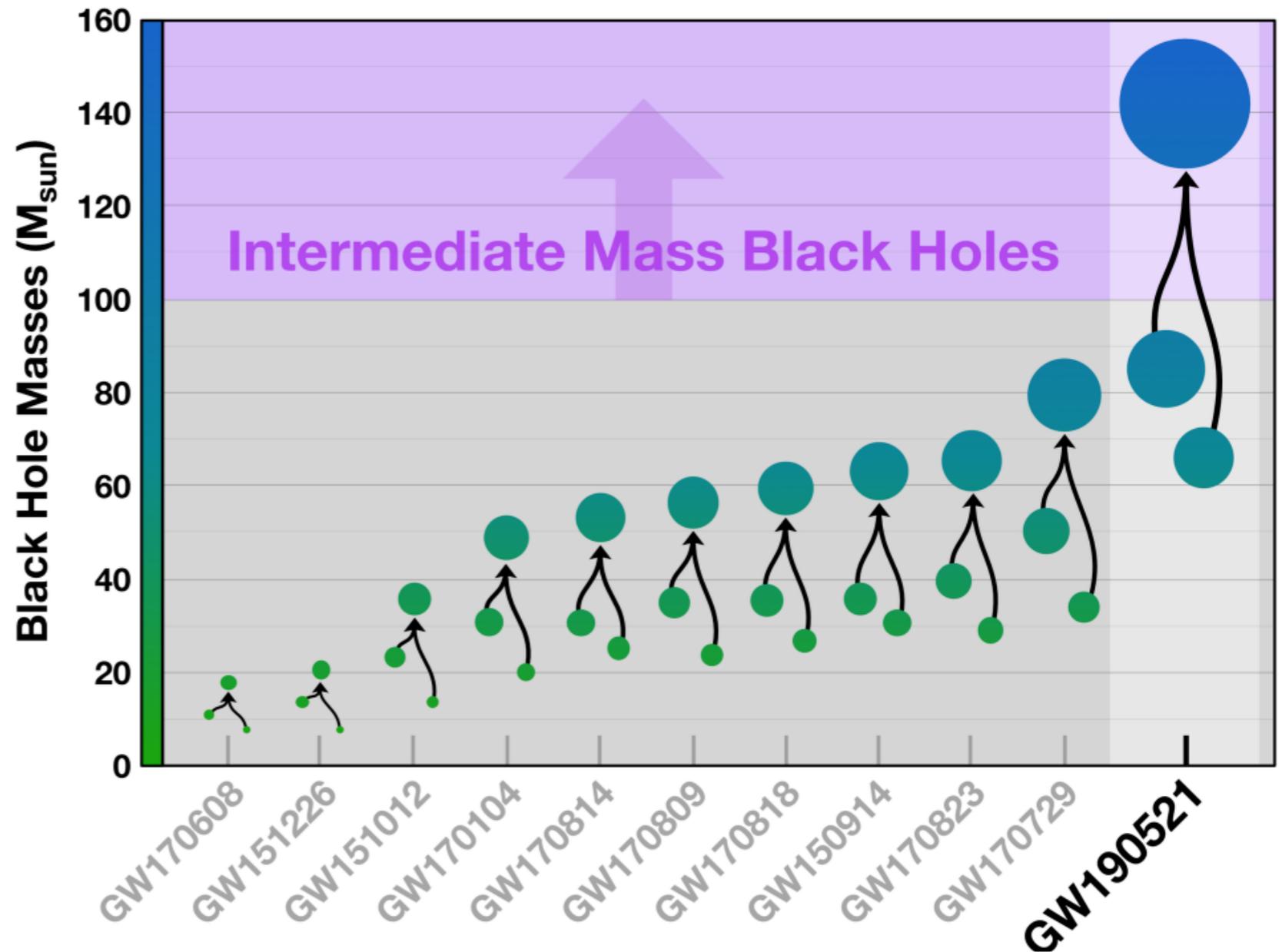
LIGO-Virgo-KAGRA Black Holes LIGO-Virgo-KAGRA Neutron Stars EM Black Holes EM Neutron Stars



Observed IMBHs

NGC No.	distance (kpc) [63]	vel. disp. σ (km/s) [111]	BH mass (M_{\odot})
104	4.5	10.0	794.7
362	8.5	6.2	116.3
1851	12.1	11.3	1299
1904	12.9	3.9	18.04
5272	10.4	4.8	41.57
5286	11.0	8.6	433.4
5694	34.7	6.1	108.9
5824	32.0	11.1	1209
5904	7.5	6.5	140.6
5946	10.6	4.0	19.97
6093	10.0	14.5	3539
6266	6.9	15.4	4508
6284	15.3	6.8	168.6
6293	8.8	8.2	357.9
6325	8.0	6.4	132.4
6342	8.6	5.2	57.35
6441	11.7	19.5	11645
6522	7.8	7.3	224.3
6558	7.4	3.5	11.68
6681	9.0	10.0	794.7
7099	8.0	5.8	88.96

LIGO-Virgo Black Hole Mergers





LIGO

Overview of LIGO

LIGO HANFORD OBSERVATORY

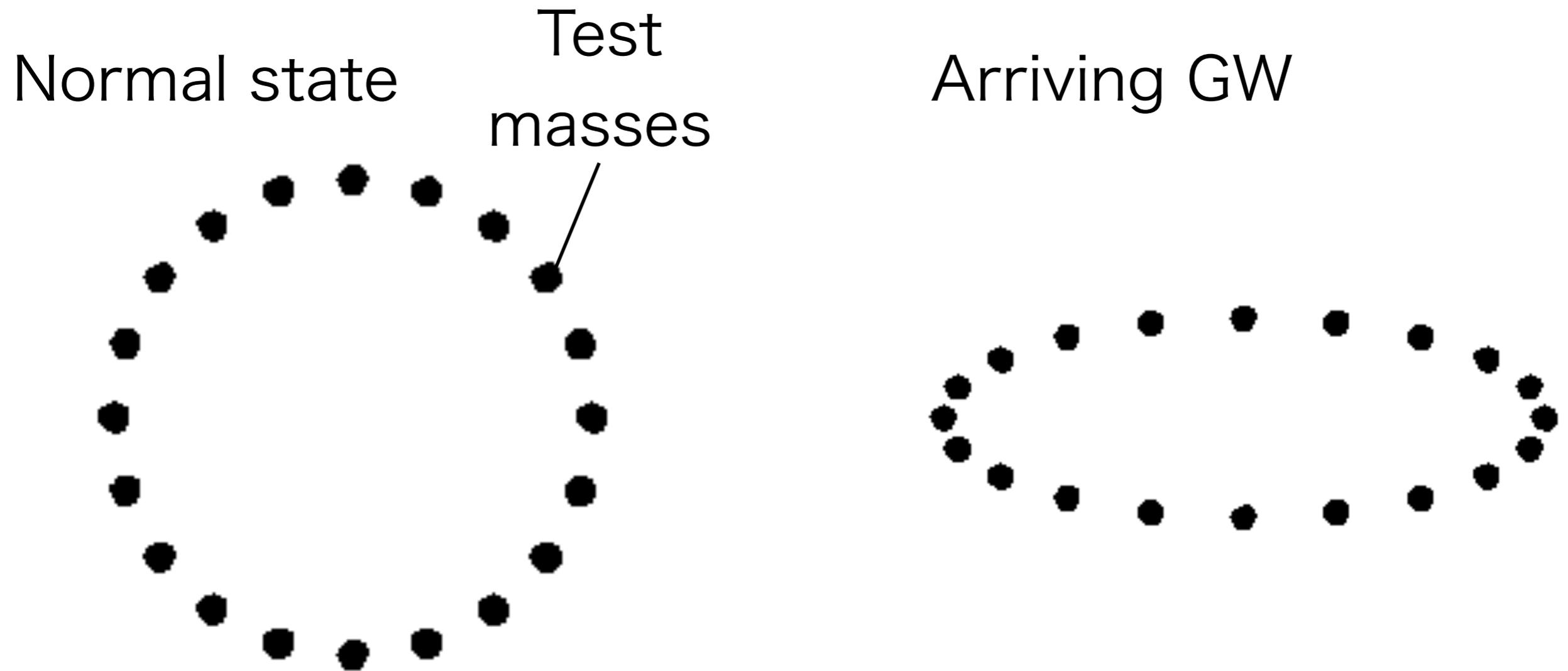


LIGO LIVINGSTON OBSERVATORY



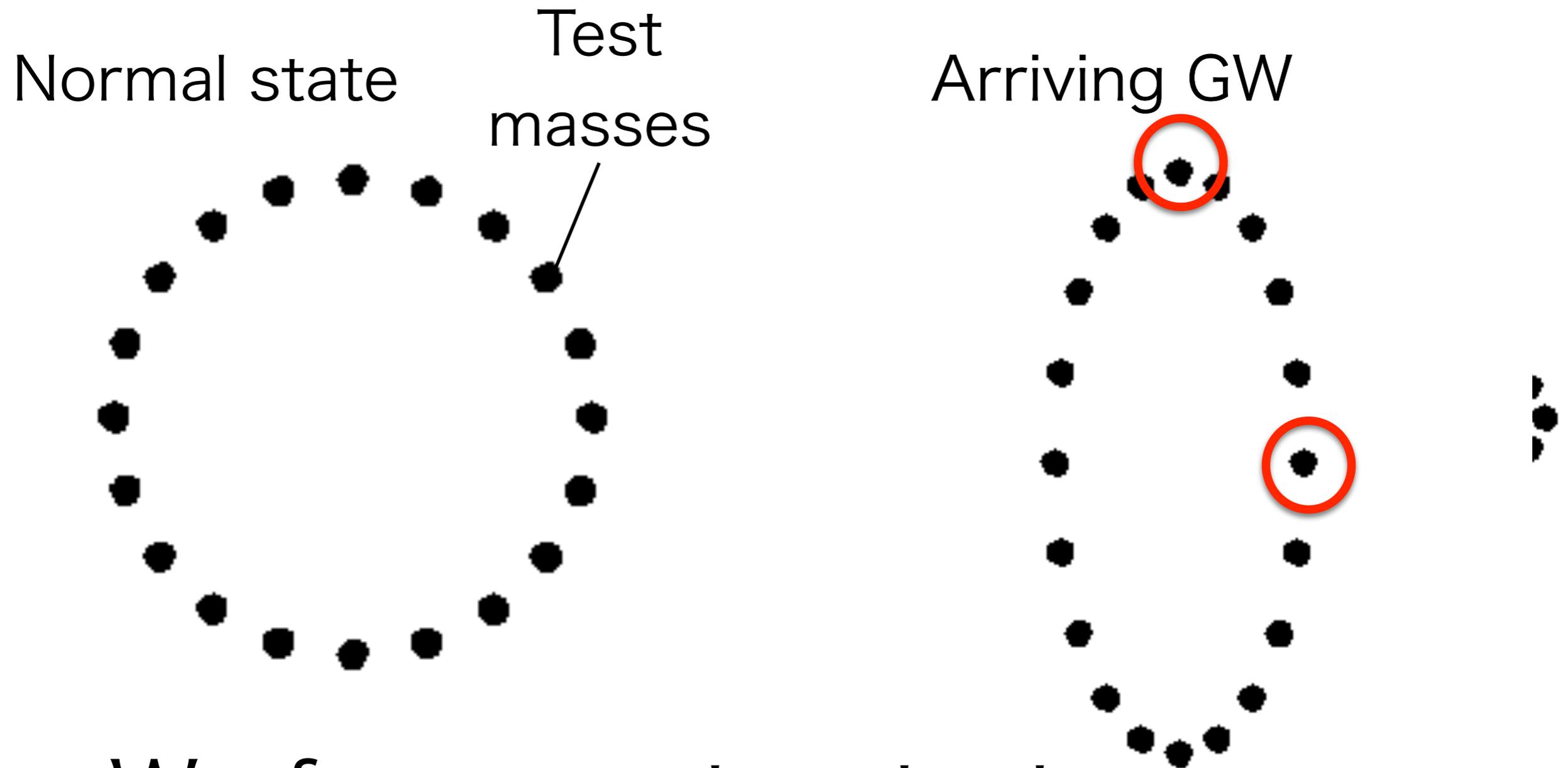
- LIGO is 2nd generation gravitational wave detector.
 - They have two detector systems in Hanford and Livingston.
 - 4km arm length interferometer
-

Principle of Observation



Test masses are moved by GWs.

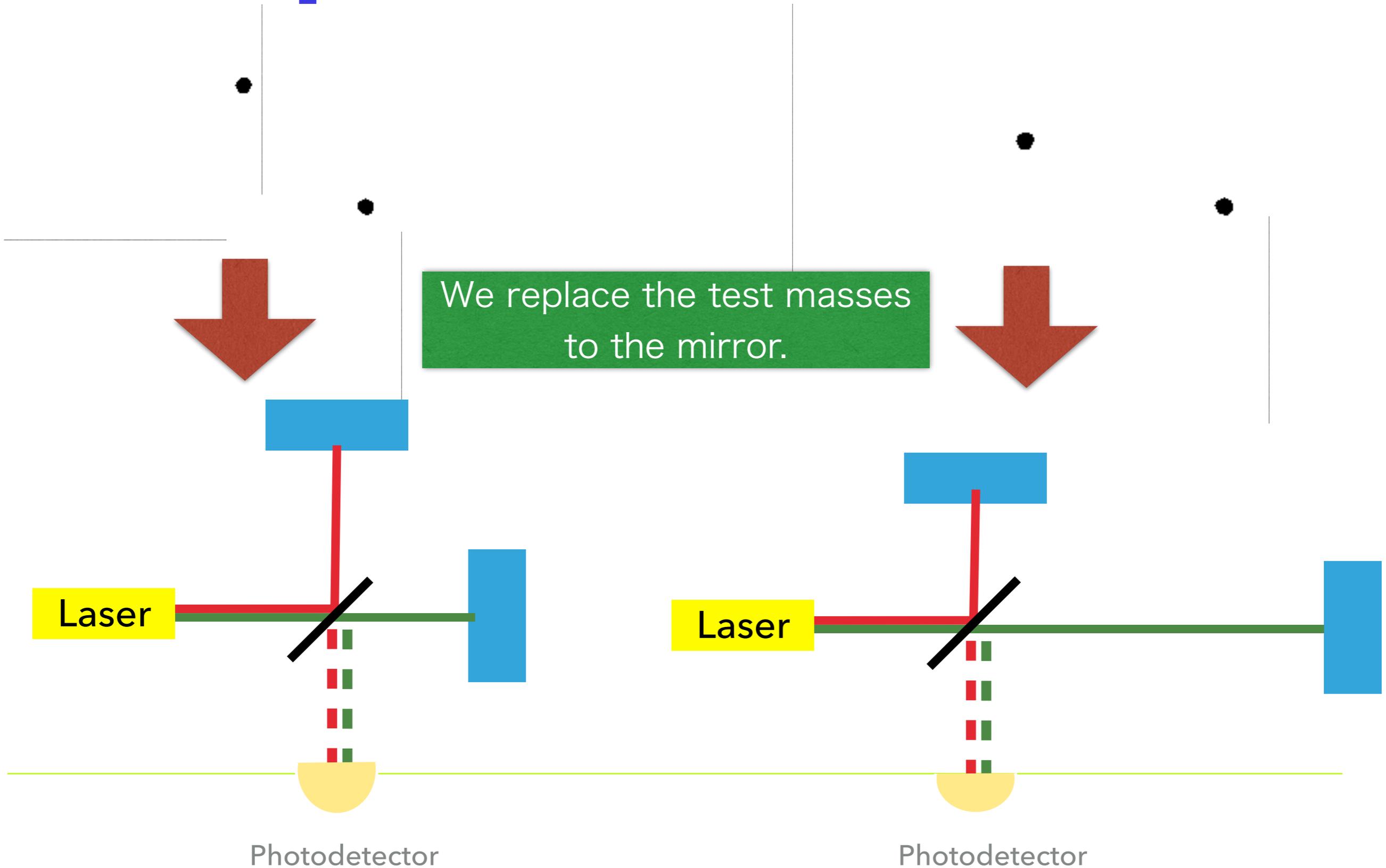
Principle of Observation



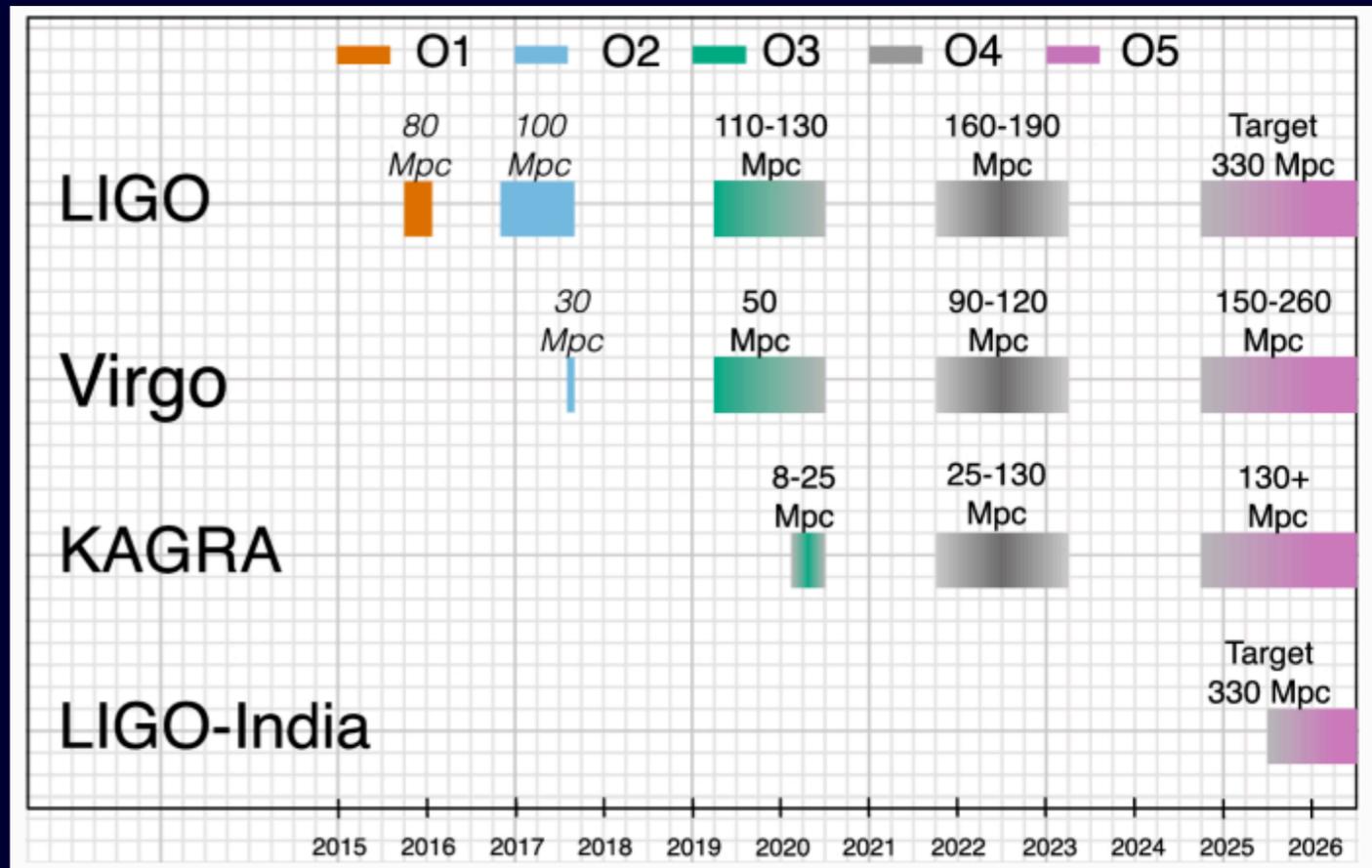
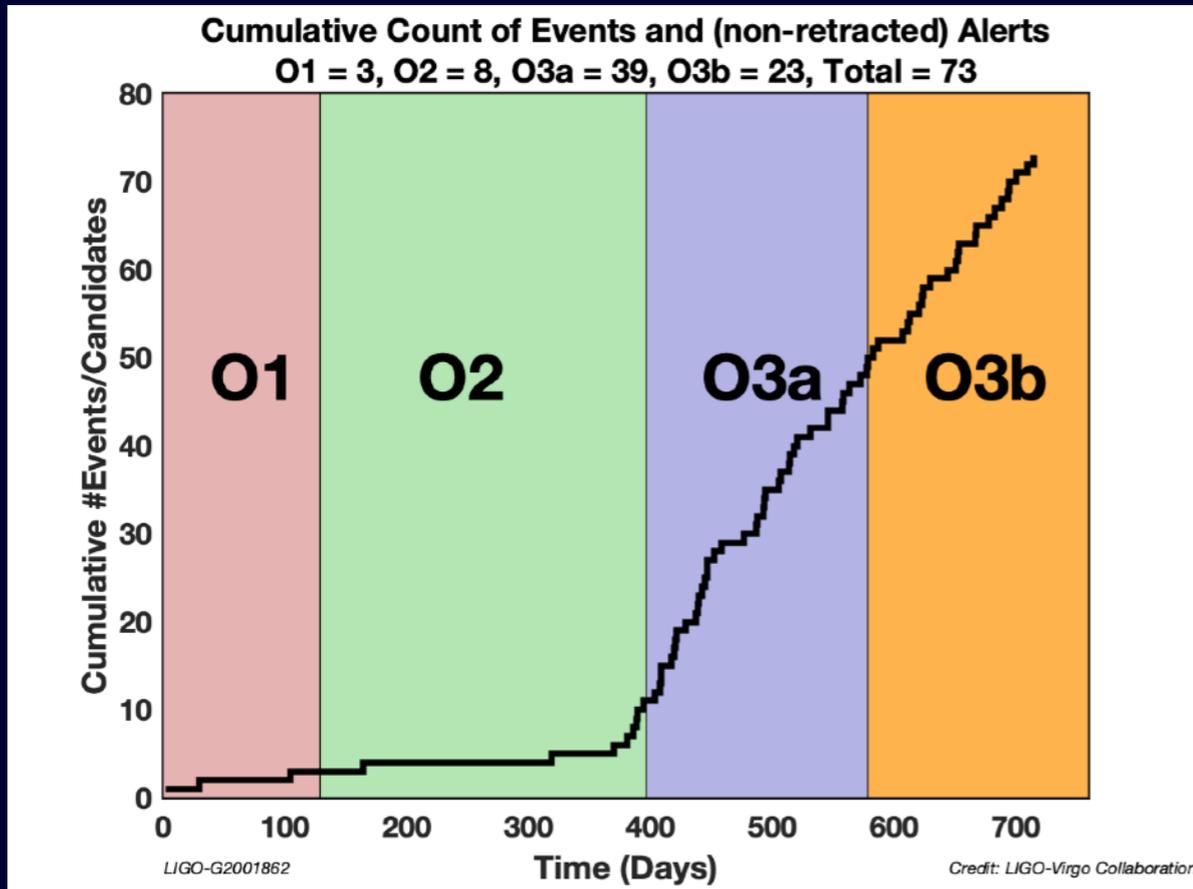
We focus on two test masses.

Principle of Observation

We replace the test masses to the mirror.



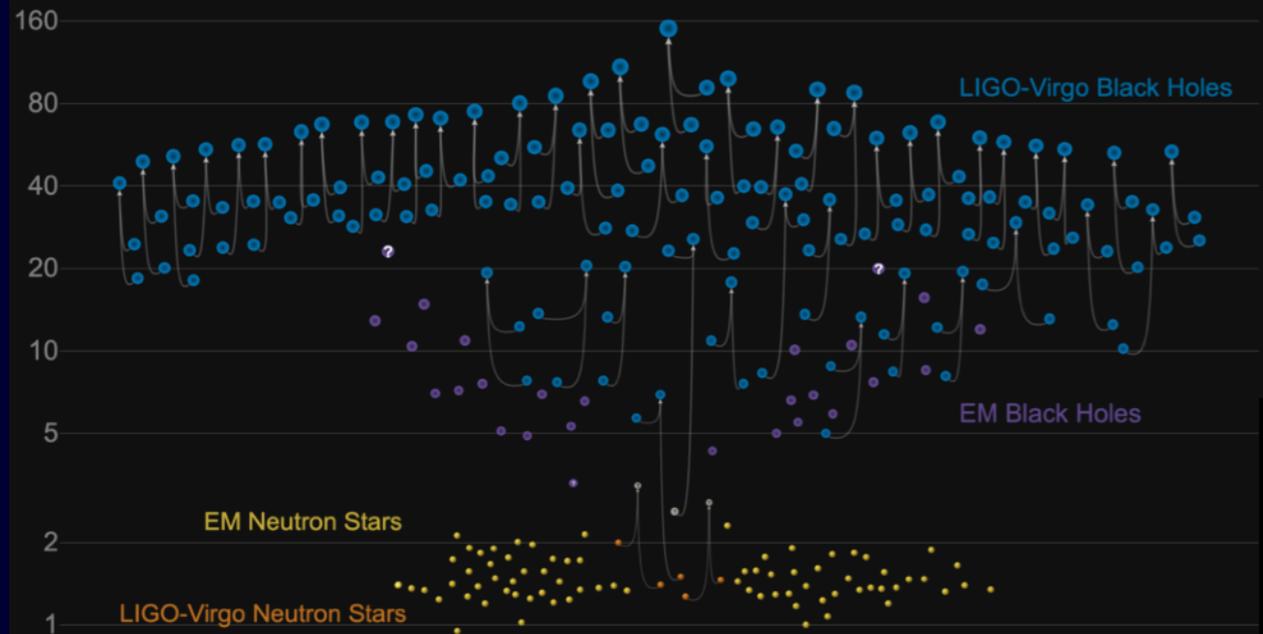
Observation history



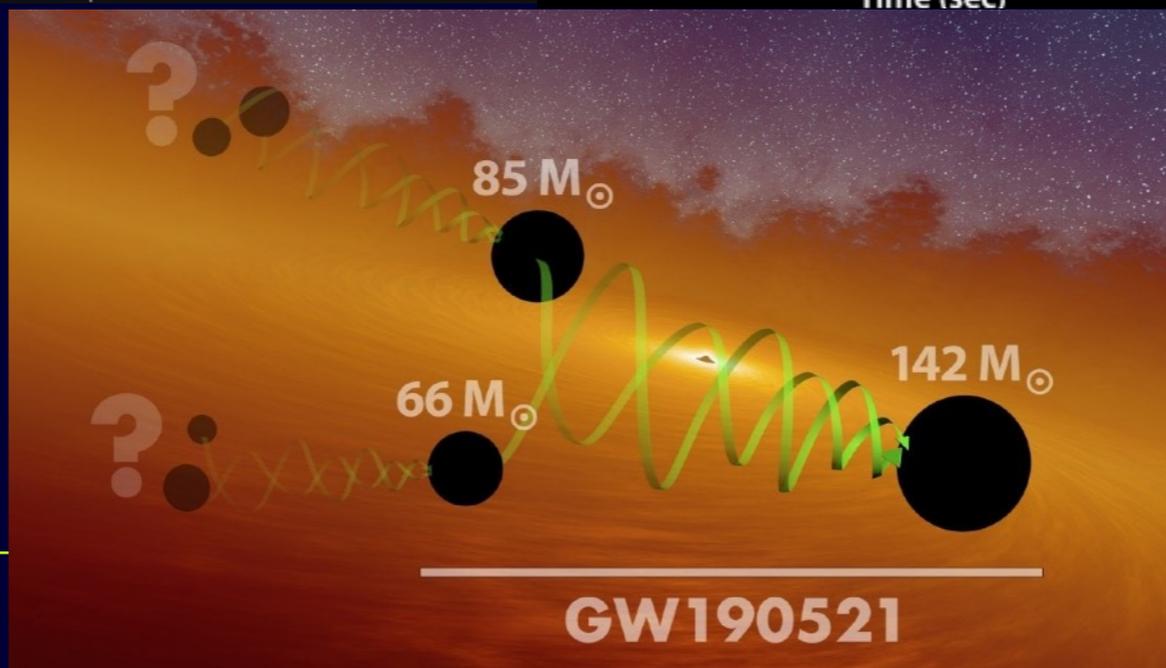
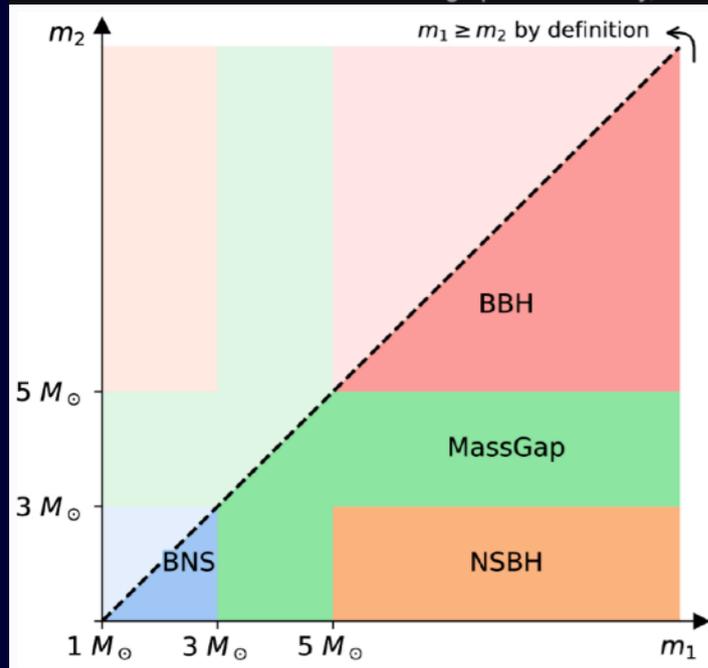
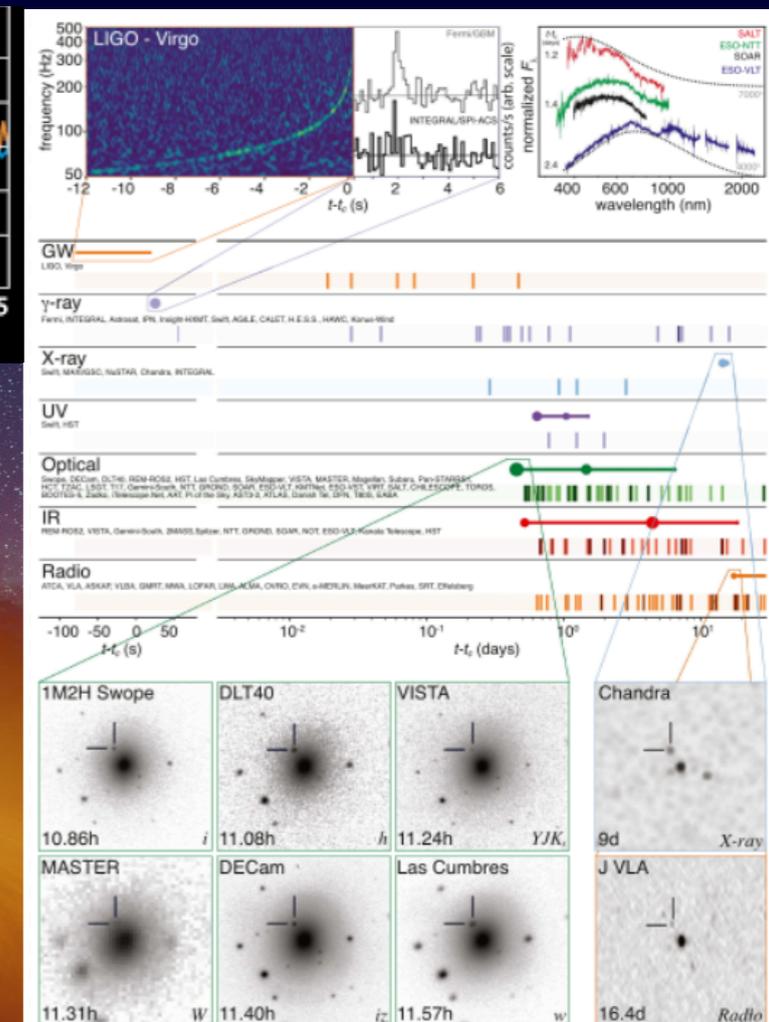
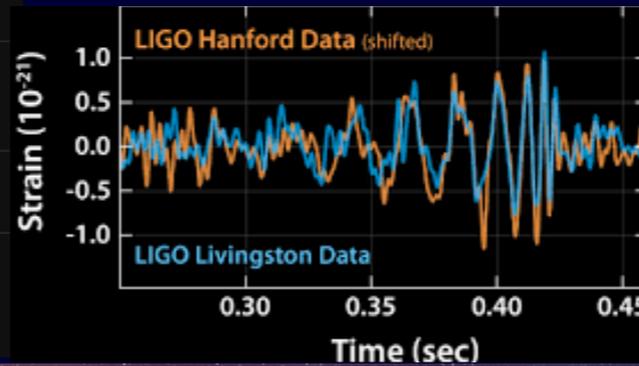
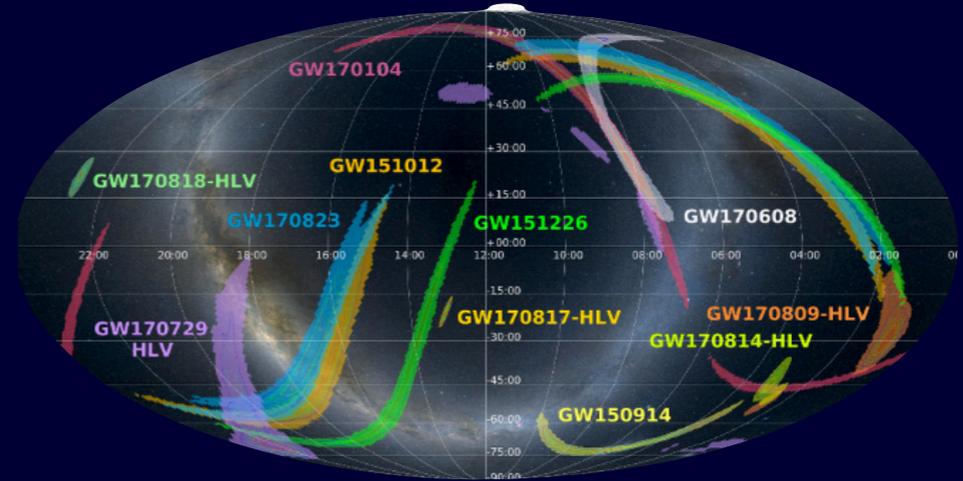
- Now is upgrade period for next observation
- Observation 4 will start from just one year later.

Science of LIGO

Masses in the Stellar Graveyard
in Solar Masses



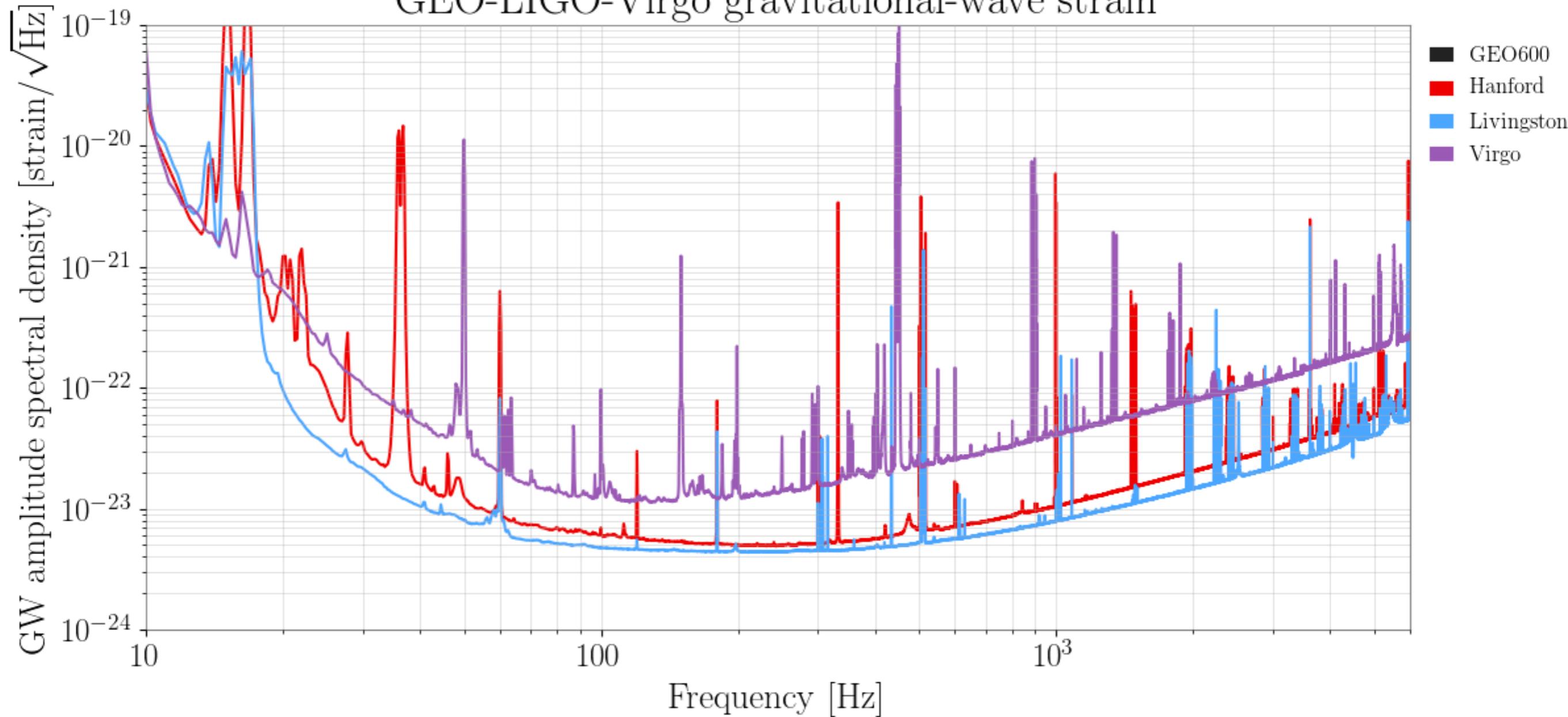
GWTC-2 plot v1.0
LIGO-Virgo | Frank Elavsky, Aaron Geller | Northwestern



Sensitivity

[1238112018-1238198418, state: Observing]

GEO-LIGO-Virgo gravitational-wave strain



Interferometer

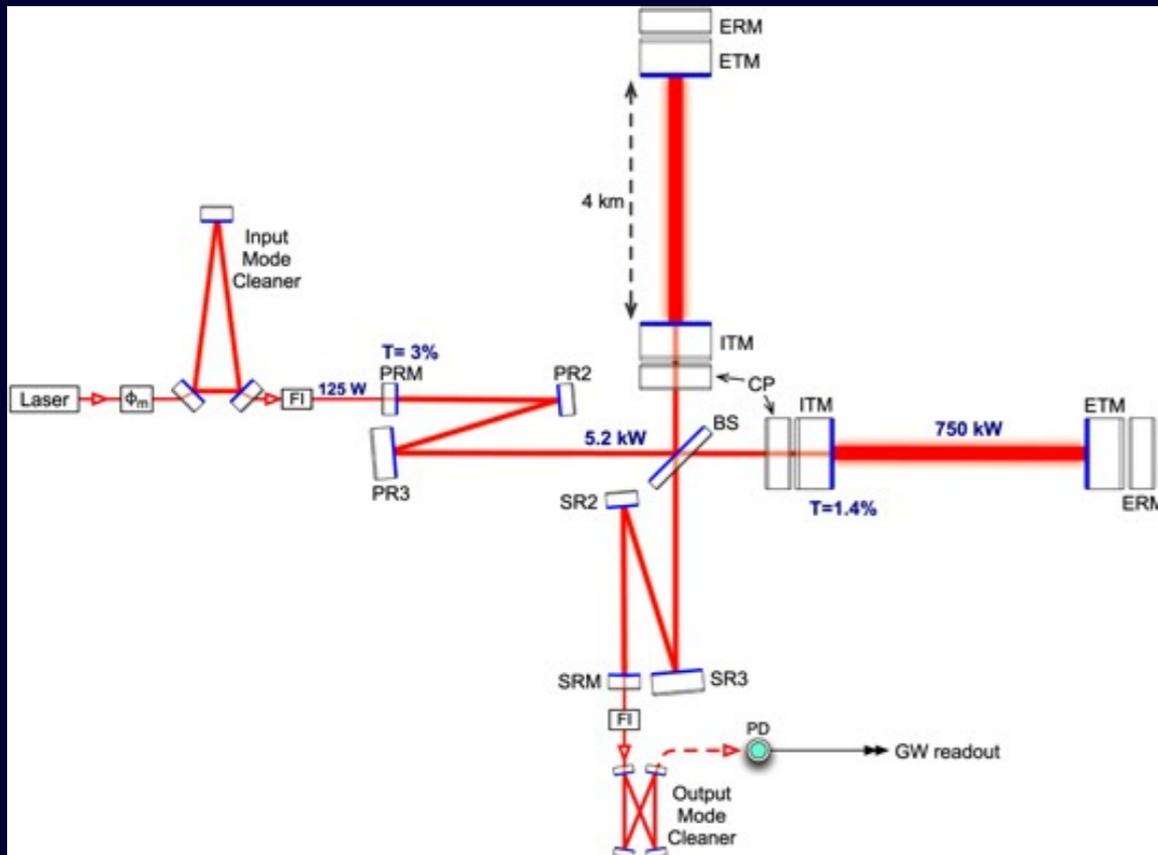


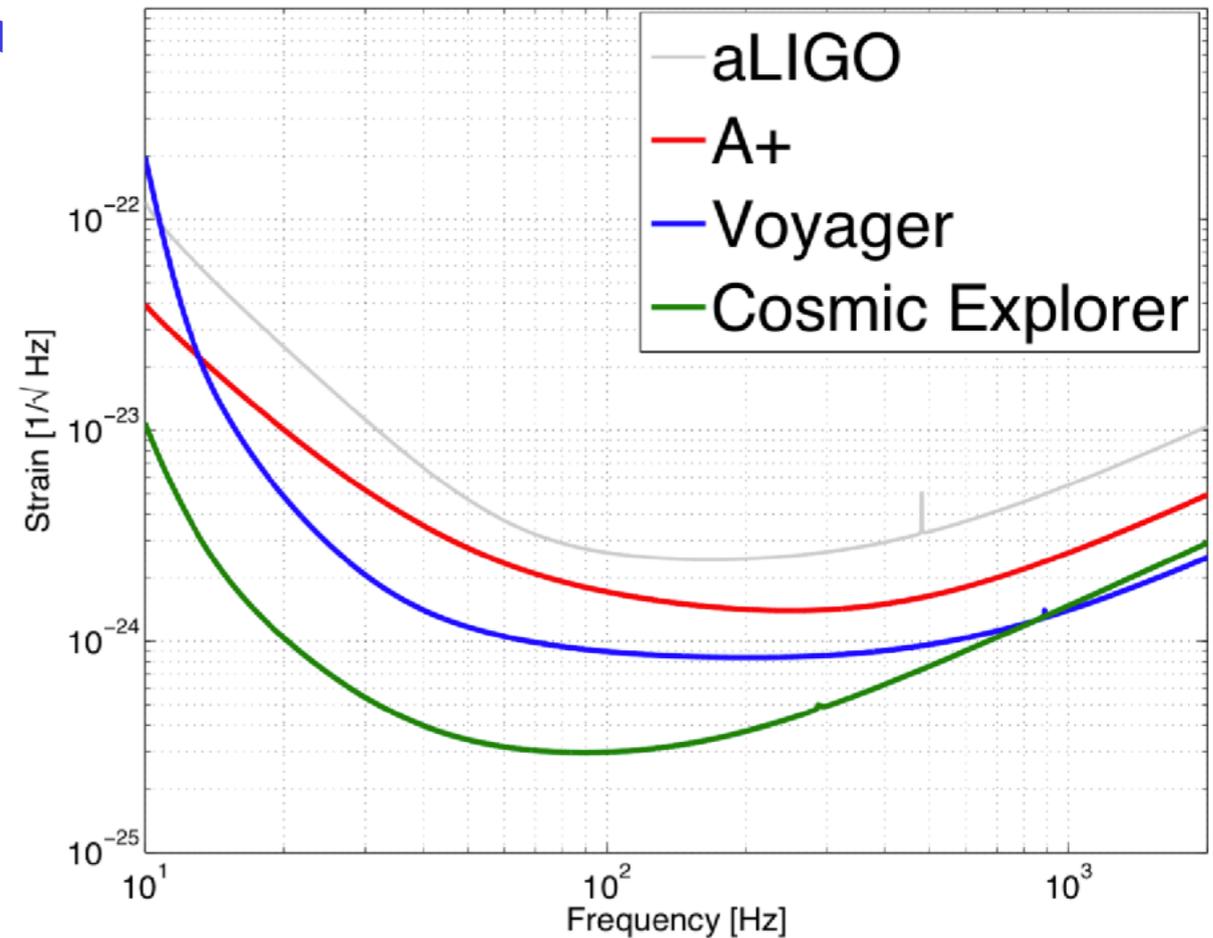
Table 1. Main parameters of the Advanced LIGO interferometers. PRC: power recycling cavity; SRC: signal recycling cavity.

Parameter	Value
Arm cavity length	3994.5 m
Arm cavity finesse	450
Laser type and wavelength	Nd:YAG, $\lambda = 1064$ nm
Input power, at PRM	up to 125 W
Beam polarization	linear, horizontal
Test mass material	Fused silica
Test mass size & mass	34cm diam. x 20cm, 40 kg
Beam radius ($1/e^2$), ITM / ETM	5.3 cm / 6.2 cm
Radius of curvature, ITM / ETM	1934 m / 2245 m
Input mode cleaner length & finesse	32.9 m (round trip), 500
Recycling cavity lengths, PRC / SRC	57.6 m / 56.0 m

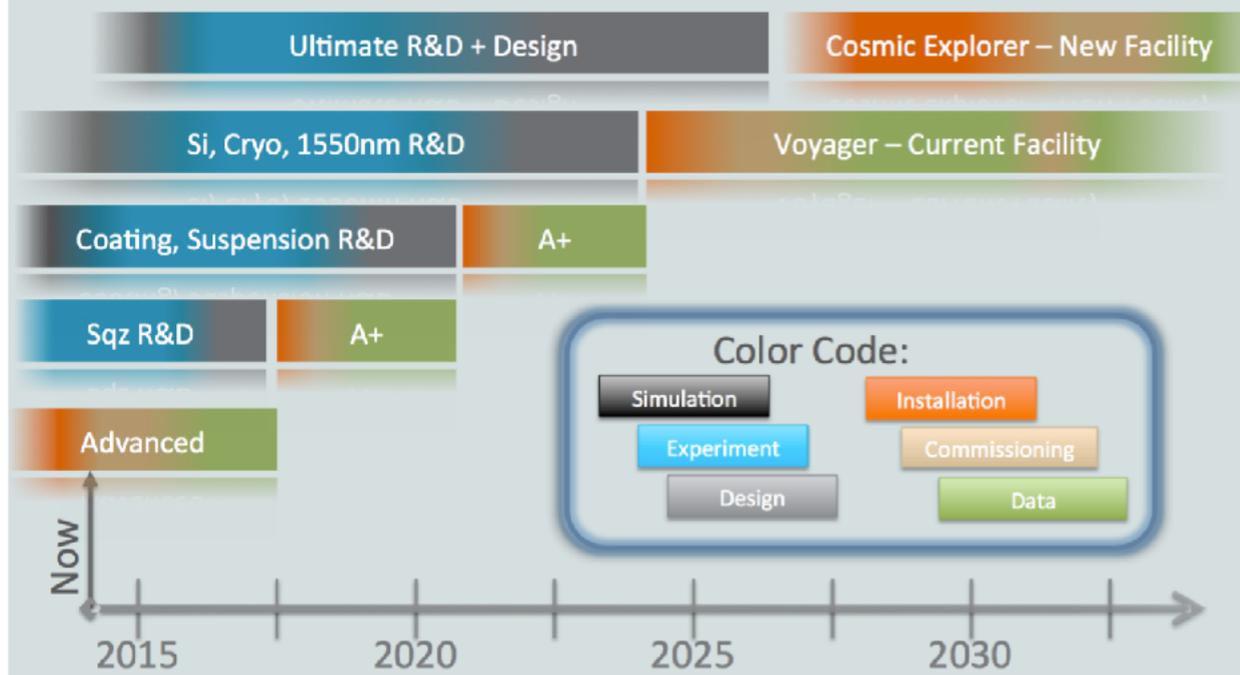
- Dual recycling Fabry Perot Michelson Interferometer
- Virgo and KAGRA also use same configuration.

LIGO Voyager

- Future experiment after O5
- Cryogenic LIGO
- Coating study is ongoing.
- Cryogenic coating characterization system is necessary.



LIGO Upgrade Timeline



IFO Cases	aLIGO	A+	Voyager	Cosmic Explorer
Mirror Mass [kg]	40	80	160	80
Mirror Material	Silica	Silica	Silicon	Silica
Mirror Temp [K]	295	295	120	295
Sus Temp [K]	295	295	120	295
Sus Fiber	0.6m SiO2	0.8m SiO2	0.6m Si	0.8m SiO2
Fiber Type	Fiber	Fiber	Ribbon	Fiber
Input Power [W]	125	125	450	125
Arm Power [kW]	800	800	3200	800
Wavelength [nm]	1064	1064	1560	1064
NN Suppression	1	5	30	5
Coating Type	SiO:TaO	TBD	ALAs:GaAs	TBD
Beam Size [cm]	5.3 / 6.2	8 / 9.4	5.3 / 6.2	11 / 12
SQZ Factor [dB]	0	6	10	10
F. C. Length [m]	0	16	300	1000

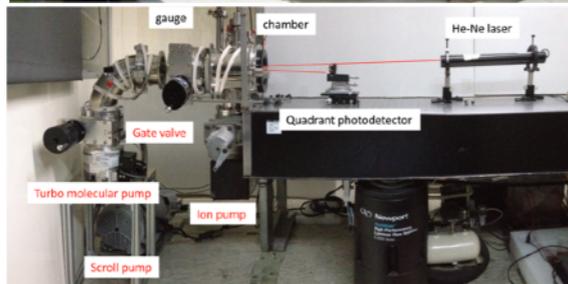
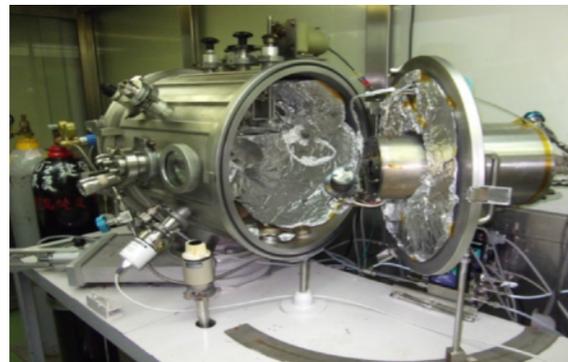


Contribution of Taiwan

Facilities of LIGO-Taiwan

NTHU

Coating lab.



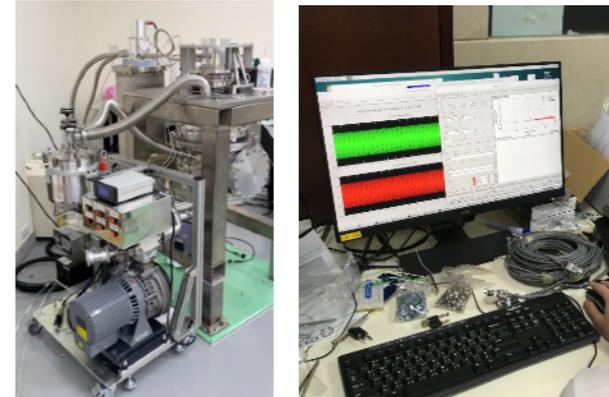
NCU

Analysis & Optics lab.



AS

Cryogenic & Electronics lab.

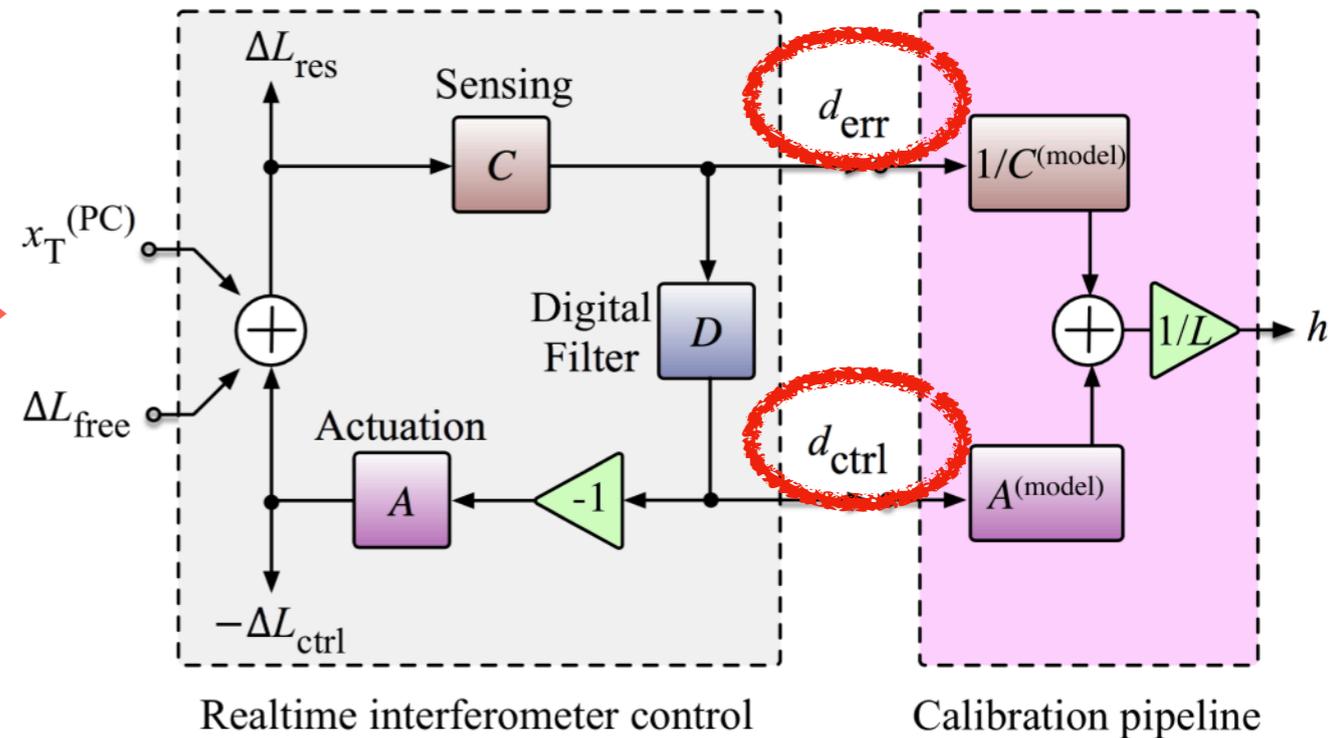
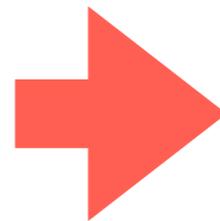


Current activity of LIGO

- Calibration
 - Error estimation pipeline
 - Systematic error study based on the simulation
- Coating
 - Large coating method
 - Low loss method
 - Cryogenic measurement system



Modeling of Interferometer



Changes of arm length are measured between Actuator and Detector

So, we can separate A and C part by estimation accurate model of A and C

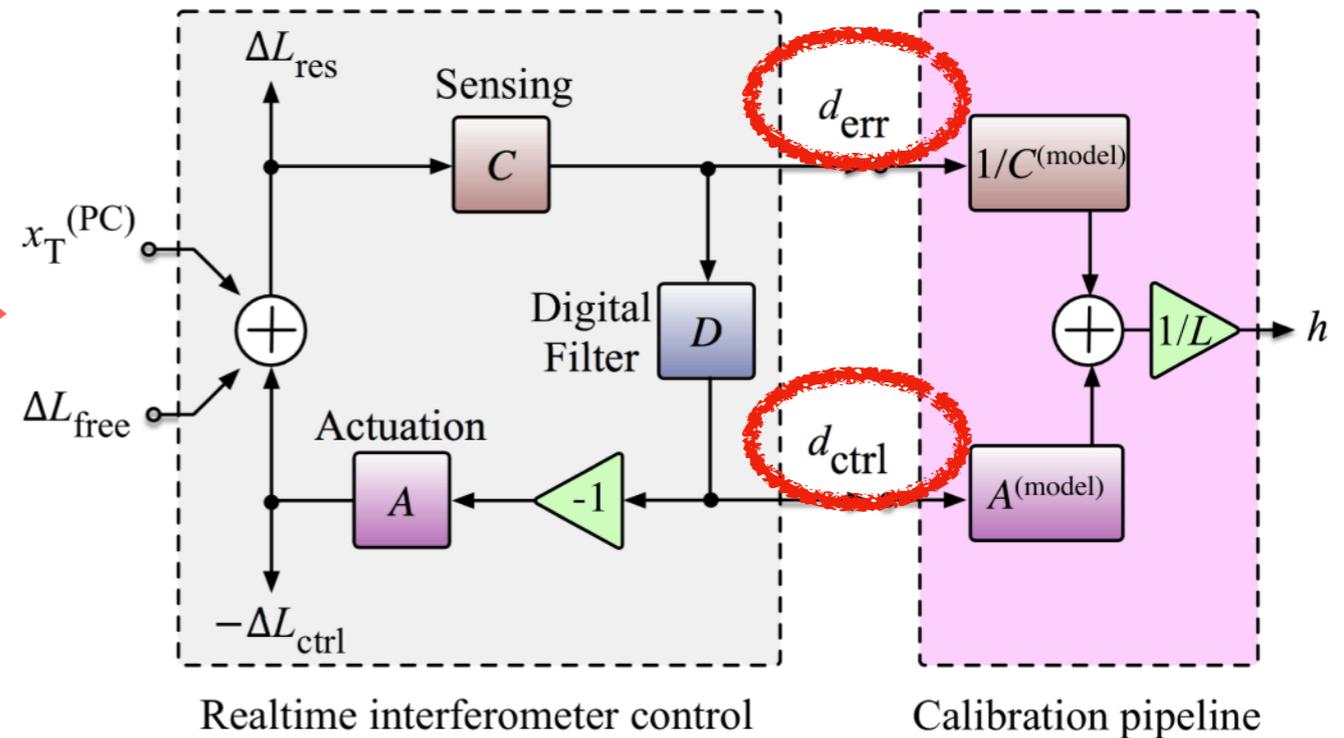
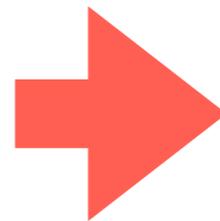
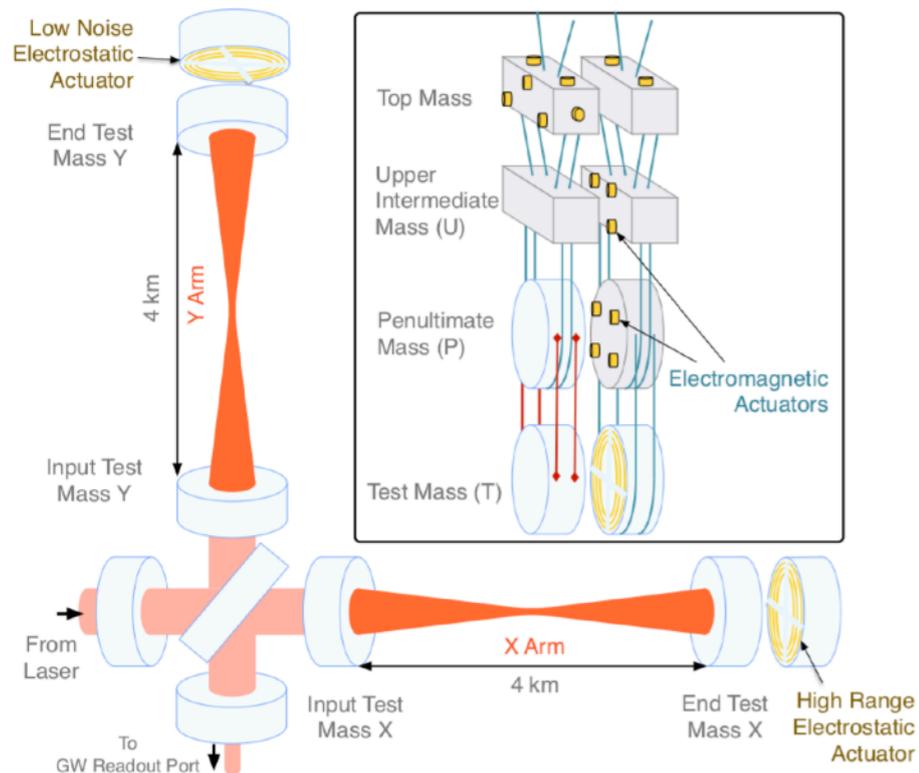


Definition of Calibration : Parameter estimation of A and C



Definition of Reconstruction : Calculation from interferometer response

Modeling of Interferometer



Changes of arm length are measured between Actuator and Detector

So, we can separate A and C part by estimation accurate model of A and C

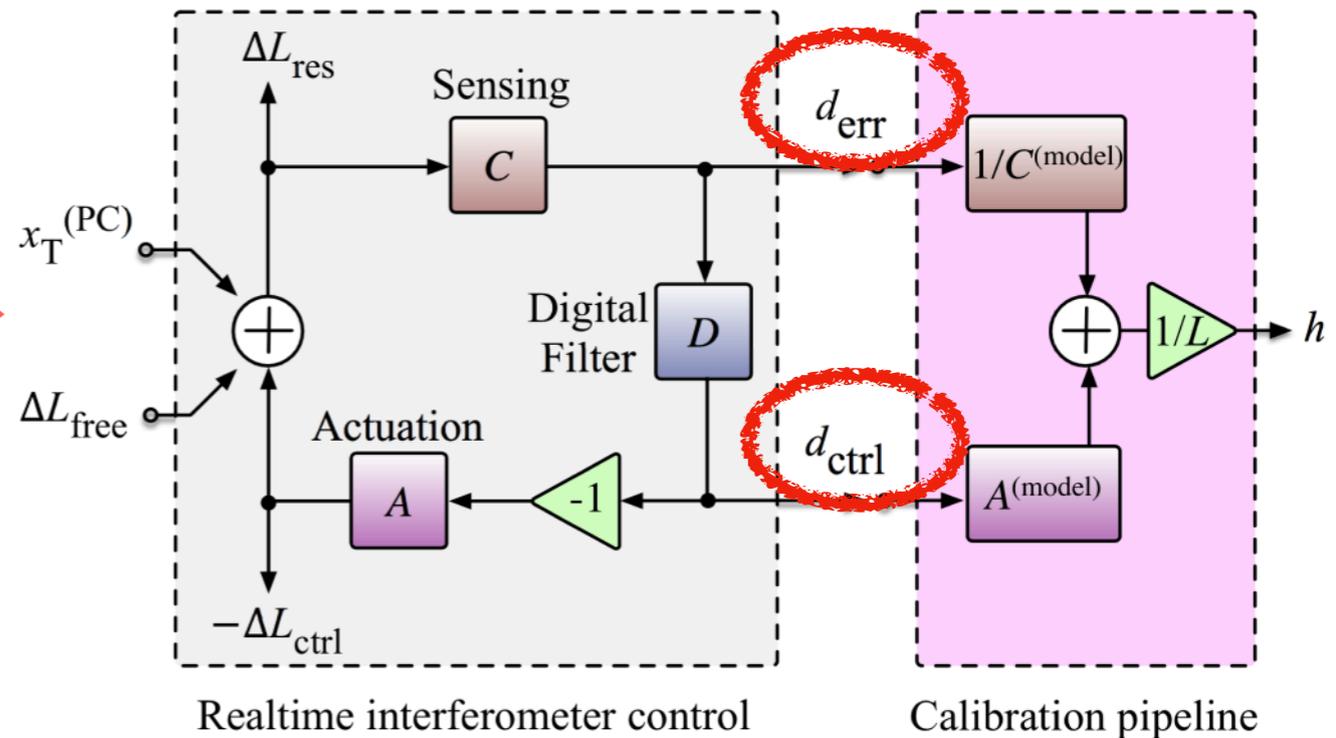
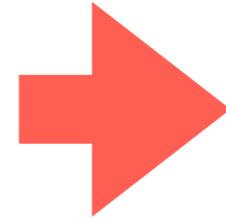
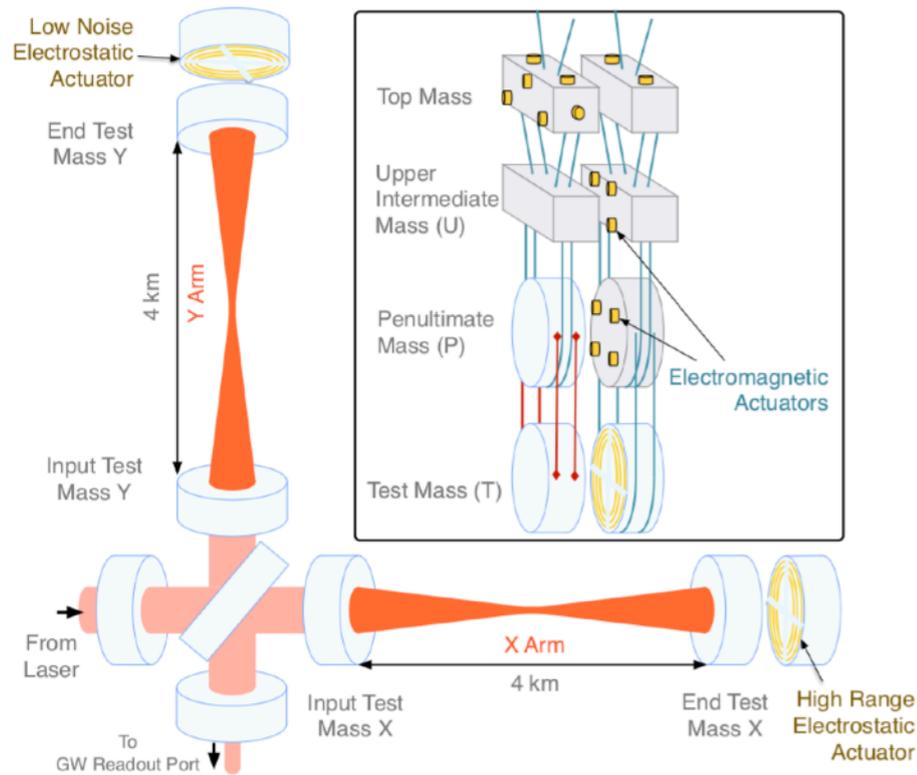


Definition of Calibration : Parameter estimation of A and C



Definition of Reconstruction : Calculation from interferometer response

Reconstruction of LIGO



$$d_{err}, d_{ctrl} \approx h(t)$$

Modeling error -> Calibration error

We reconstruct $h(t)$ by modeling time-dependent Sensing and Actuation factor

$$h(t) = \frac{\Delta L_{ext}(t)}{L} = C^{-1} * d_{err}(t)/L + A * d_{ctrl}(t)/L$$

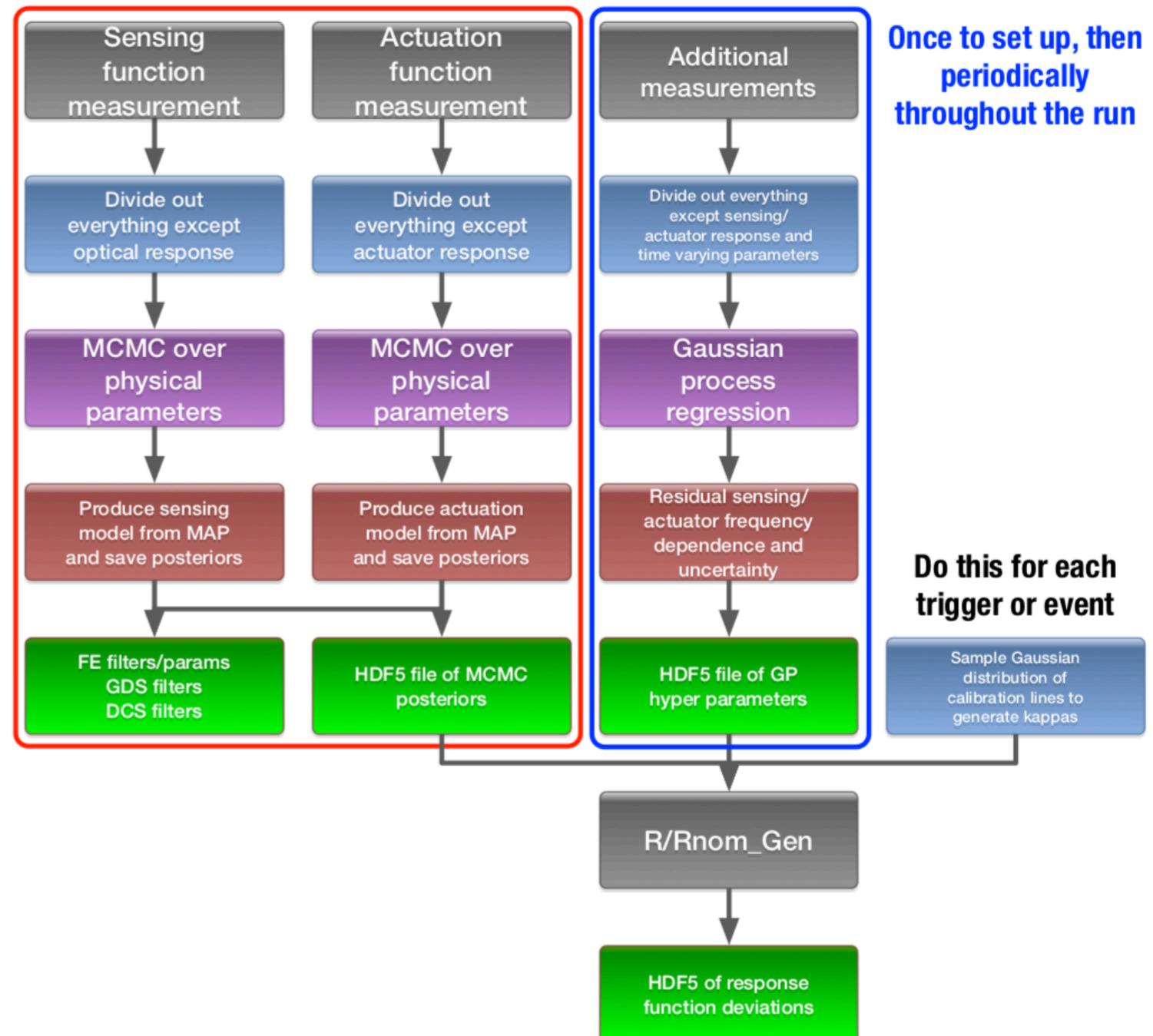
Development of pyDARM

pyDARM

- python DARM model
- Interferometer modeling
- Filter generation for reconstruction
- Calibration parameter and filter
- Systematic uncertainty estimation of provided $h(t)$

03 PIPELINE

Do this once to set up reference model



History of pyDARM

- ▶ O1: Matlab model only, simplified error analysis
 - ▶ O2: Combination of Matlab and python codes used for modeling, filter generation, error/uncertainty (Bayesian) estimation
 - ▶ O3: pure python codebase, but awkward to use (not modular, not easily extendable, doesn't integrate well, etc.)
 - ▶ O4: modular python codebase, installable using pip/conda-forge/source
-

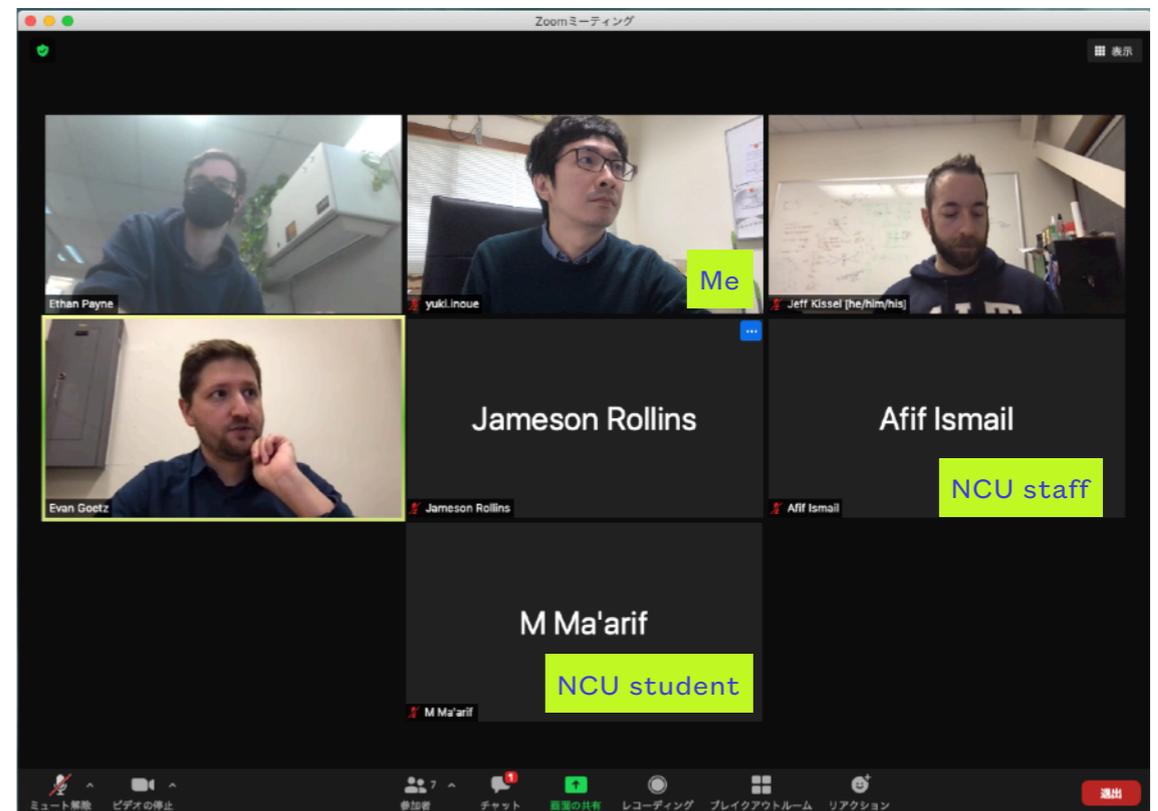
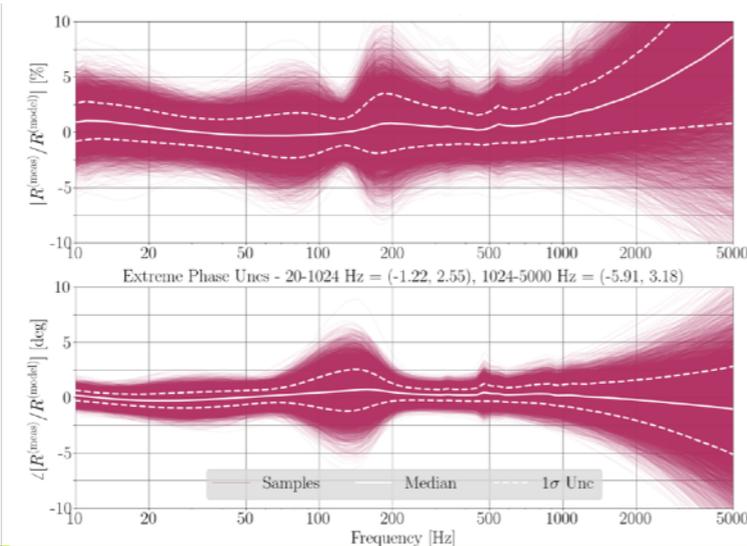
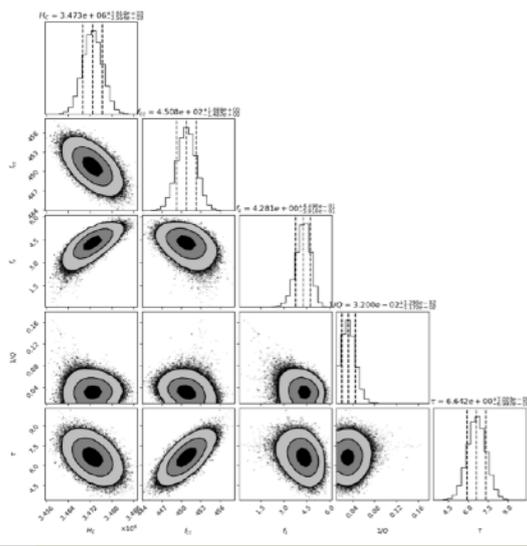
Calibration activity

LIGO calibration code sprint on Dec.2 1:00 am -9:00 am



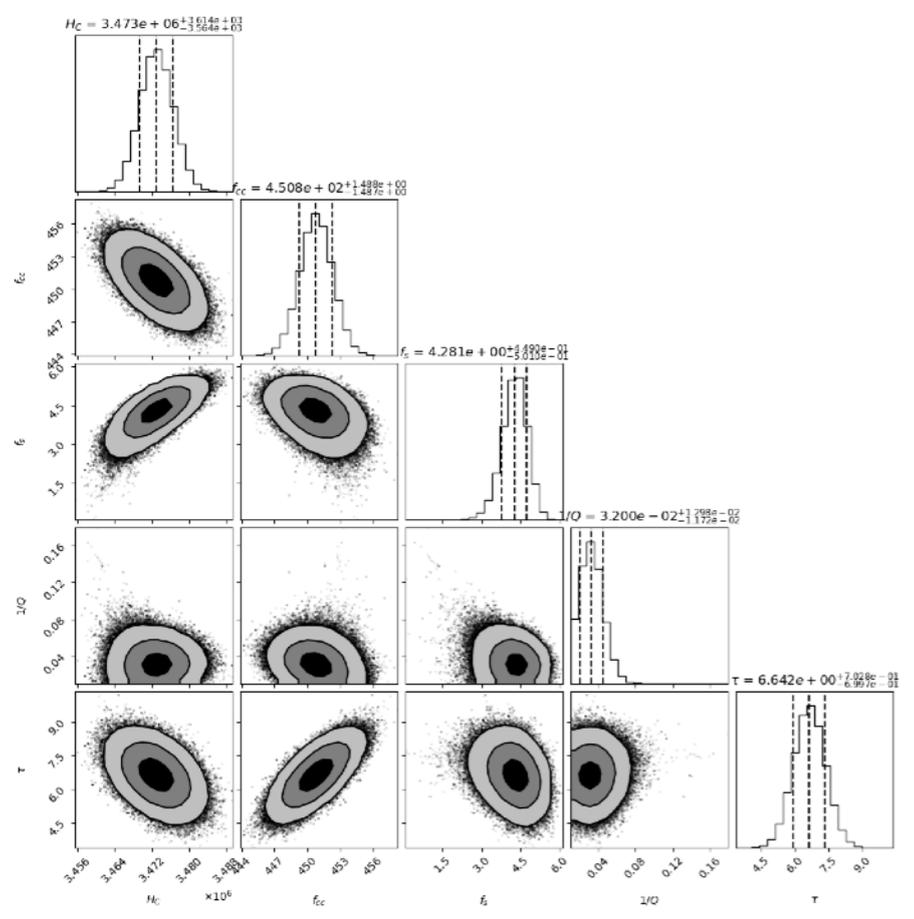
Wake up, pyDARM team...
The Matrix has you...
Follow the white rabbit.
Knock, Knock, pyDARM team

- Development of systematic error estimation tool based on the interferometer model
- pyDARM = python base Differential ARM length modeling code
- Taiwan team are developing new software

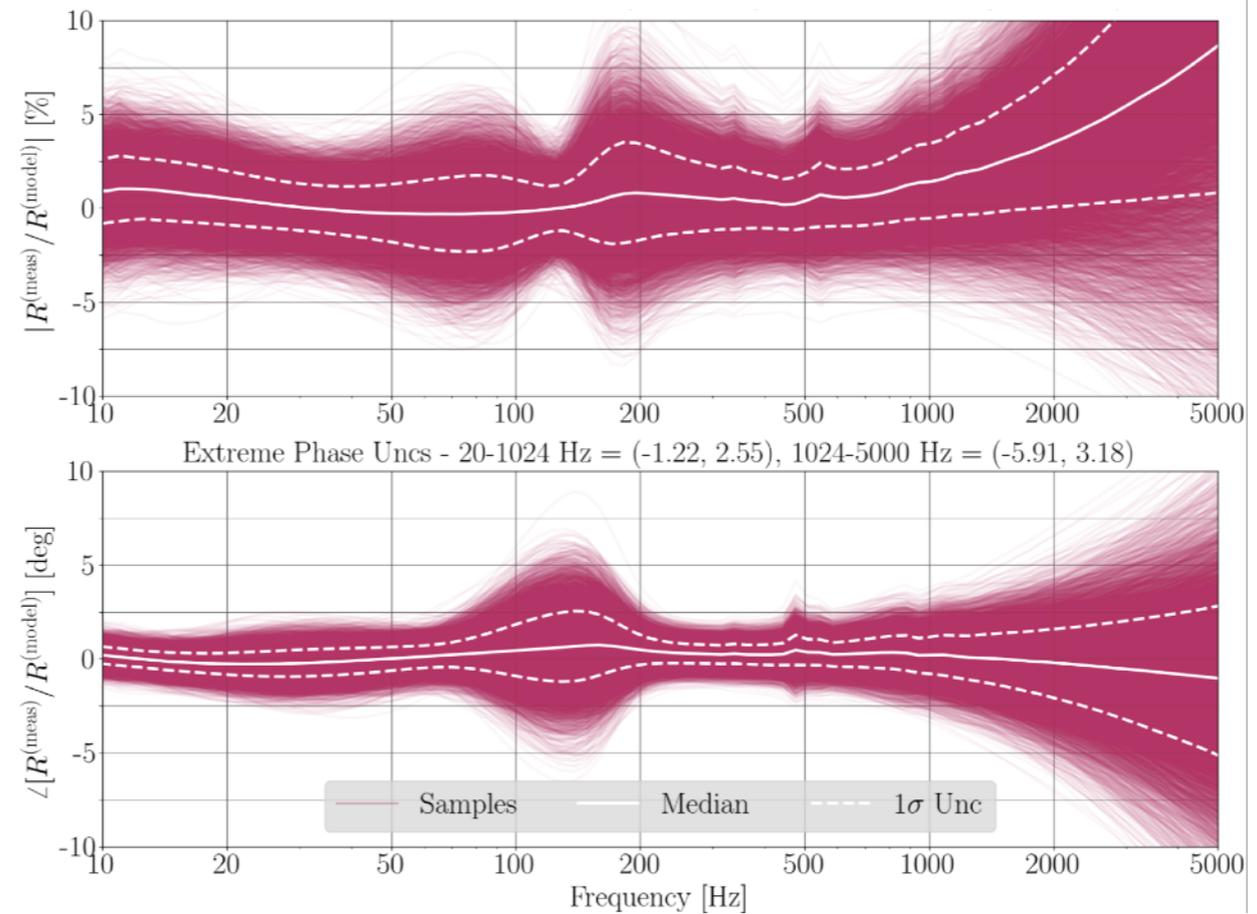


Calibration error envelop

CALIBRATION PARAMETER ESTIMATION



CALIBRATION ERROR OF STRAIN SENSITIVITY



- MCMC and Gaussian process regression
- Provide hourly calibration error for the world wide collaborator

Coating study



NTHU Prof.Chao

NCU&AS Yuki Inoue

- Prof.Chao will retire at next summer
- Yuki is taking over his coating facility
- Process of taking over is ongoing
- Prof.Chao plan to continue the research in Yuki's group

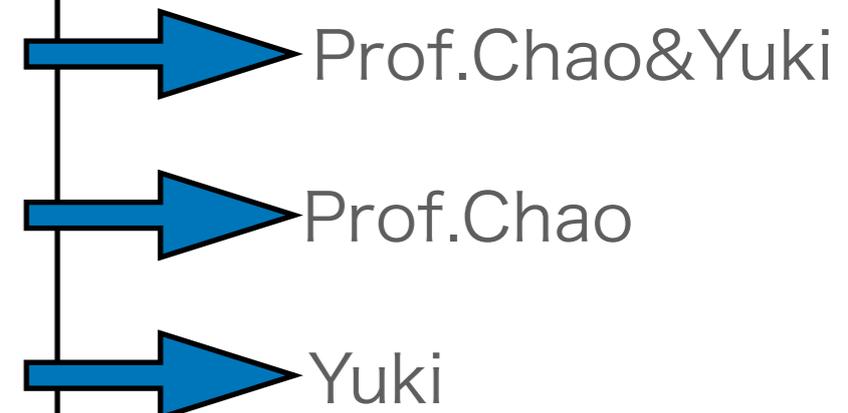
Assignment of human resource for taking over

- 1 postdoc and 1 Ph.D. student visit NTHU constantly.
- 1 master student stay in NTHU and focus on CVD method (Training now)
- Technical staffs and 1 master student focus on development of cryogenic loss measurement system in Academia Sinica

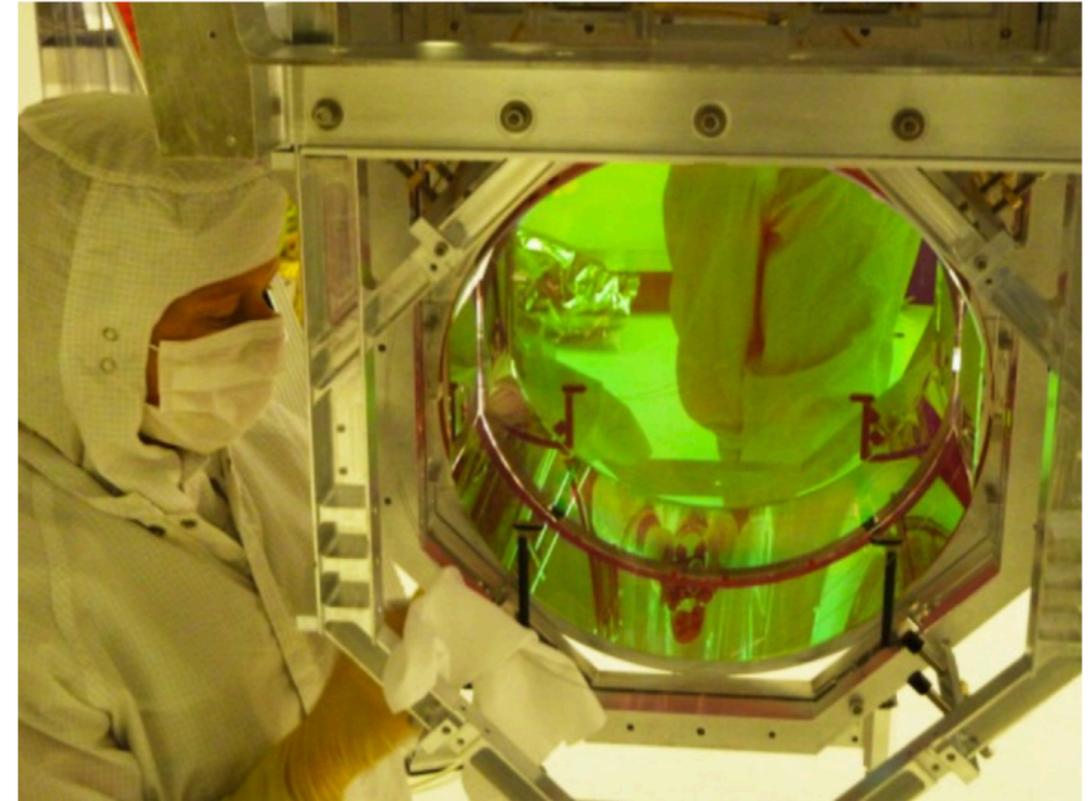
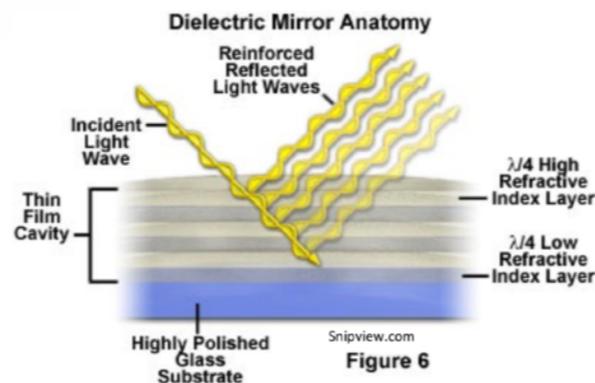
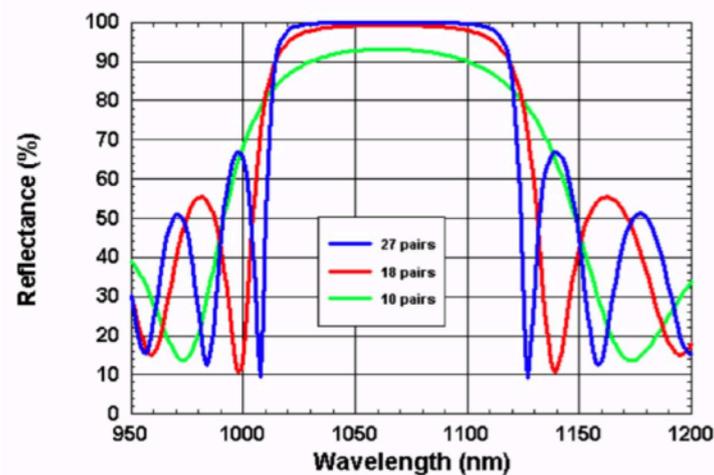
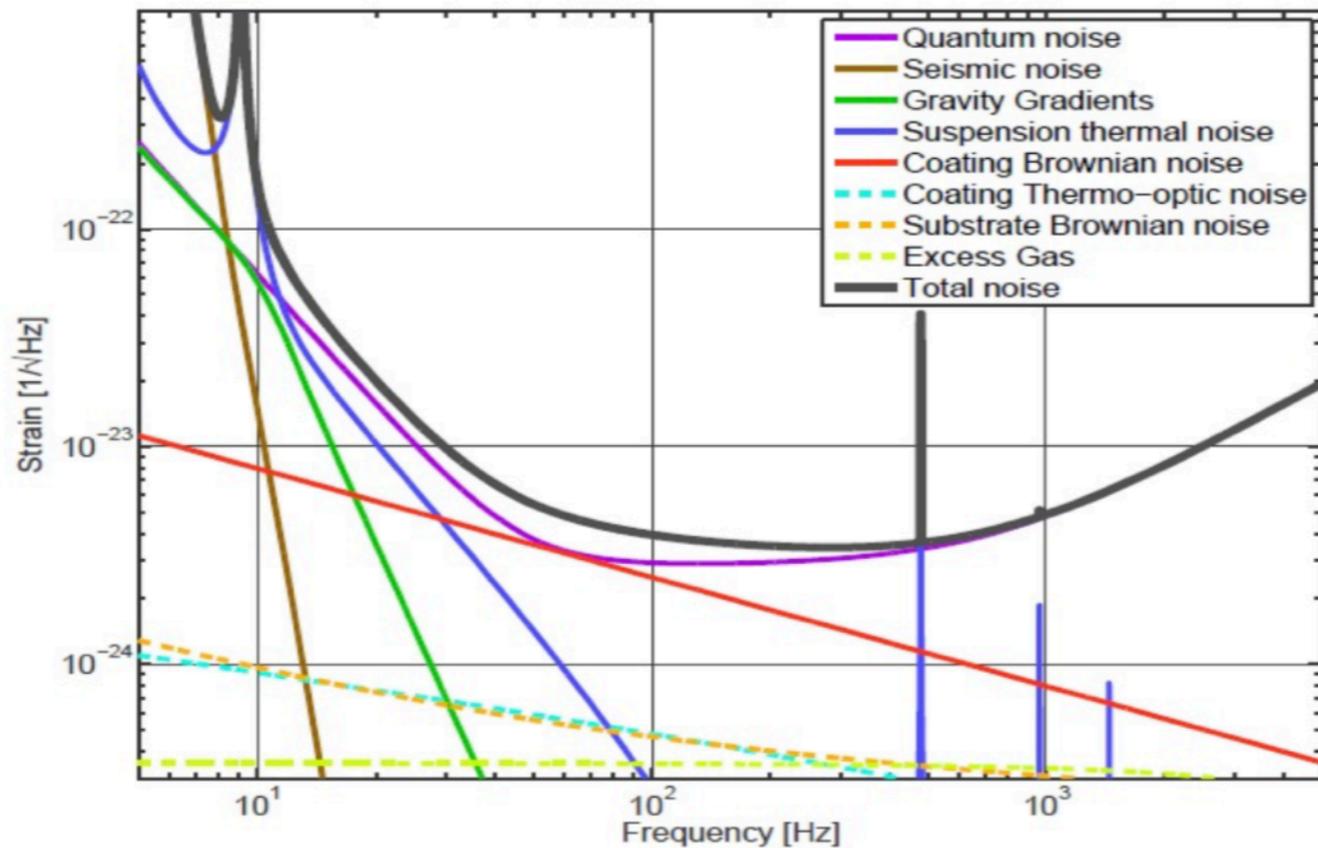
High Priority studies

1. Verification of large area coating with CVD method
2. Optimization of fabrication process for low loss coating
3. Development of cryogenic loss measurement system

2022 plan



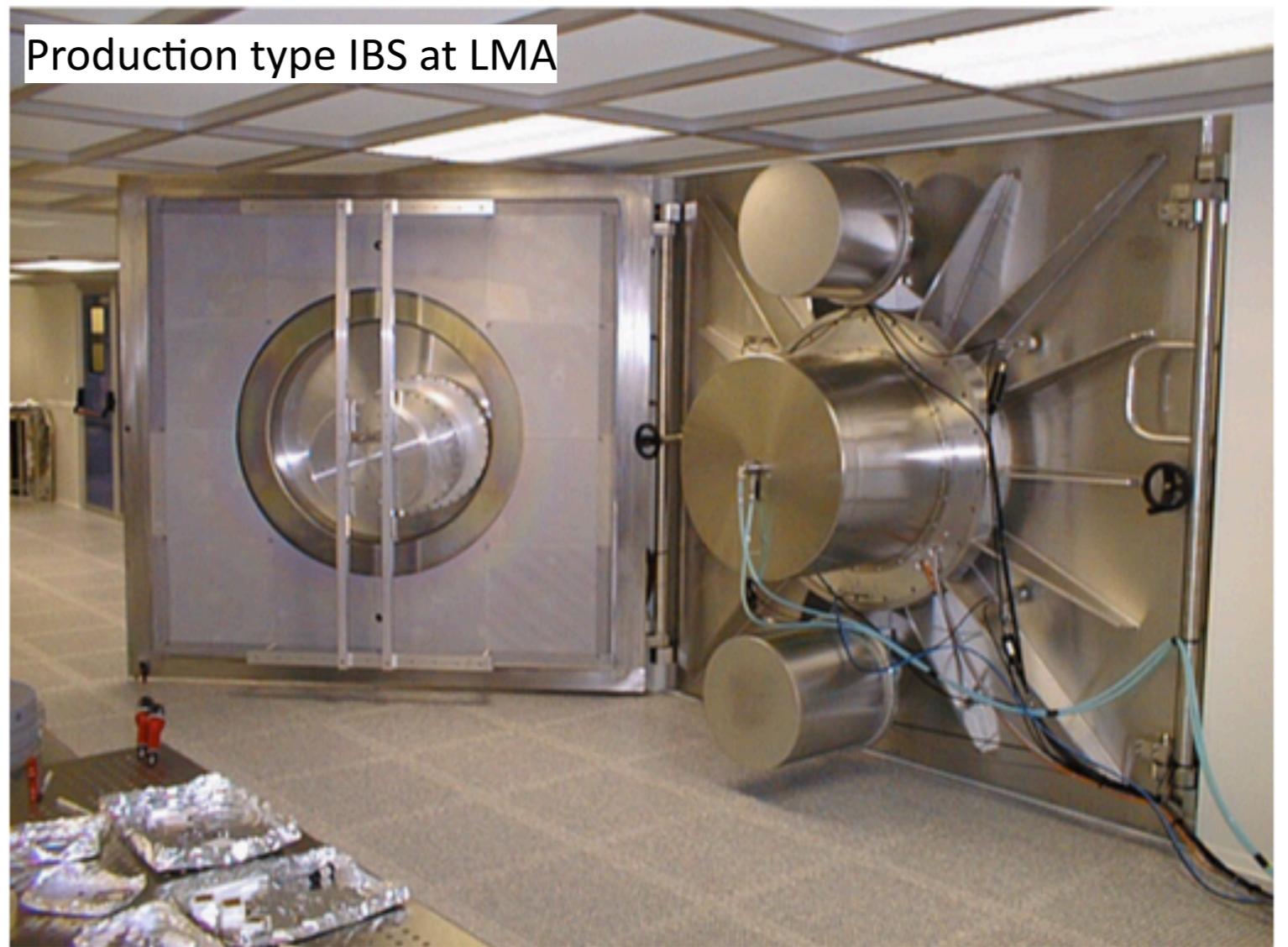
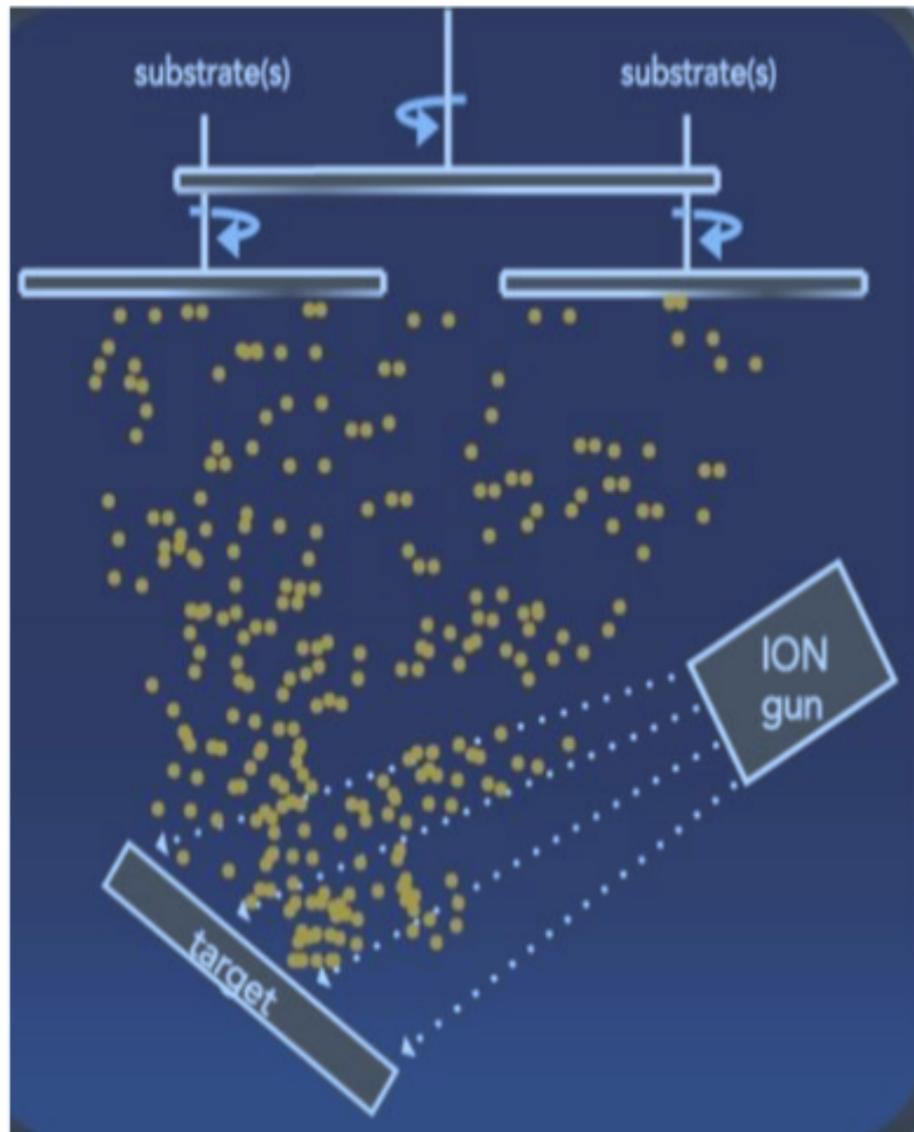
LIGO coating



$$S_x(f) = \frac{2k_B T}{\pi^{3/2} f} \frac{1 - \sigma^2}{wY} \left\{ \phi_{\text{substrate}} + \frac{2}{\sqrt{\pi}} \frac{(1 - 2\sigma) d}{(1 - \sigma) w} \phi_{\parallel} \right\}$$

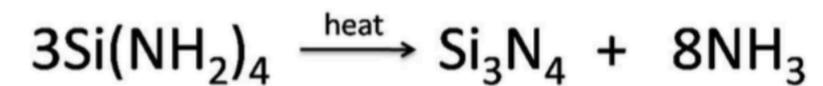
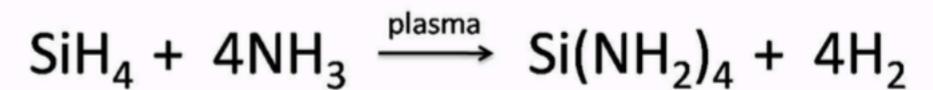
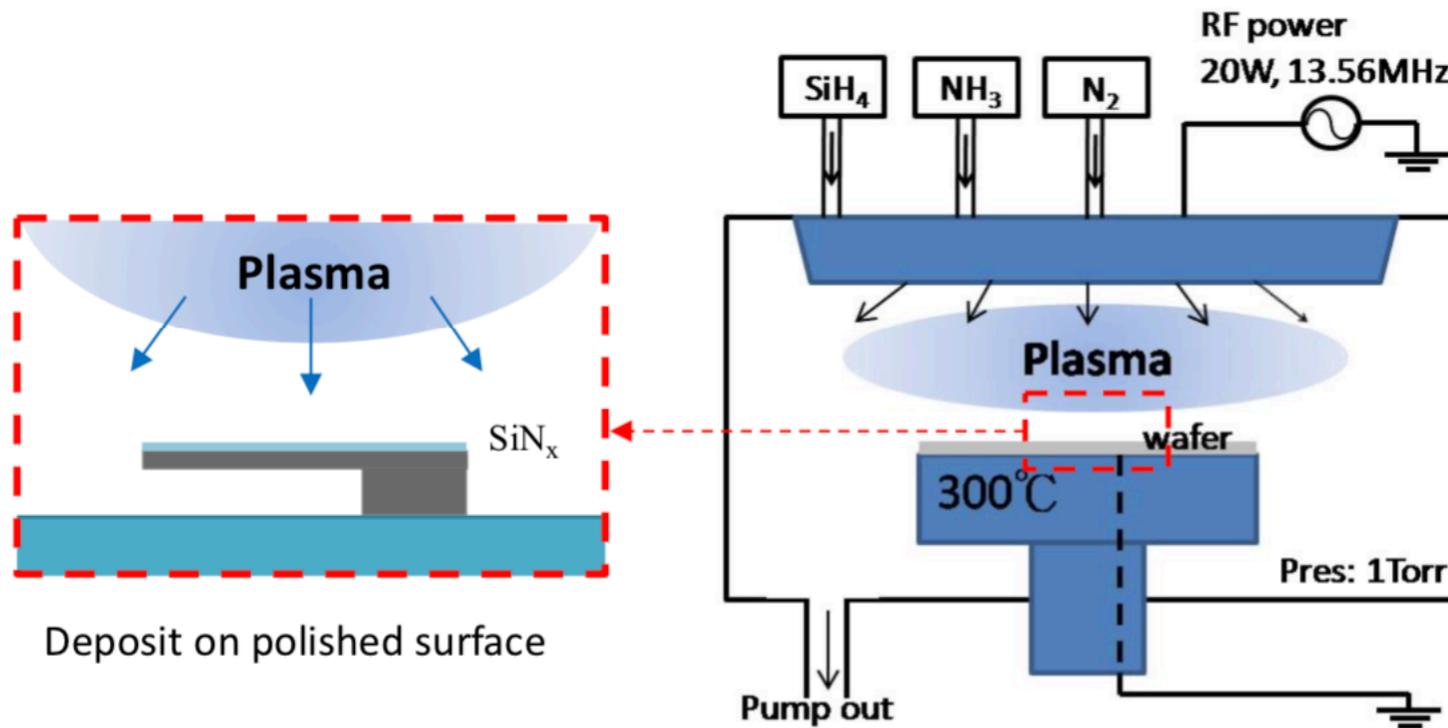
- LIGO employs Ta₂O₅-TiO₂ coating with Fused Silica mirror
- Ion Beam Sputter (IBS) method is used in the fabrication process
- They still have a challenging issue for the large area coating with IBS.

IBS coating in LIGO



Two aLIGO mirrors are coated simultaneously with planetary rotation and masking to ensure the thickness uniformity (all Zernike poly terms $< 0.5\text{nm}$ was achieved for a-LIGO)

Fabrication of SiN film on Silicon by Plasma Enhanced CVD method



Ref : Donald L. Smith, et al. "mechanism of SiN_xH_y Deposition from NH₃-SiH₄ plasma". J. Electrochem. Soc. **137**, 614-623(1990)

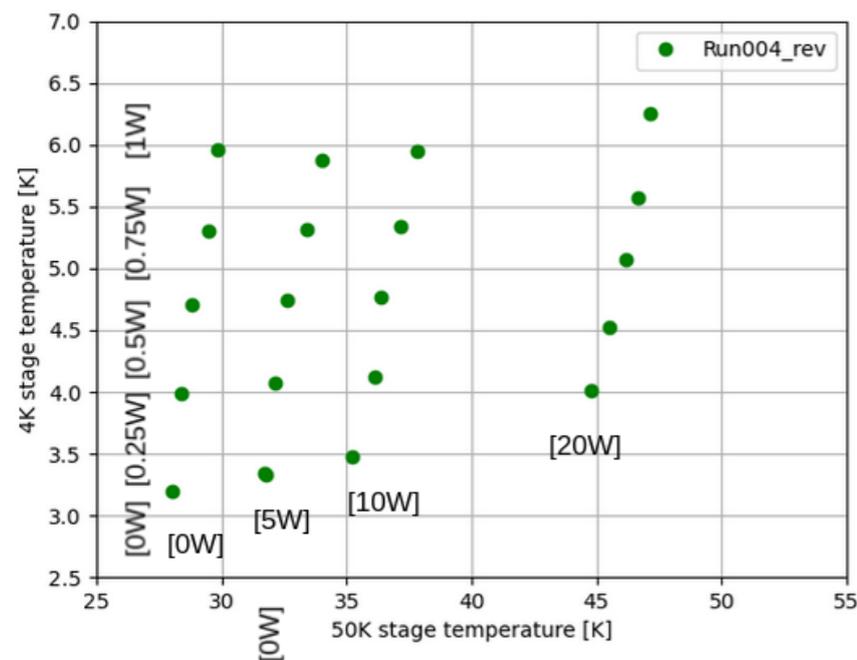
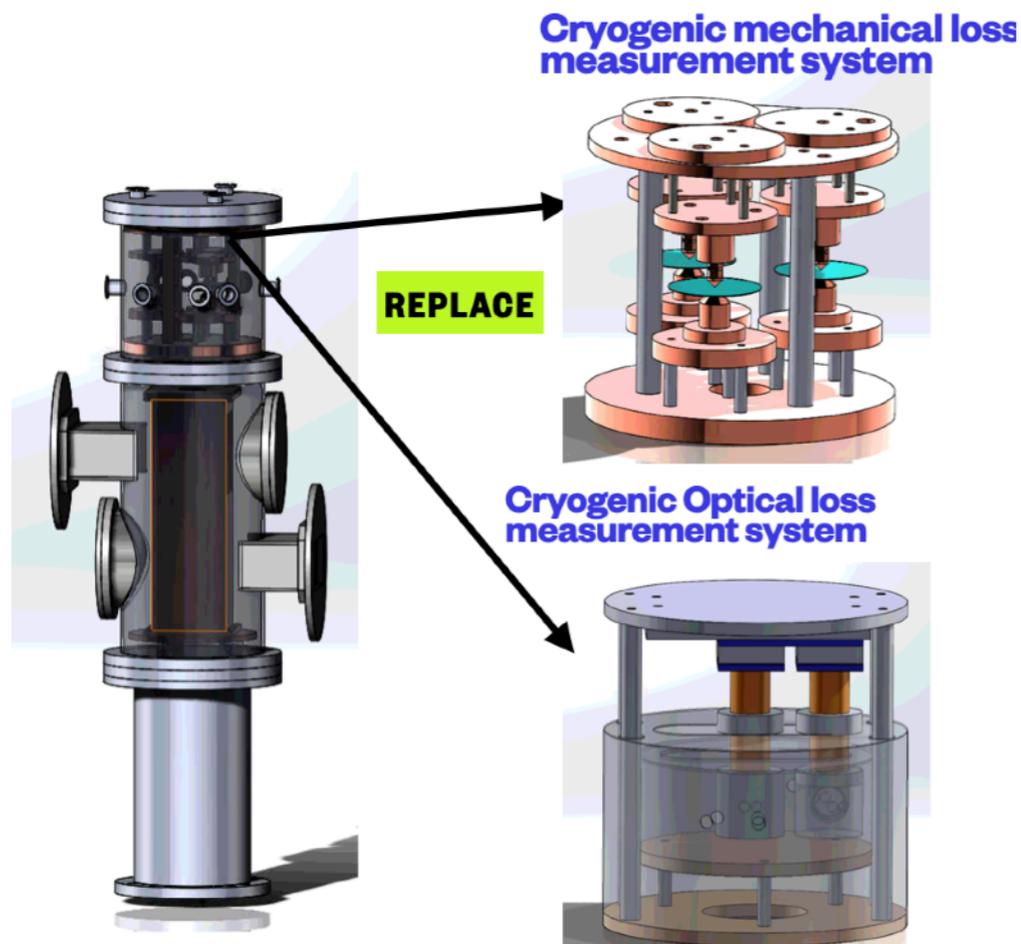
Ref : J. N. Chiang, et al "Mechanistic Considerations in the Plasma Deposition of silicon nitride film" J. Electrochem. Soc. **137**, 2222-2226.(1990)

Adjusting the ratio of the gas flow rate, the composition of the SiN film can be changed

With fixed N₂ gas flow at 980 sccm, we used 5 recipes with different gas flow rate :

Gas flow rate SiH ₄ /NH ₃ (sccm)	Composition	thickness * (nm)	Refractive index [†] @1550nm	Young's modulus (GPa)	Stress (MPa)	Uncoated cantilever frequency	Coated cantilever frequency
45/15	SiN _{0.40}	159.1±2.7	2.300±0.006	103.7±5.6	120.2±15.5	103.42	103.47
38/22	SiN _{0.49}	179.2±1.4	2.138±0.005	107.0±10.8	143.8±13.2	107.32	107.38
25/30	SiN _{0.65}	198.5±0.8	1.930±0.002	131.6±4.8	256.7±6.6	104.88	105.02
15/45	SiN _{0.79}	204.4±1.5	1.816±0.001	137.7±9.7	382.2±21.3	107.37	107.53
8/48	SiN _{0.87}	211.8±0.1	1.783±0.001	137.0±9.2	412.7±20.0	106.93	107.5

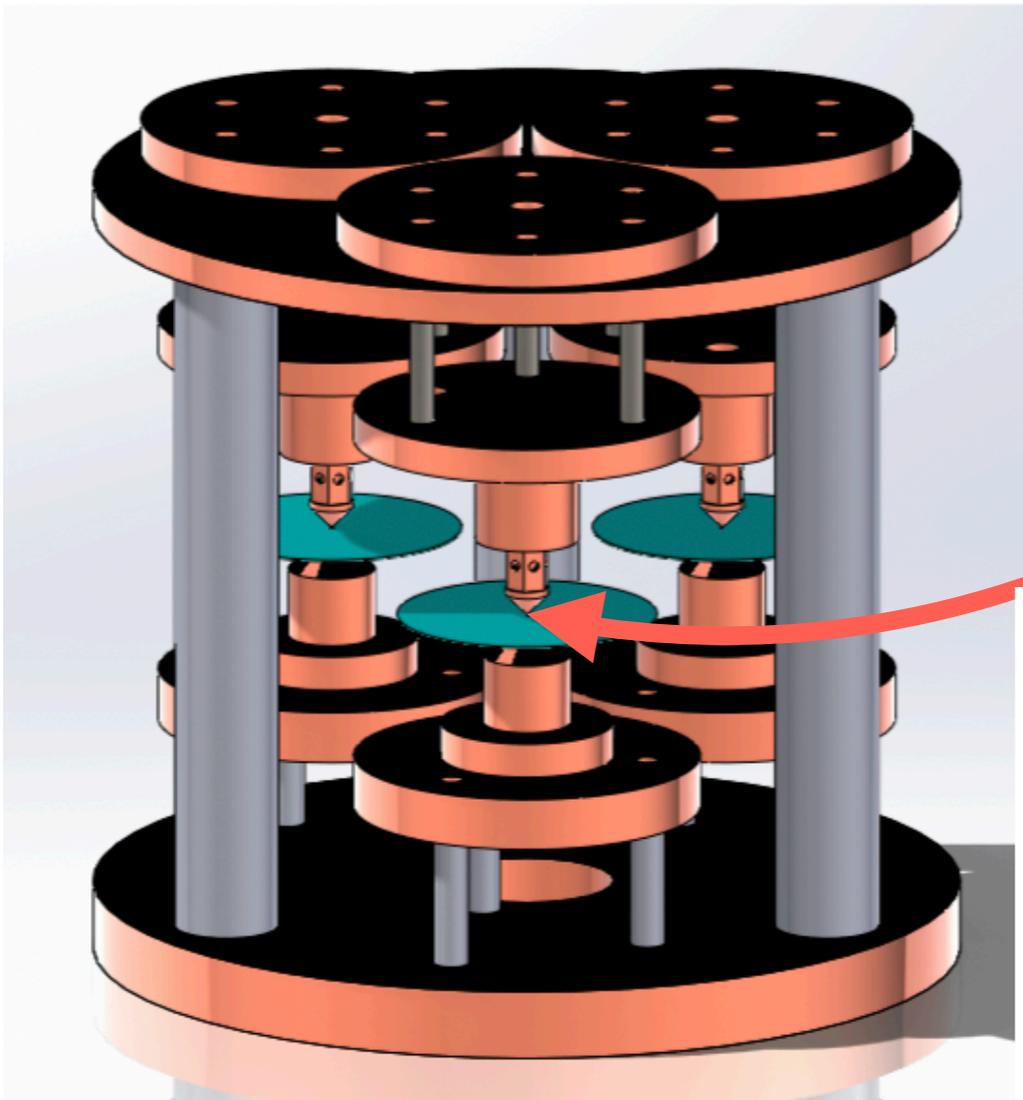
Development of loss measurement system - Characterization of thermal property-



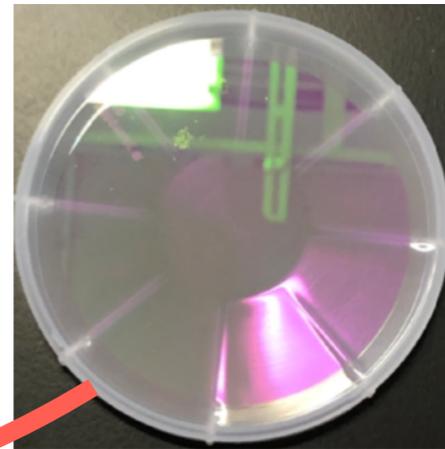
- Installed two thermal stages pulse tube cooler for coating system
- By injecting power for each stage, we measured thermal loading map
- We can keep 4.2 K with 0.25 W (low stage), 10W (high stage)

We confirmed the enough heat capability of our cryogenic system

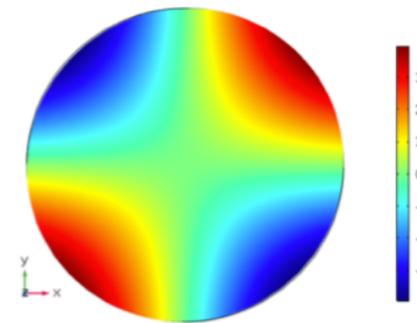
Coating measurement system



t0.5mm×φ3 inches

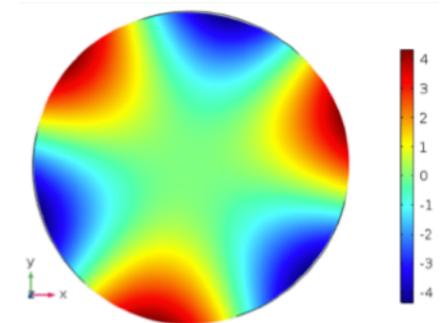


720Hz

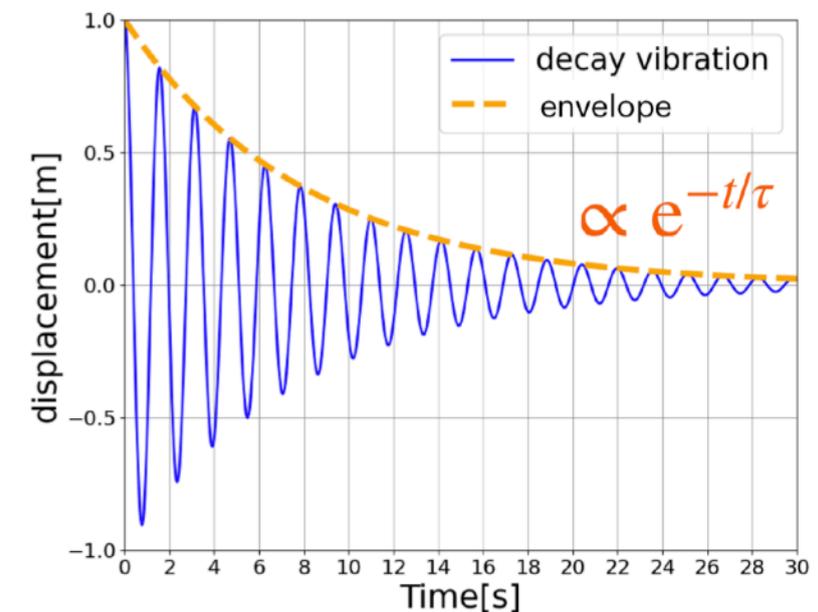
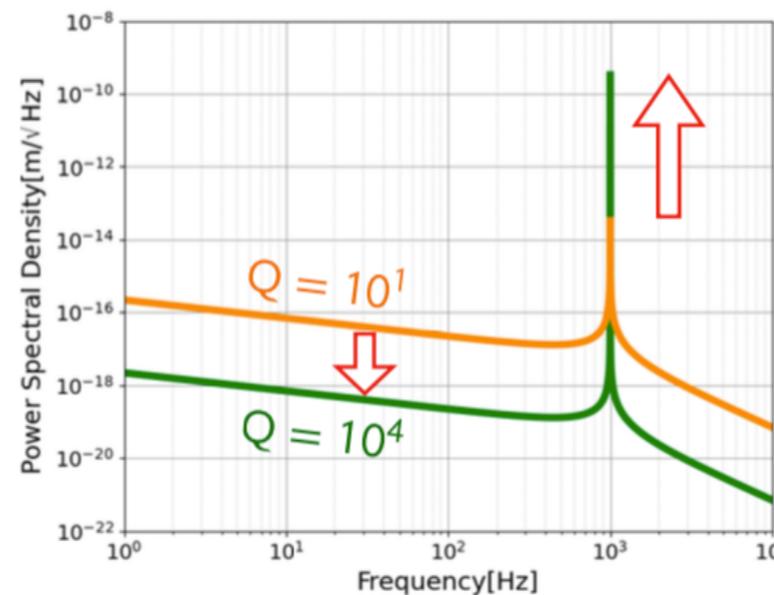


1st mode

1653Hz



3rd mode



$$G_{\text{thermal noise}} \propto \sqrt{T\phi_{\text{loss}}(\omega)}$$

- We are developing the coating characterization system for measurement of coating in CHRONOS.

Cryogenic photo-thermal common-path interferometry system

TOP VIEW

Moving stage 1

Cryogenic chamber

MOVING STAGE 1

MOVING STAGE 2

50K

4K
Sample
(Coating&reference)

Flexible heatlink

Chopper

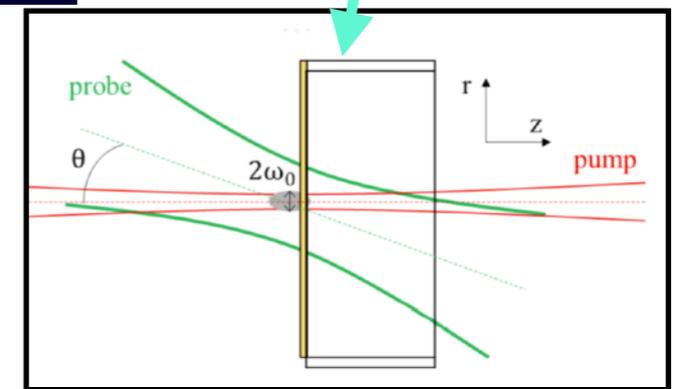
Pump laser

Probe laser

Moving stage 2

Lock-in
Amplifier

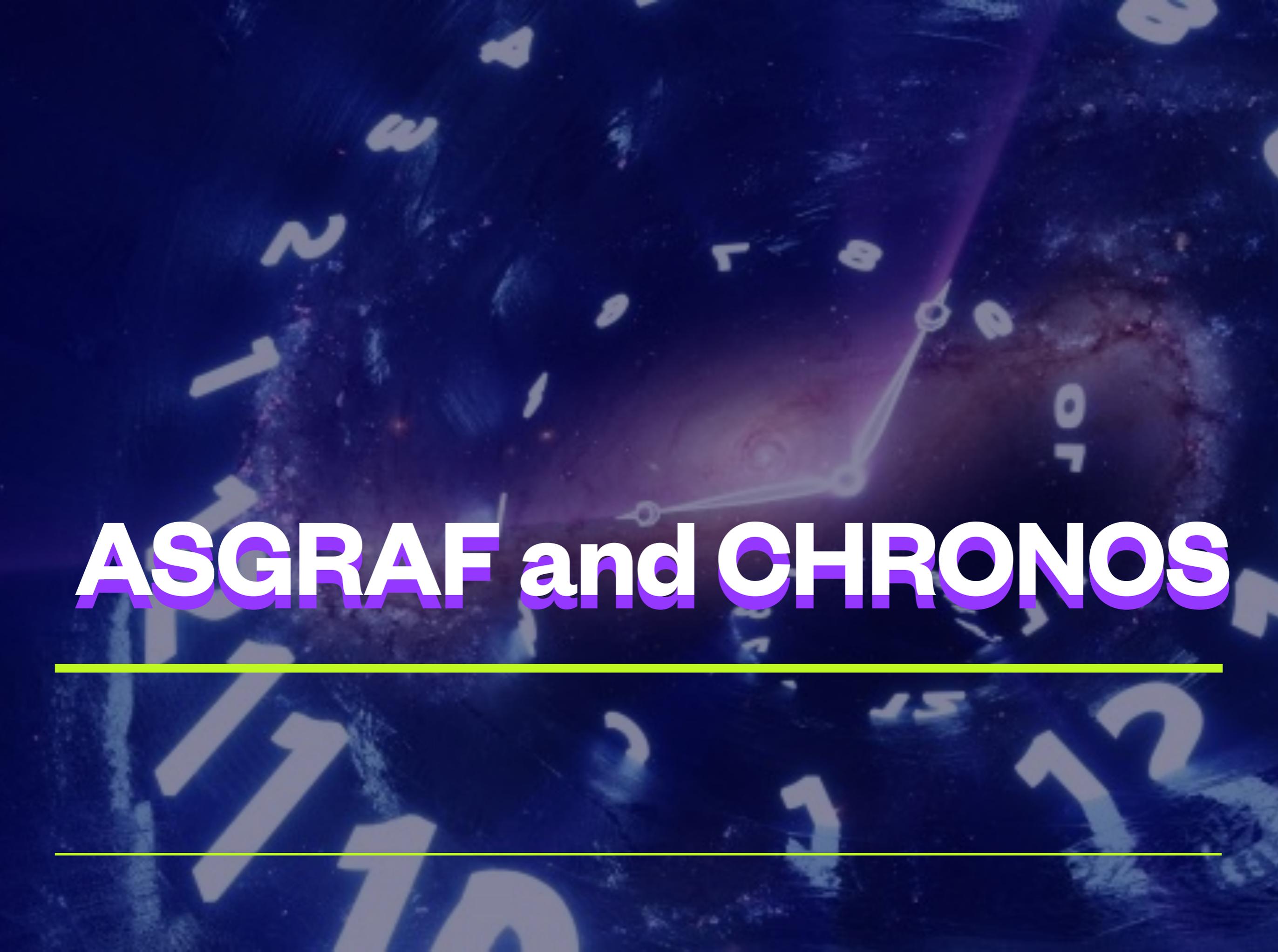
reflecting lens



Moving stage 1: Replace Coating sample and reference sample

Moving stage 2: Alignment of sample position

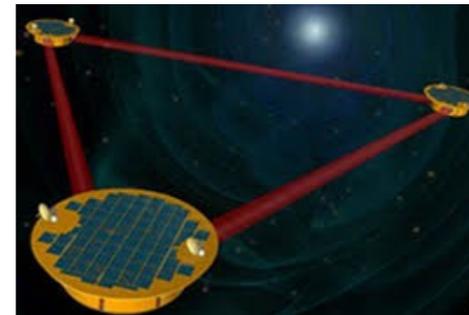
- We will mount the radiation shield around the sample
- We can replace the mirrors with piezo motor.
- We employ the high purity aluminum wire for moving cryogenic stage.



ASGRAF and CHRONOS

Introduction

2035: START OF GW SATELLITE MISSION



15 years

What should we do 15 years for GW science in Taiwan??

2020: START OF WORLDWIDE JOINT OBSERVATION



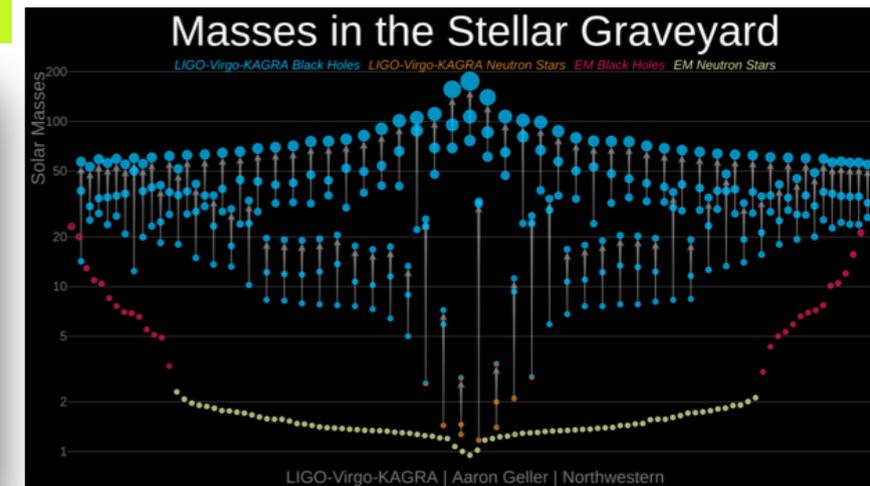
LIGO



VIRGO

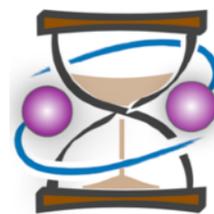


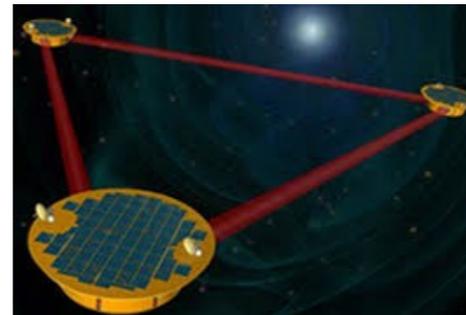
KAGRA



Introduction

2035: START OF GW SATELLITE MISSION

 **CHRONOS**



15 years

What should we do 15 years for GW science in Taiwan??

2020: START OF WORLDWIDE JOINT OBSERVATION



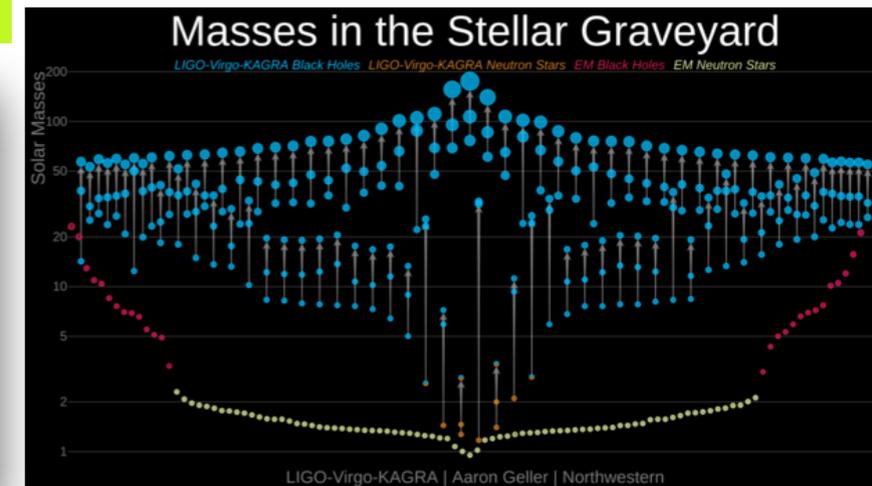
LIGO



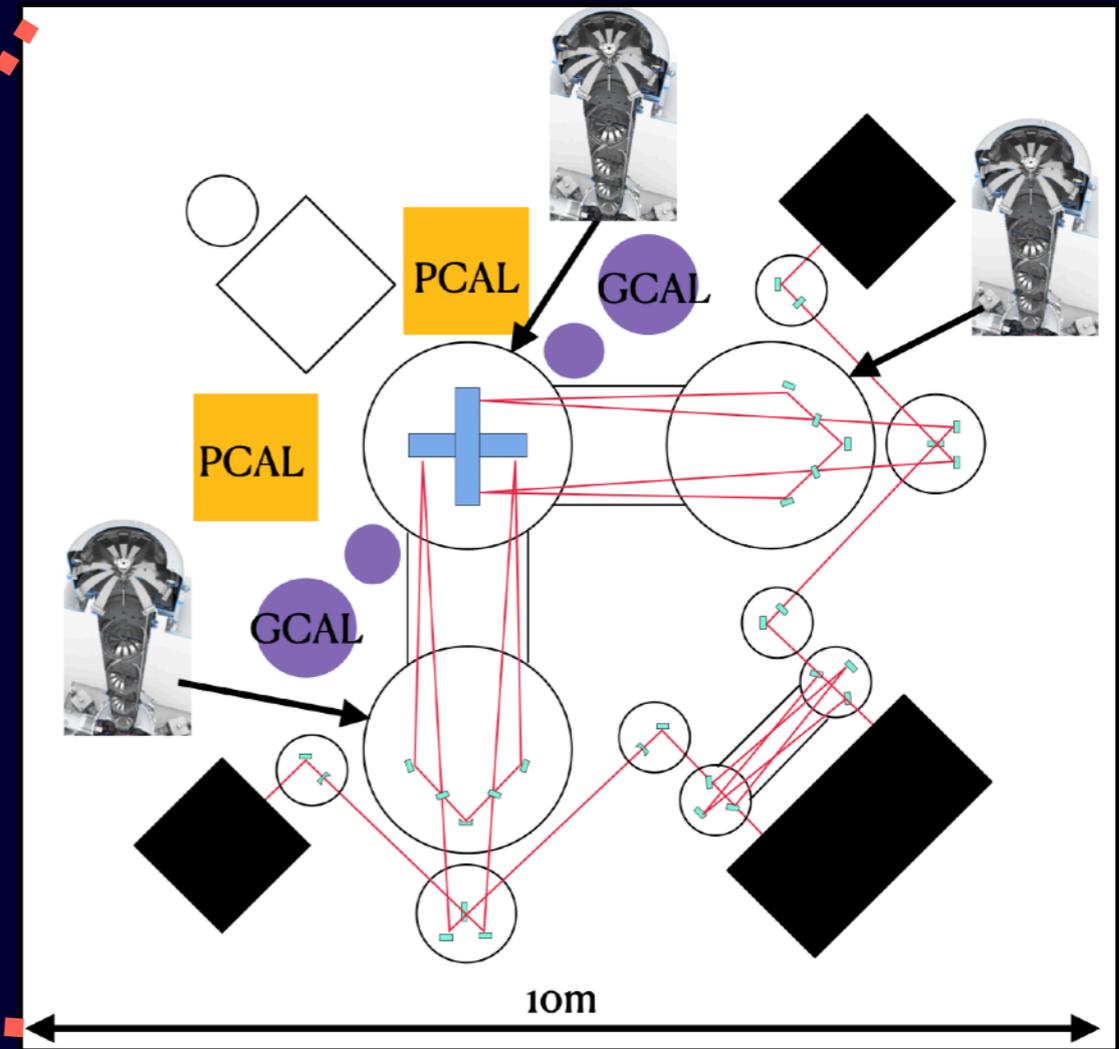
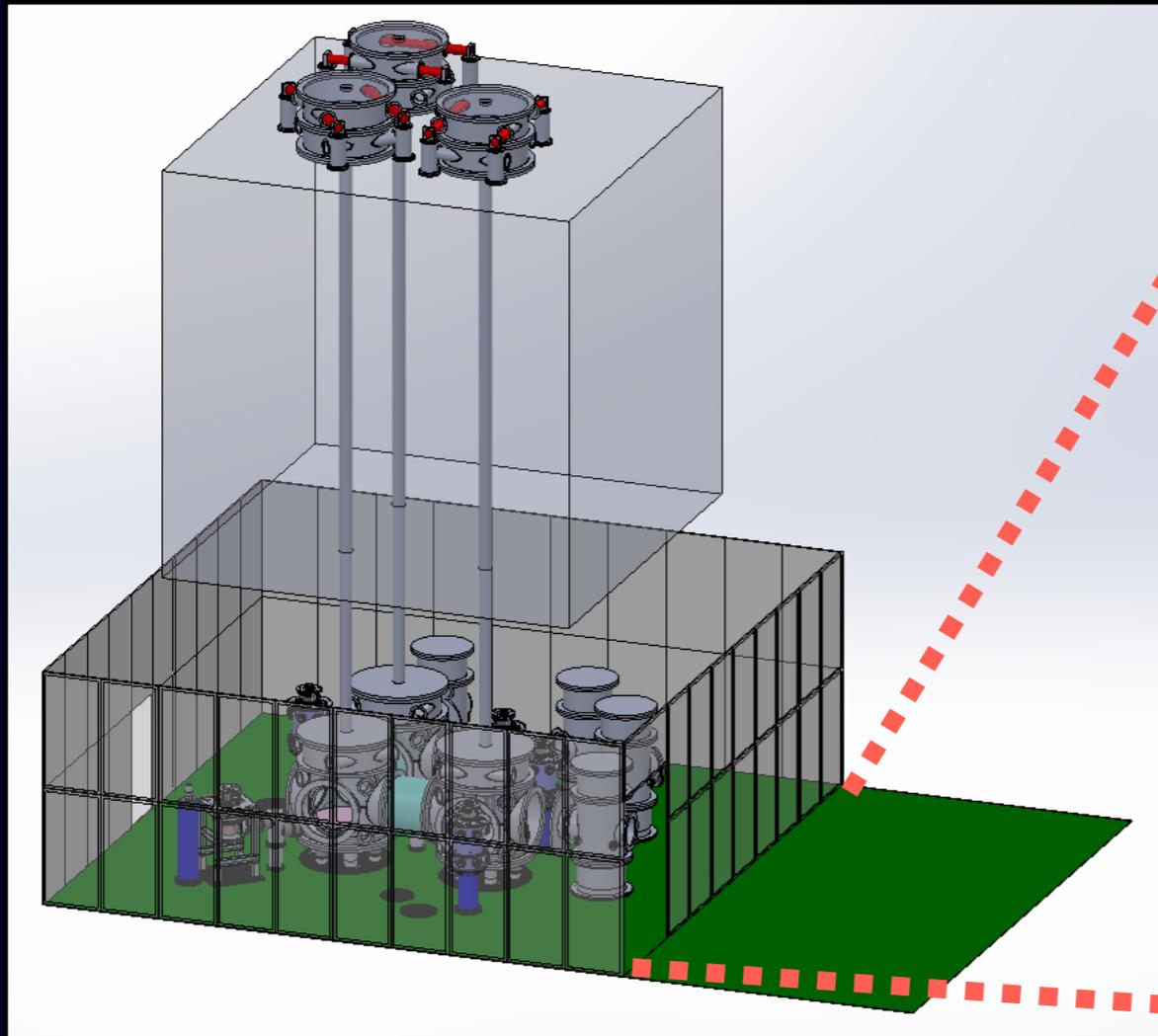
VIRGO



KAGRA



CHRONOS Overview



Cryogenic sub-**H**z **cR**Oss torsion bar detector
with quantum **N**on-demolition **S**peed meter

Collaborator of CHRONOS

National Central University

Yuki Inoue (PI)
Daiki Tanabe
Ko-Han Chen
Miftahul Ma'arif
Hong-Lin Lin
Tsung-Chieh Ho
Dennis
You-Ru Lee
Hsiang-Yu Huang
Chiu Yi-Hsuan
Tseng Shun-Lin

Academia Sinica

Tsz-King Wong
Fong-Kai Lin
Cheng-I Chiang
Hsiang-Chieh Hsu
Afif Ismail
Niko
Chen Yung-Ying

NTHU

Chao Shiu
Debby Lin
Martin Spinrath

TKU

Guo-Chin Liu

KEK

Masaya Hasegawa

NTNU

Chen Chuan-Ren
Chrisna Setyo Nugroho



CHRONOS Overview

- Mission: Search for Intermediate black hole on Sub-Hz range
- Method: Interferometrical Speed meter
- Full success: First detection of Intermediate Black hole merger on $O(10^4 M_{\odot})$ range
- Unique point: 10m x 10m Observatory

SPEED METER

Key technologies

CRYOGENIC

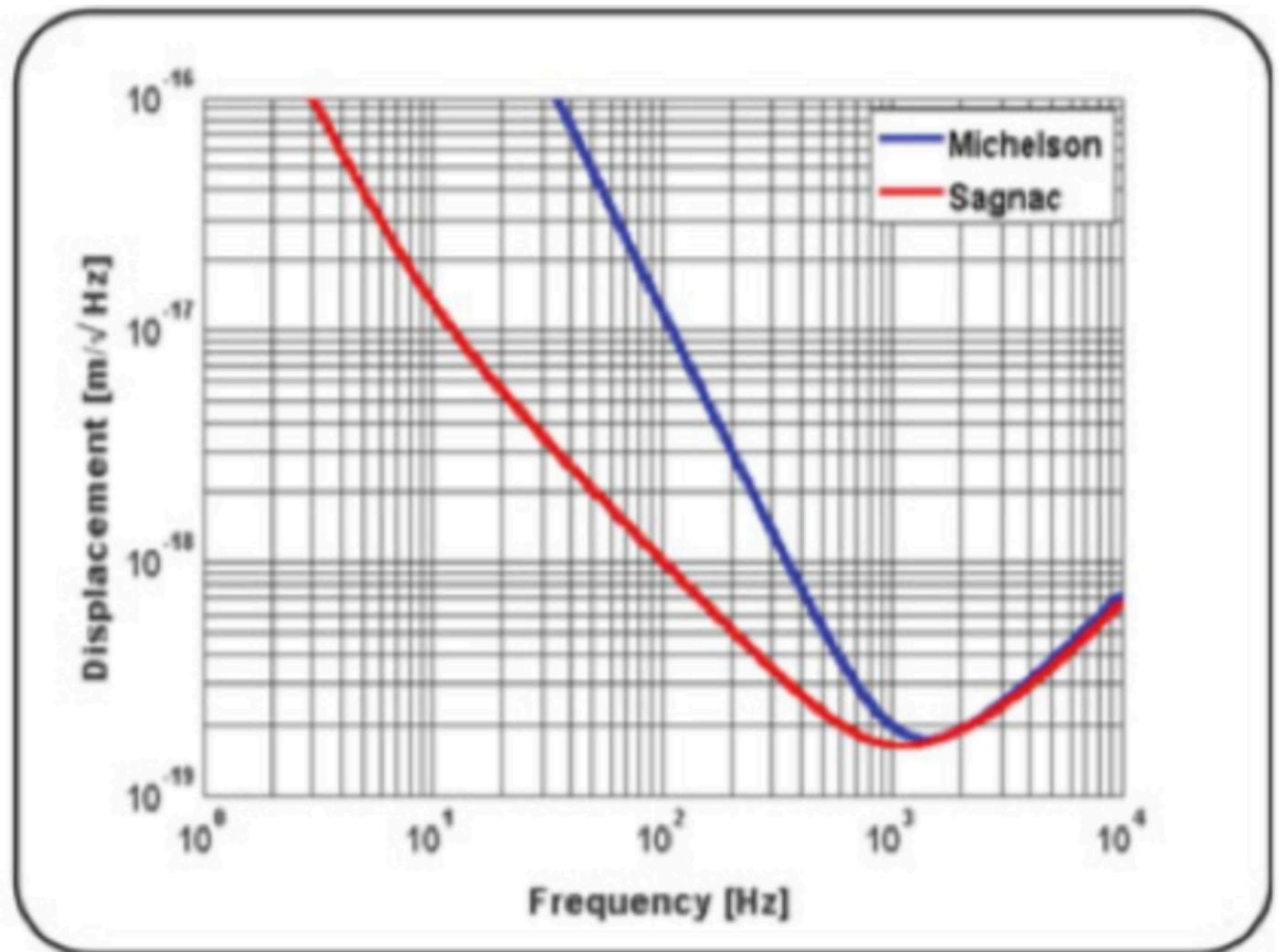
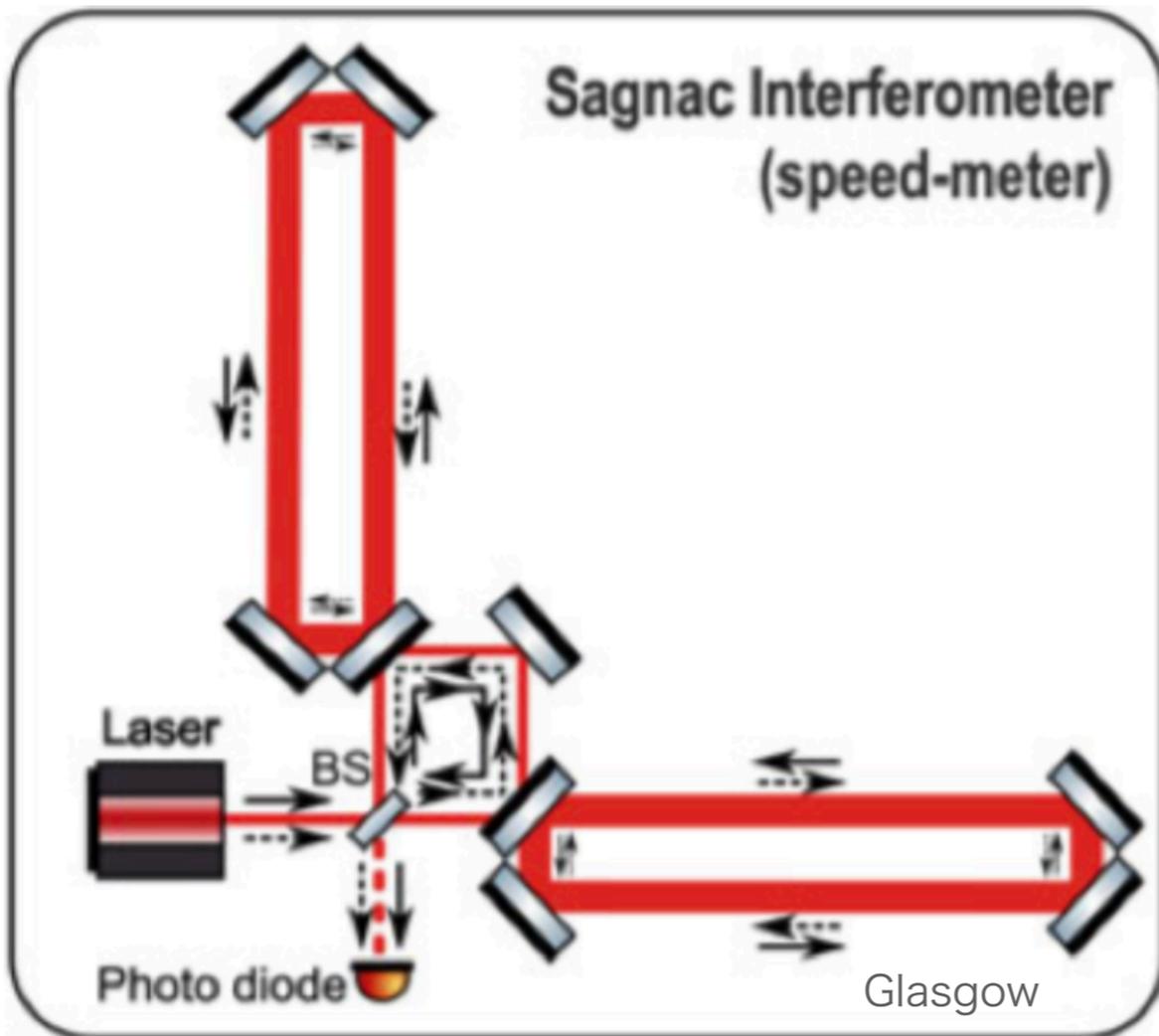
TORSION BAR

CHRONOS Phase

- Location: Underground site in Taiwan
- R&D is ongoing
- Phase 1: R&D for Key technologies (2020-2022)
- Phase 2: Integration test in ASGRAF (2022-2025)
- Phase 3: Insulation and Commissioning of CHRONOS in Underground lab (2025-2027)

CHRONOS's target observation year = 2027

Fabry-Pérot Michelson vs. Sagnac Speed meter



	Fabry-Pérot Michelson	Sagnac speed meter
Input	$ma = F = A \exp(i\omega t)$	$ma = F = A \exp(i\omega t)$
Output	$ x = A / (m\omega^2) \exp(i\omega t) = F / (m\omega^2)$	$ v = A / (m\omega) \exp(i\omega t) = F / (m\omega)$

LIGO White paper

LASER INTERFEROMETER GRAVITATIONAL WAVE OBSERVATORY
- LIGO -

LIGO SCIENTIFIC COLLABORATION

Technical Note	LIGO-T2000407-v3	2020/08/31
Instrument Science White Paper 2020		
LIGO Scientific Collaboration		

Distribution of this document:
LIGO Scientific Collaboration

California Institute of Technology
LIGO Project, MS 100-36
Pasadena, CA 91125
Phone (626) 395-2129
Fax (626) 304-9834
E-mail: info@ligo.caltech.edu

Massachusetts Institute of Technology
LIGO Project, Room NW22-295
Cambridge, MA 02139
Phone (617) 253-4824
Fax (617) 253-7014
E-mail: info@ligo.mit.edu

LIGO Hanford Observatory
P.O. Box 159
Richland, WA 99352
Phone (509) 372-8106
Fax (509) 372-8137
E-mail: info@ligo.caltech.edu

LIGO Livingston Observatory
19100 LIGO Lane
Livingston, LA 70754
Phone (225) 686-3100
Fax (225) 686-7189
E-mail: info@ligo.caltech.edu

<http://www.ligo.org/>

SPEED METER

LT-4.4.5 Speed meter

Normally, a GW detector measures the test mass position at different times to infer the signal. However, position at different times does not commute with the Hamilton operator of a free mass. According to quantum measurement theory (151), such a measurement process inevitably introduces quantum back action and perturbs the test mass motion. (In the context of GW detectors, the back action is the radiation-pressure noise.) In order to evade back action, one needs to measure the conserved dynamical quantity of the test mass—the momentum. The latter is (approximately) proportional to speed, which is why a *speed meter* is ideal for measuring gravitational waves with greatly reduced radiation-pressure noise (105).

CRYOGENIC

LT-7.3.5 Cryogenics

It has long been known that cryogenically cooled test masses can have much improved material parameters which lead to significant reductions in thermal noise. However, operating at cryogenic temperatures presents multiple new challenges which need to be addressed. The most pressing is to find ways to cool the temperature, to isolate the mirrors from their hot surroundings and to constantly extract the deposited laser heat without short-circuiting the suspension and seismic isolation system. Detailed thermal models have to be developed and tested to maximize radiative and conductive cooling paths.

LIGO also has common technical issue for future GW technology



Procedure of technical demonstration in LIGO

TEST FACILITIES

US

CAHTECH 40M



EU

GE0600



GLASGOW 10M



ASIA



There is no test facility of LIGO in Asia!

LIGO HANFORD OBSERVATORY



LIGO LIVINGSTON OBSERVATORY



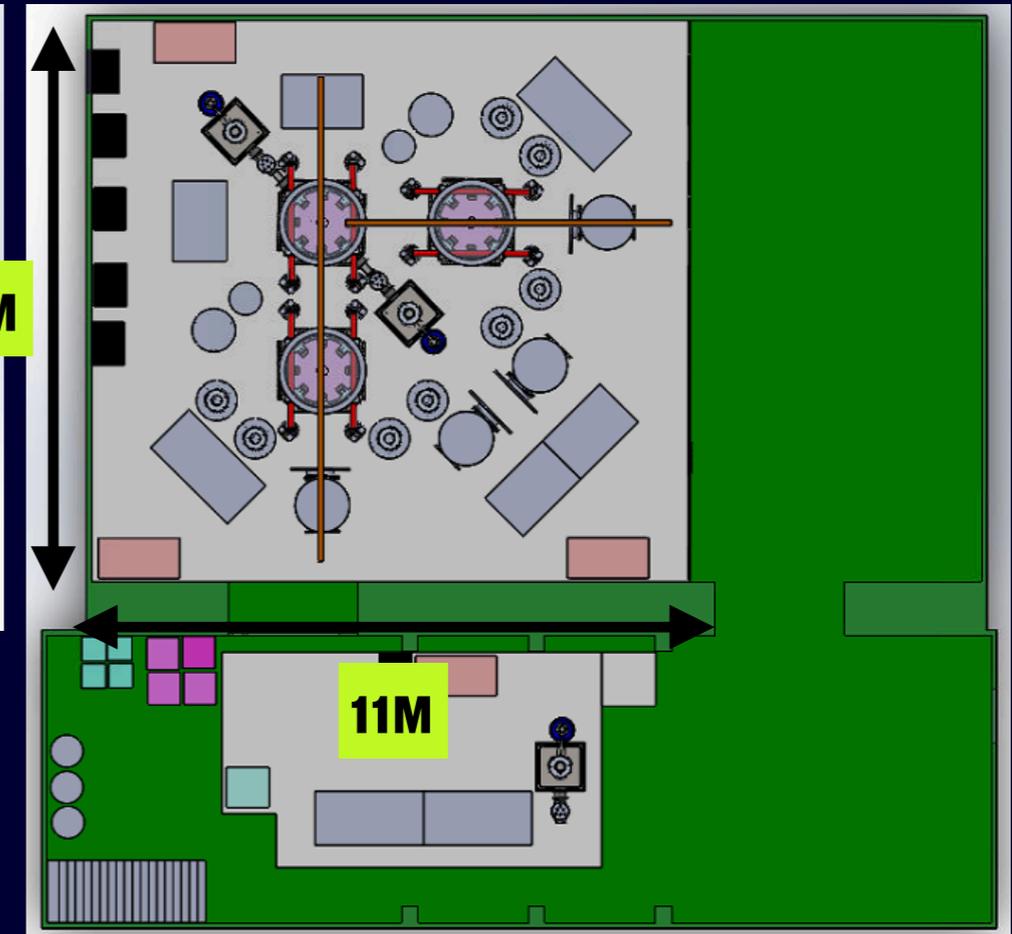
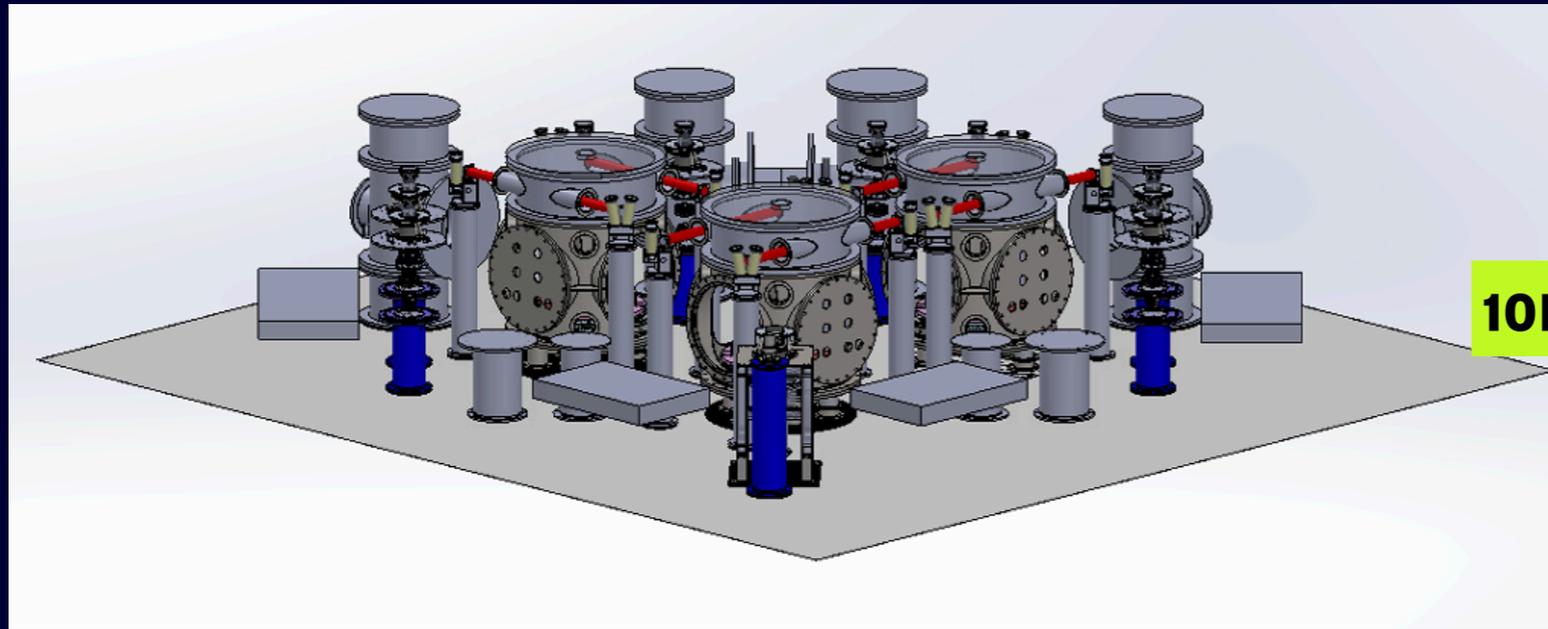
Academia Sinica Gravitational physics

Research Facility (*ASGRAF*)

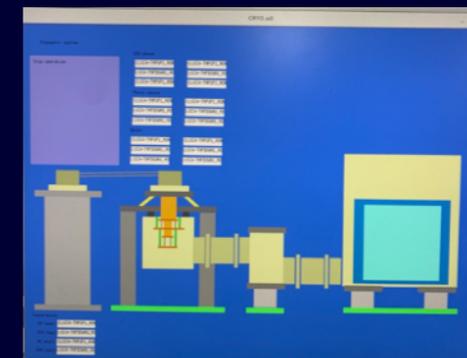
- Location: Academia Sinica Institute of Physics (B1 floor)
- Environment: 10m x 11m Class 10000 clean room and Class1000 clean booth
- Cryogenic Interferometer
- Main purpose: R&D of gravitational wave technologies



Academia Sinica Gravitational physics Research Facility (ASGRAF)



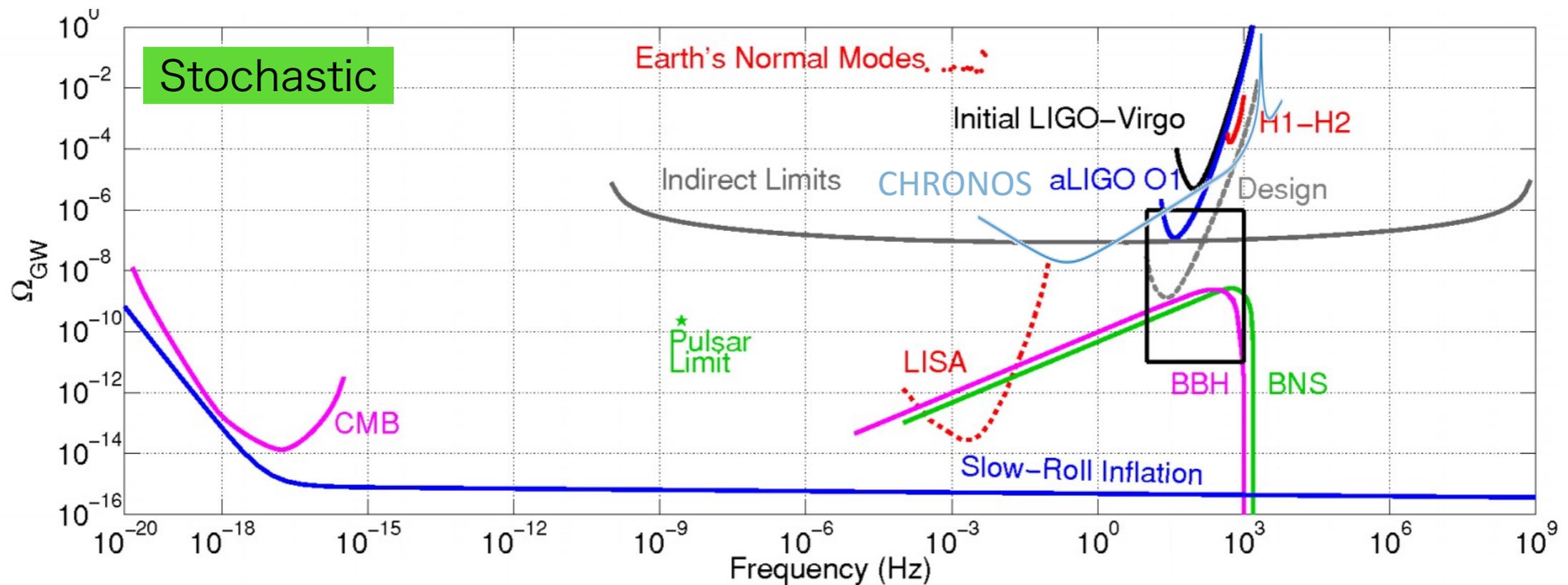
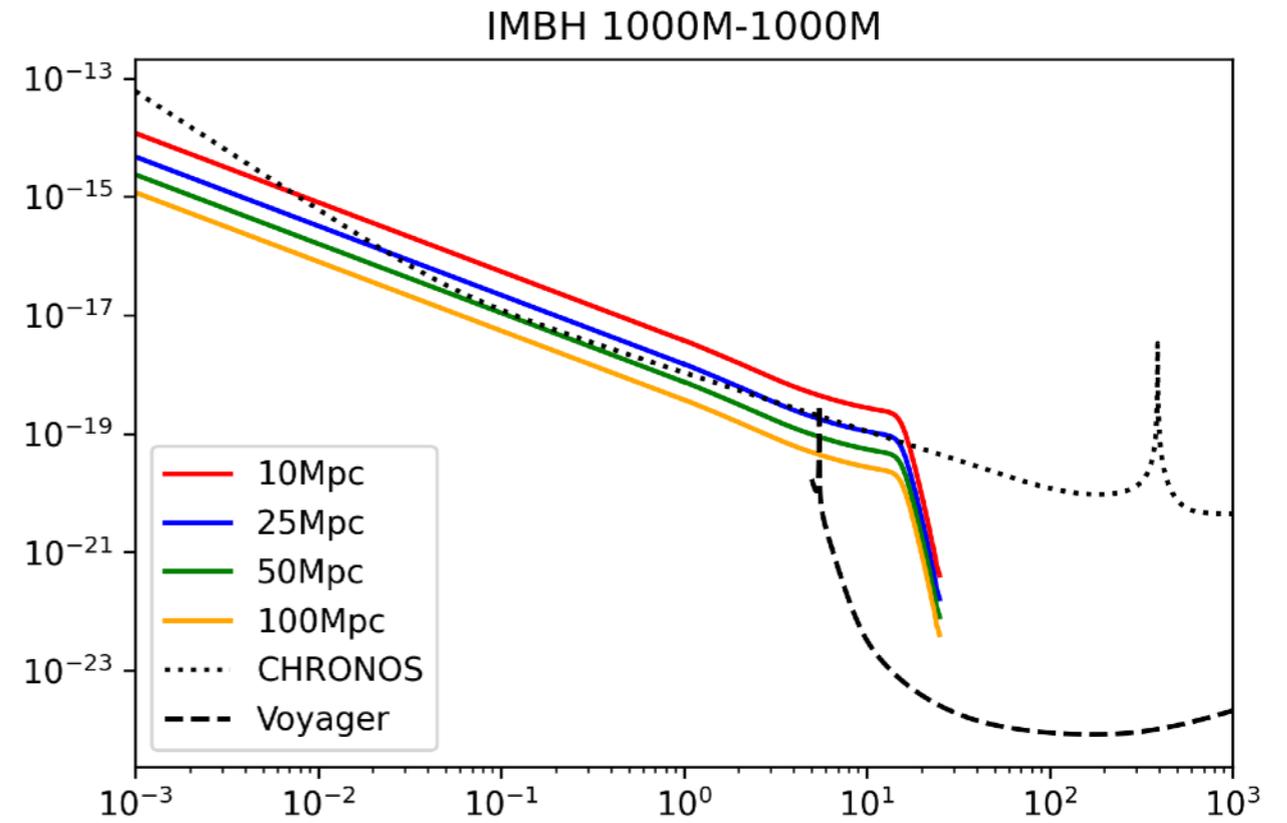
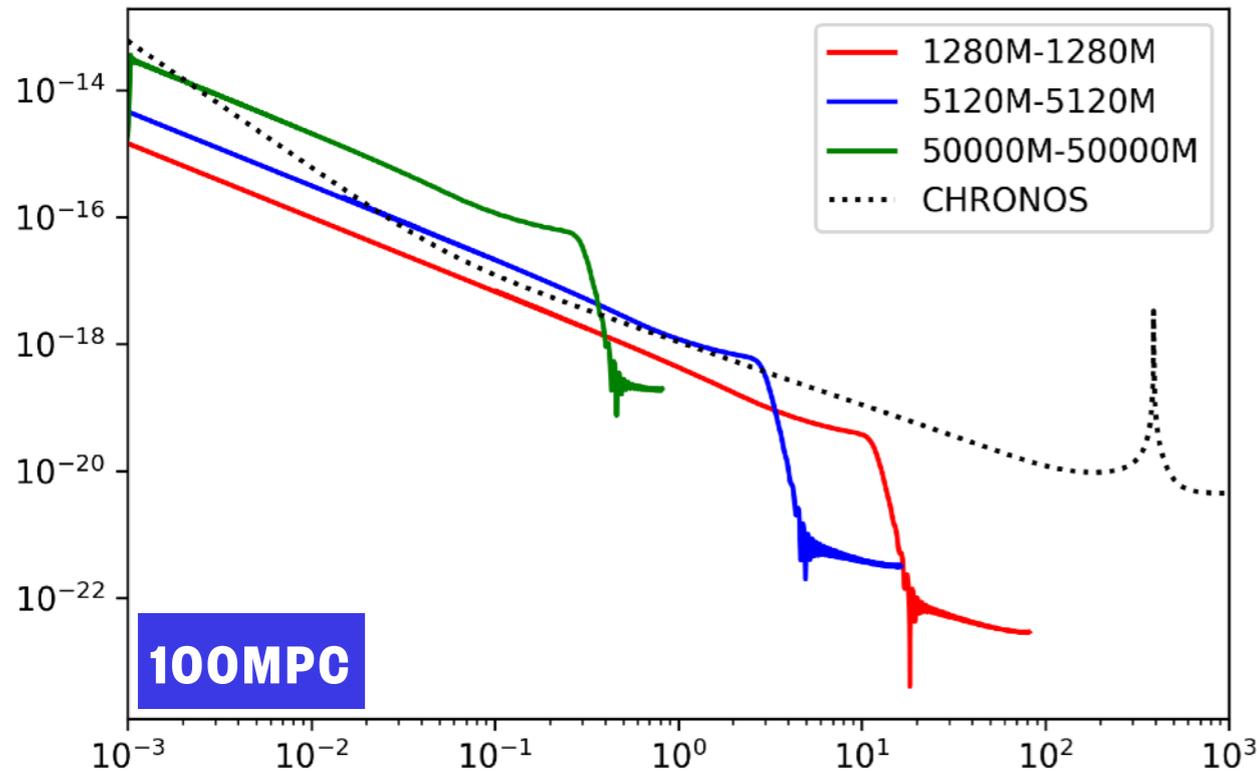
- Cryogenic Active Vibration isolation system
- Controlled by Digital Control System
- Dual recycling interferometer
- Verification of calibration instruments
- Apply for Geoscience



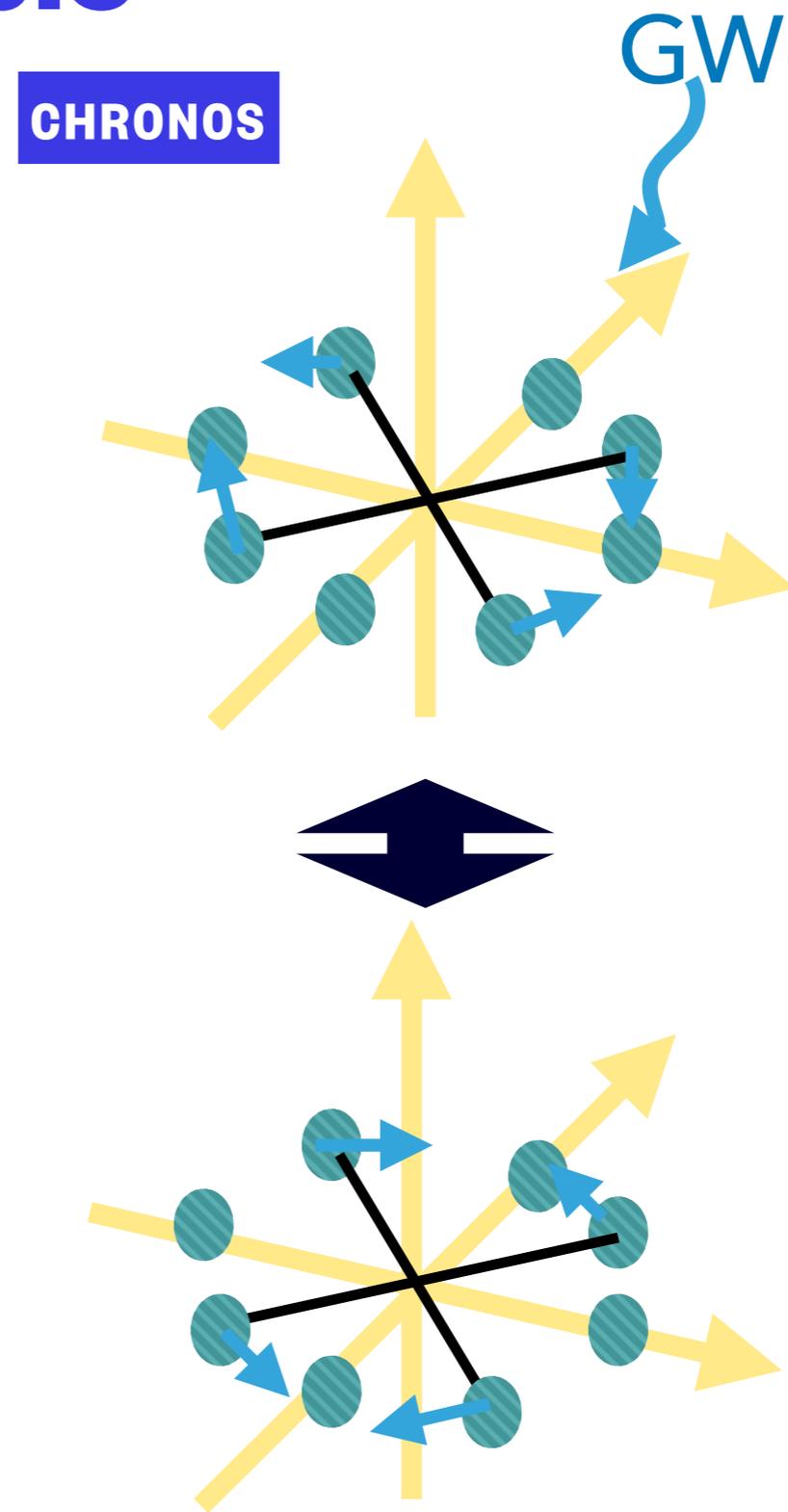
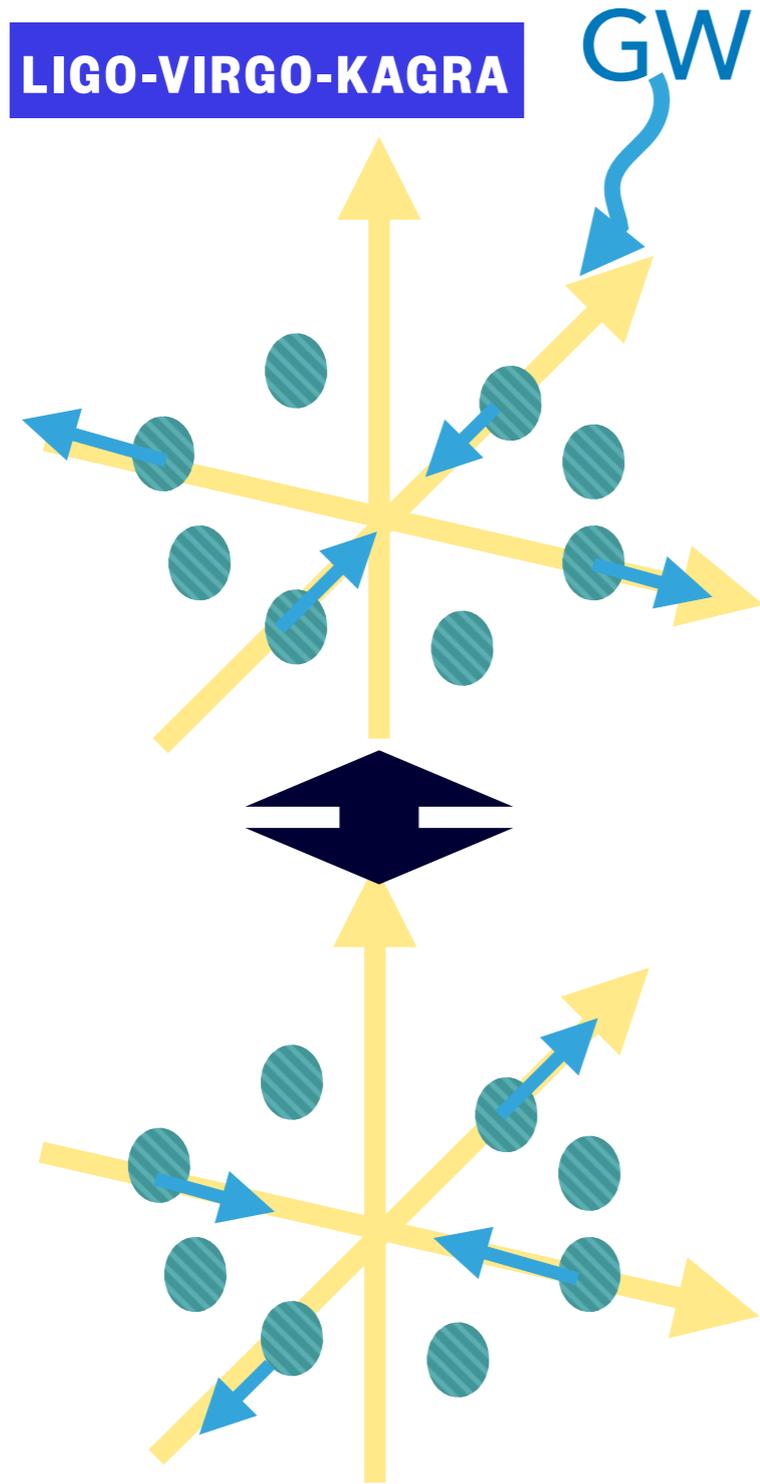
Benefit of ASGRAF for future application

- We can give a good training of interferometer control in Taiwan. We will send the human resource to LIGO after COVID-19.
 - We can test the new GW technology in Taiwan. If we can try actual contribution, ASGRAF will be a test facility of LIGO in Asia.
 - CHRONOS itself has interesting science. This technology can be applied for future LIGO. In any case, our effort can be led for the essential contribution in GW science
 - System is totally same as LIGO. So, we can test the LIGO's software in ASGRAF.
-

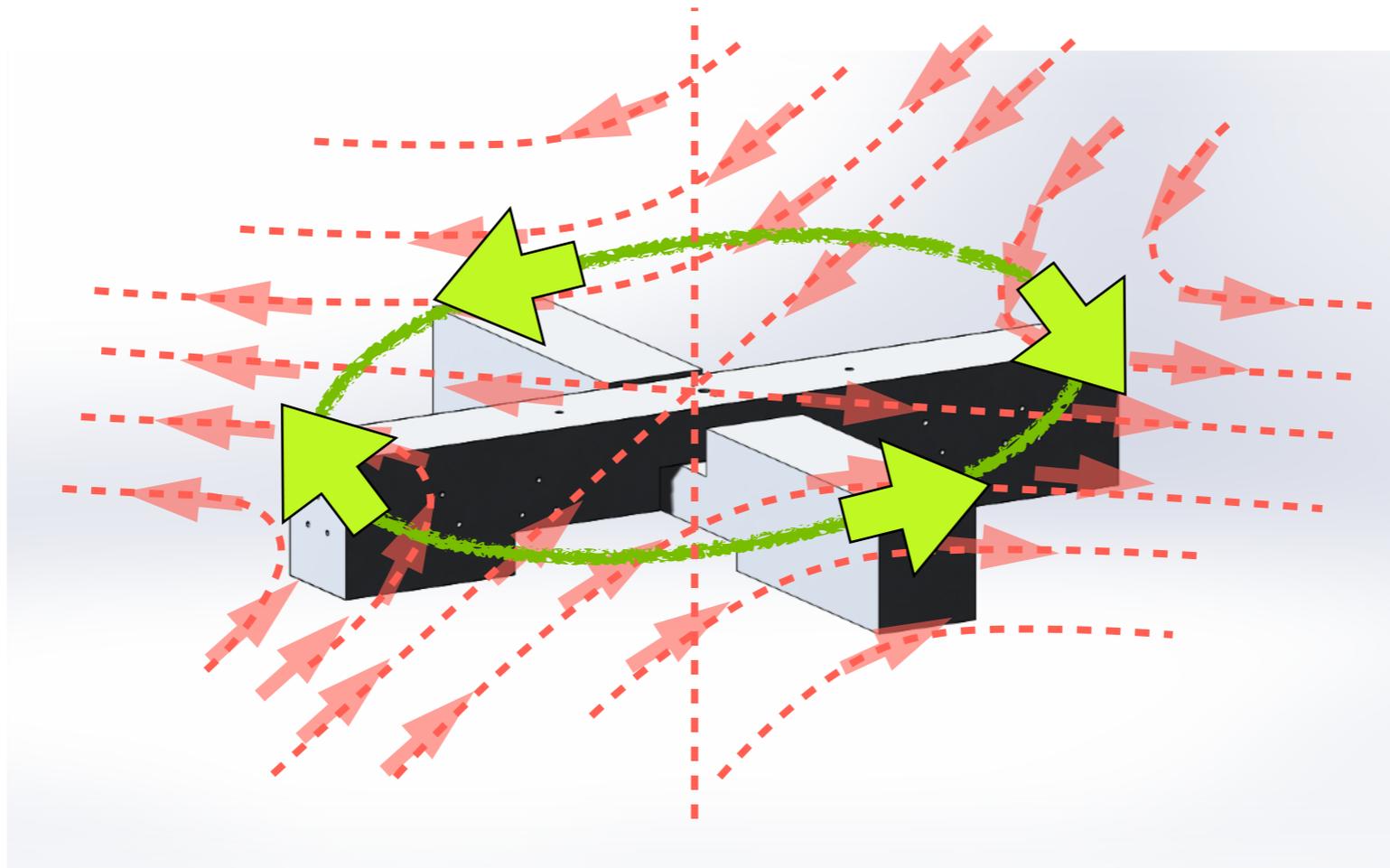
Expected Science



Comparison of principle

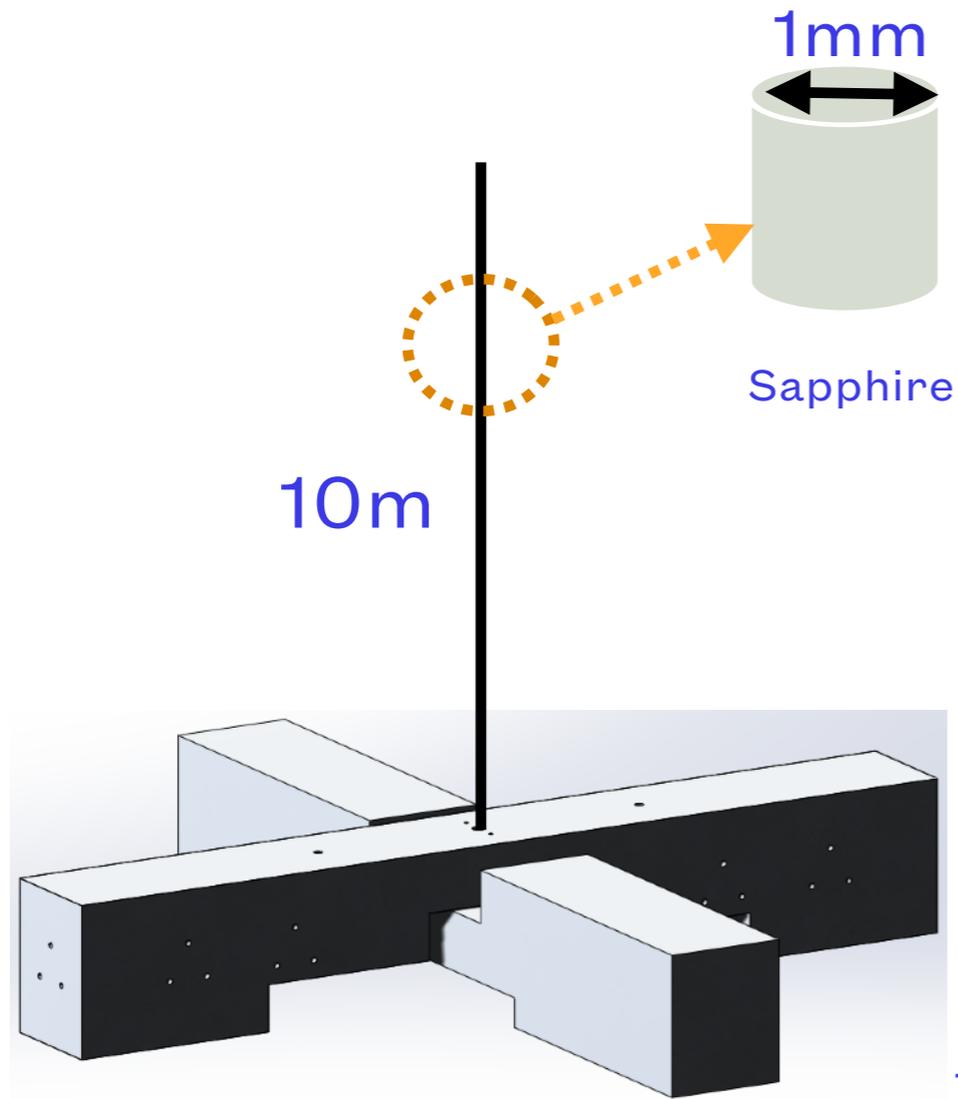


Torsion bar in Gravitational Wave

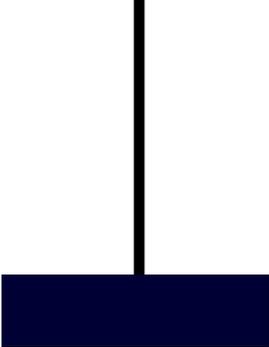


- Torsion bars keep staying through the metric
- Tensor mode metric perturbation (= Gravitational wave) change the relative angle of cross bars
- By measuring relative angle, we can reconstruct the gravitational wave foam, $h(t)$.

Resonant frequency



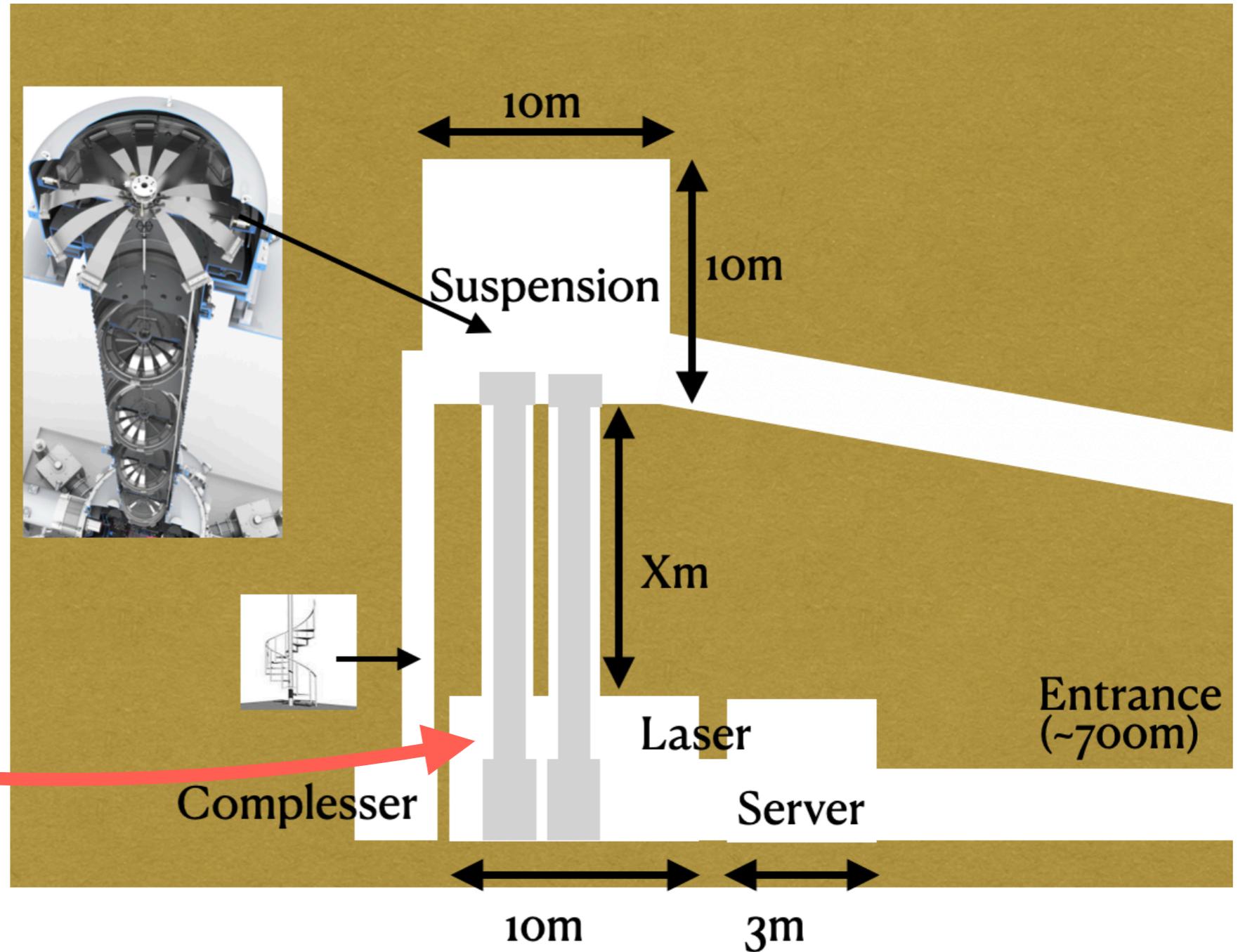
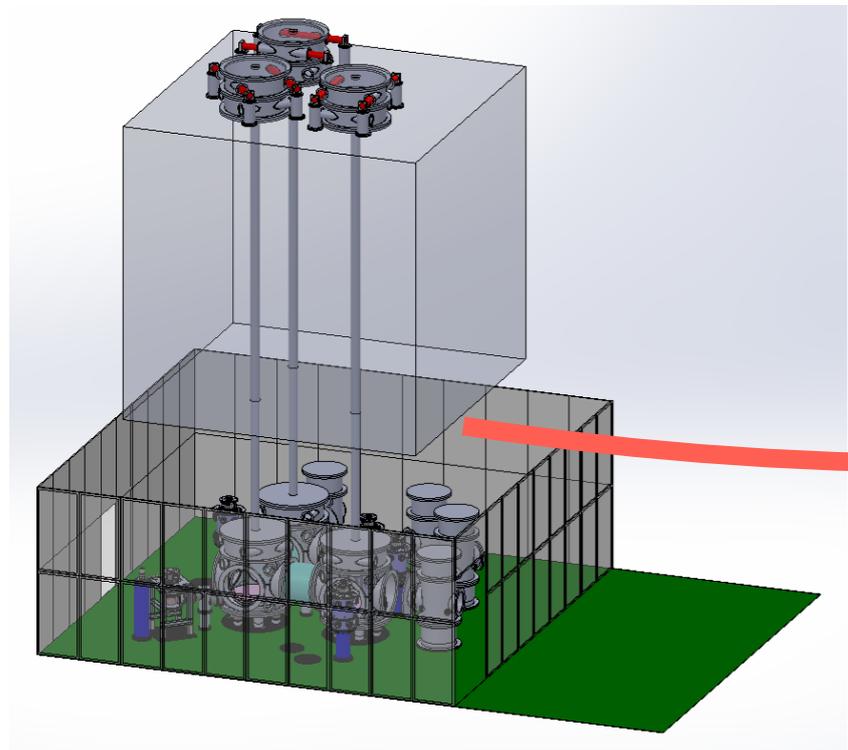
Typical value
($l=10\text{m}$, $d=1\text{mm}$)

	LVK	CHRONOS
type	 Pendulum	 Torsion bar
EOM	$m\ddot{x} + c\dot{x} + kx = F$	$I\ddot{\theta} + \Gamma\dot{\theta} + \mu\theta = \tau$
Resonant Freq.	$f = \frac{1}{2\pi} \sqrt{\frac{g}{l}}$	$f = \frac{1}{2\pi} \sqrt{\frac{\mu}{I}}$ $\mu = \frac{\pi Gr^4}{2l}$ $G = \frac{E}{2(1+\nu)}$
Typical value	0.15Hz	0.004Hz



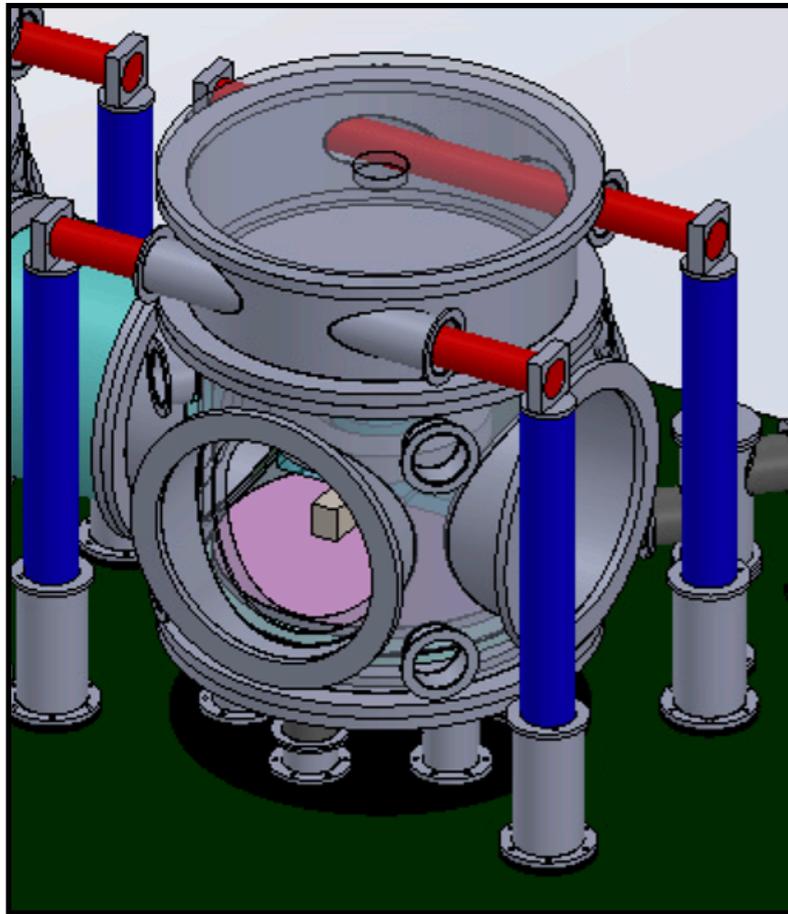
We can dramatically reduce resonant frequency

Cross section of CHRONOS observatory



Seismic isolator

Lab test



STAGE 0

$\times 1/10$

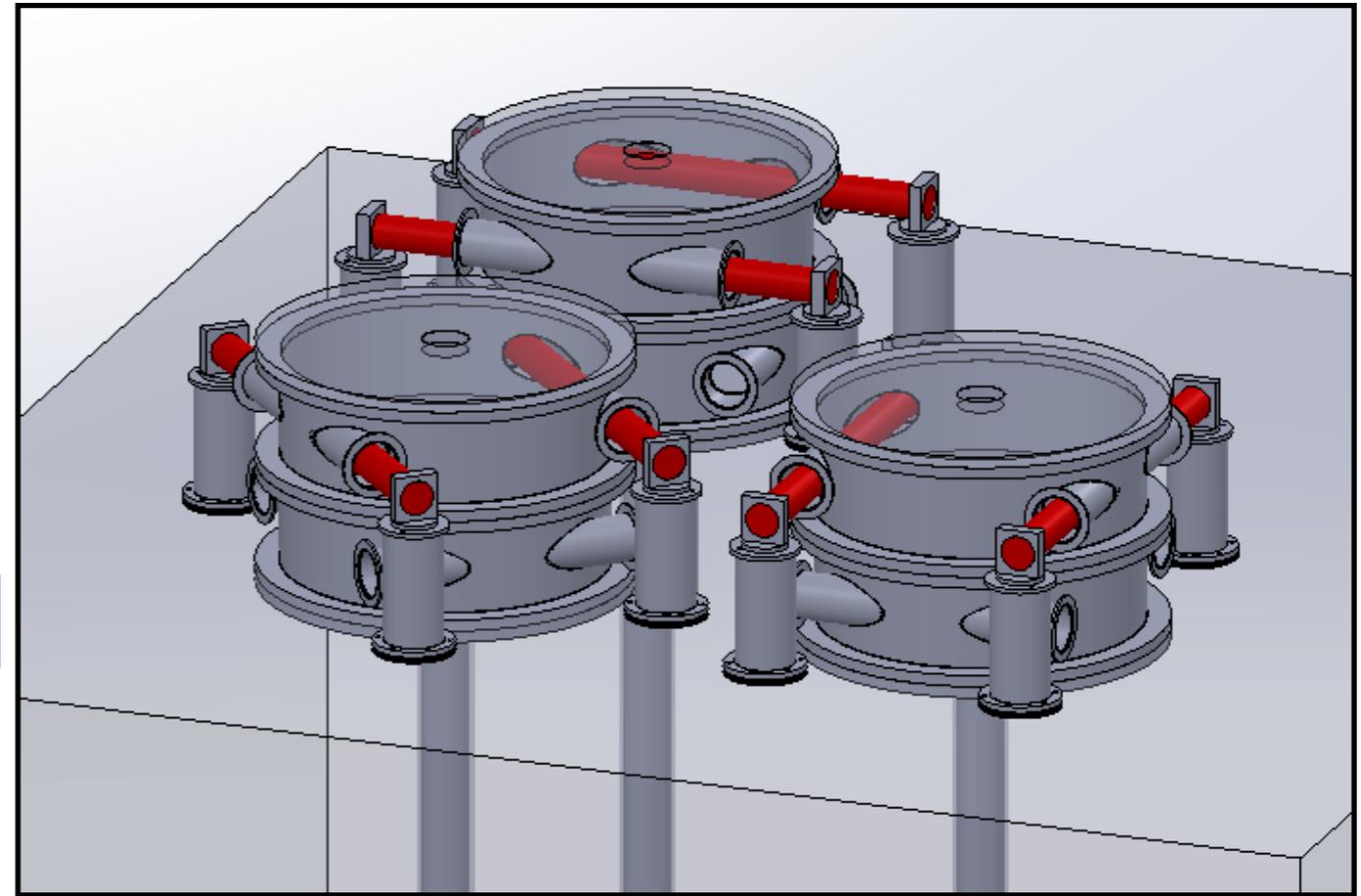
STAGE 1-3

$\times 1/1000$

10M PENDULUM

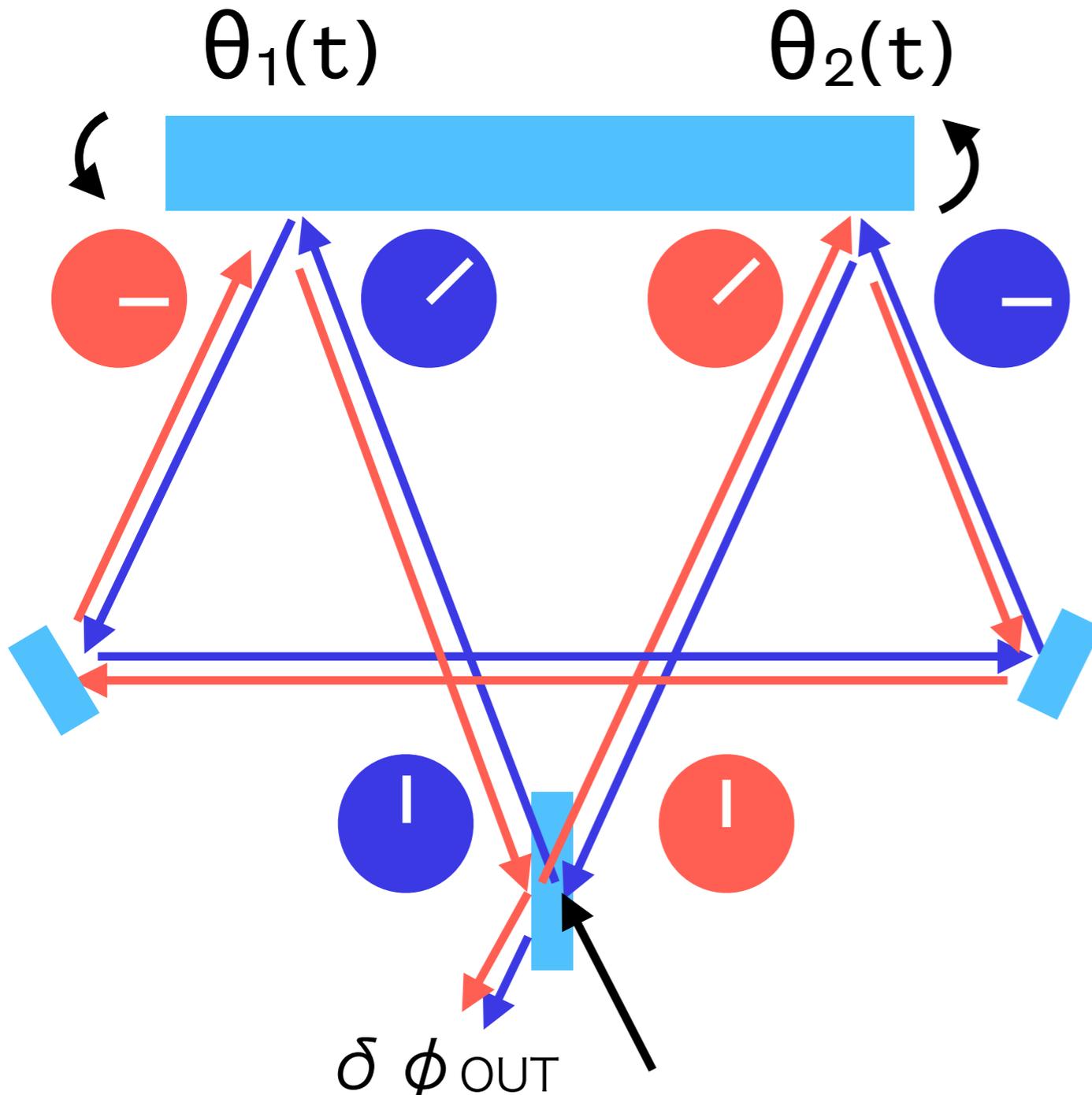
$\times 1/10^8$

Underground site



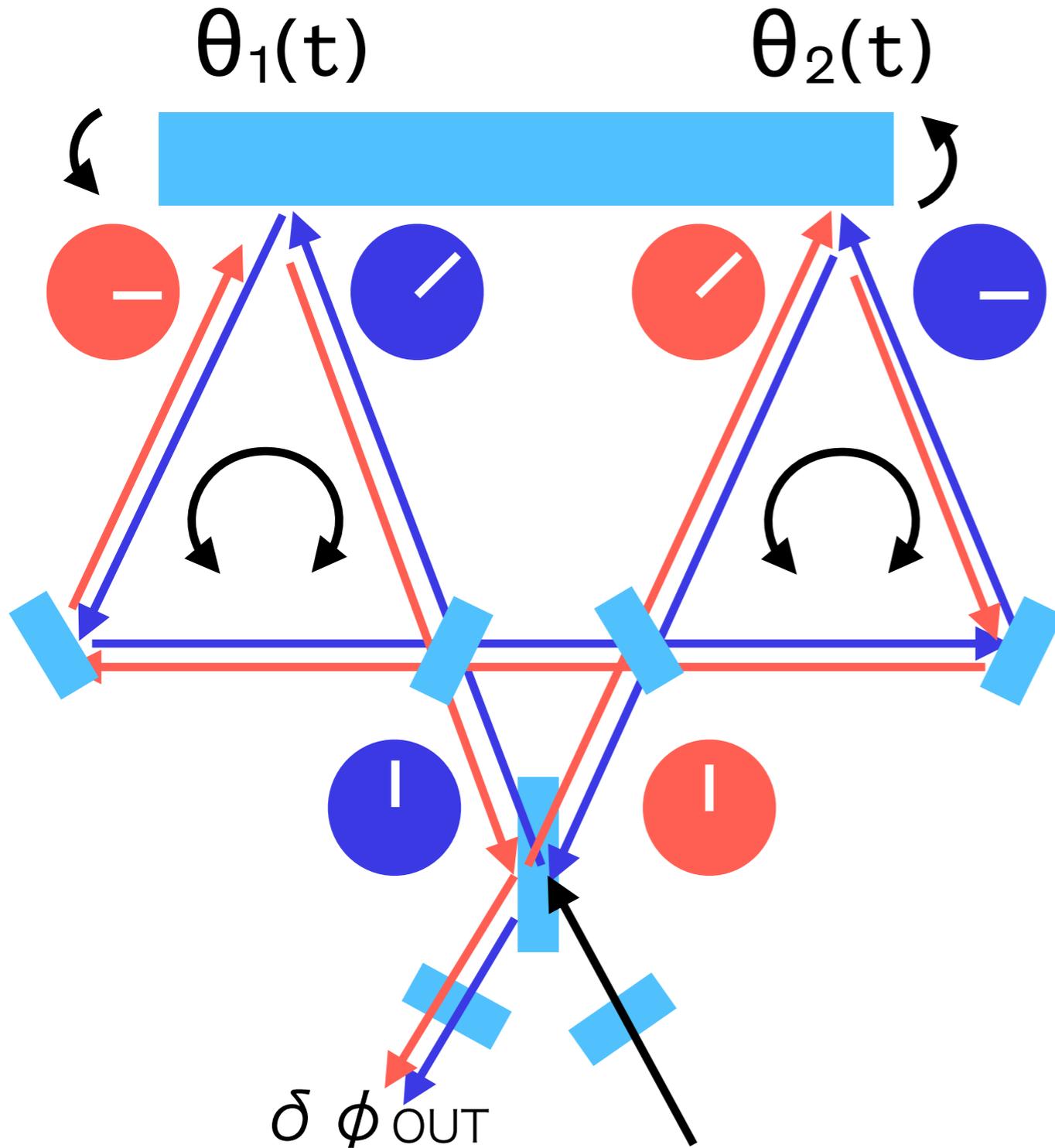
Expected Attenuation factor for rotation: $1/10^{12}$

Speed meter technique



- $\delta \phi_{CW} \propto \theta_1(t) + \theta_2(t + \tau)$
- $\delta \phi_{CCW} \propto \theta_2(t) + \theta_1(t + \tau)$
- $\delta \phi_{OUT} = \tau (\omega_{CCW} - \omega_{CW})$
- We measure the phase delay of CW and CCW beams.
- Time interval, τ , should be same.
- Similar to Sagnac Gyroscope.

Speed meter technique

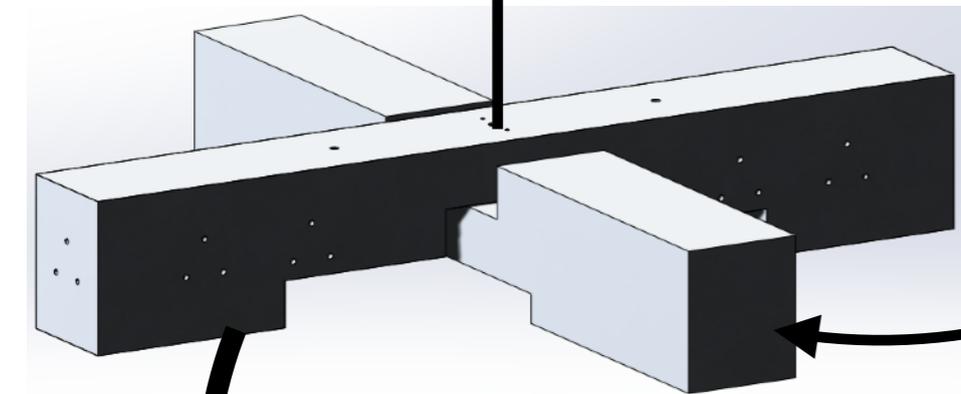


- $\delta \phi_{CW} \propto \theta_1(t) + \theta_2(t + \tau)$
- $\delta \phi_{CCW} \propto \theta_2(t) + \theta_1(t + \tau)$
- $\delta \phi_{OUT} = \tau (\omega_{CCW} - \omega_{CW})$
- Install the ring cavity to amplify the signal.
- Power recycling cavity and Signal recycling cavity are also employed
- Differential angular velocity.

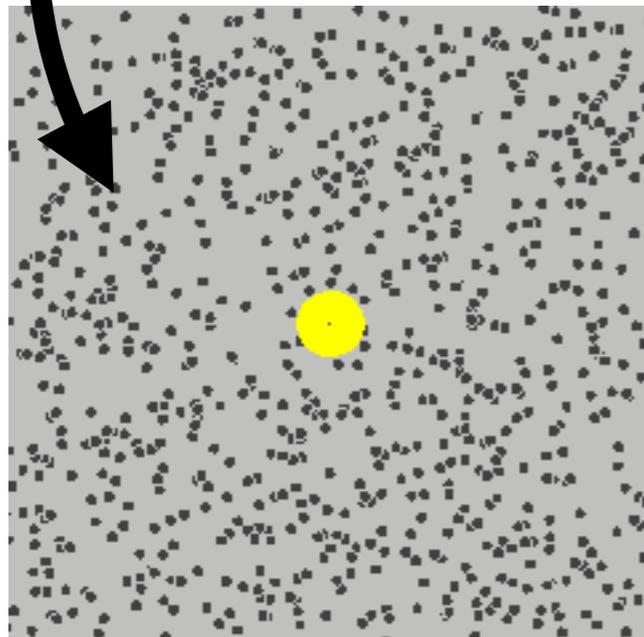
Cryogenic vibration isolation technology

$$\delta\theta_{\text{sus}} = \sqrt{4\gamma k_B T / (I \omega^2)}$$

$$\delta\theta_{\text{mass}} \approx \frac{8}{L} \sqrt{\phi_{\text{mass}} k_B T / (M \omega_{\text{bar}}^2 \omega)}$$

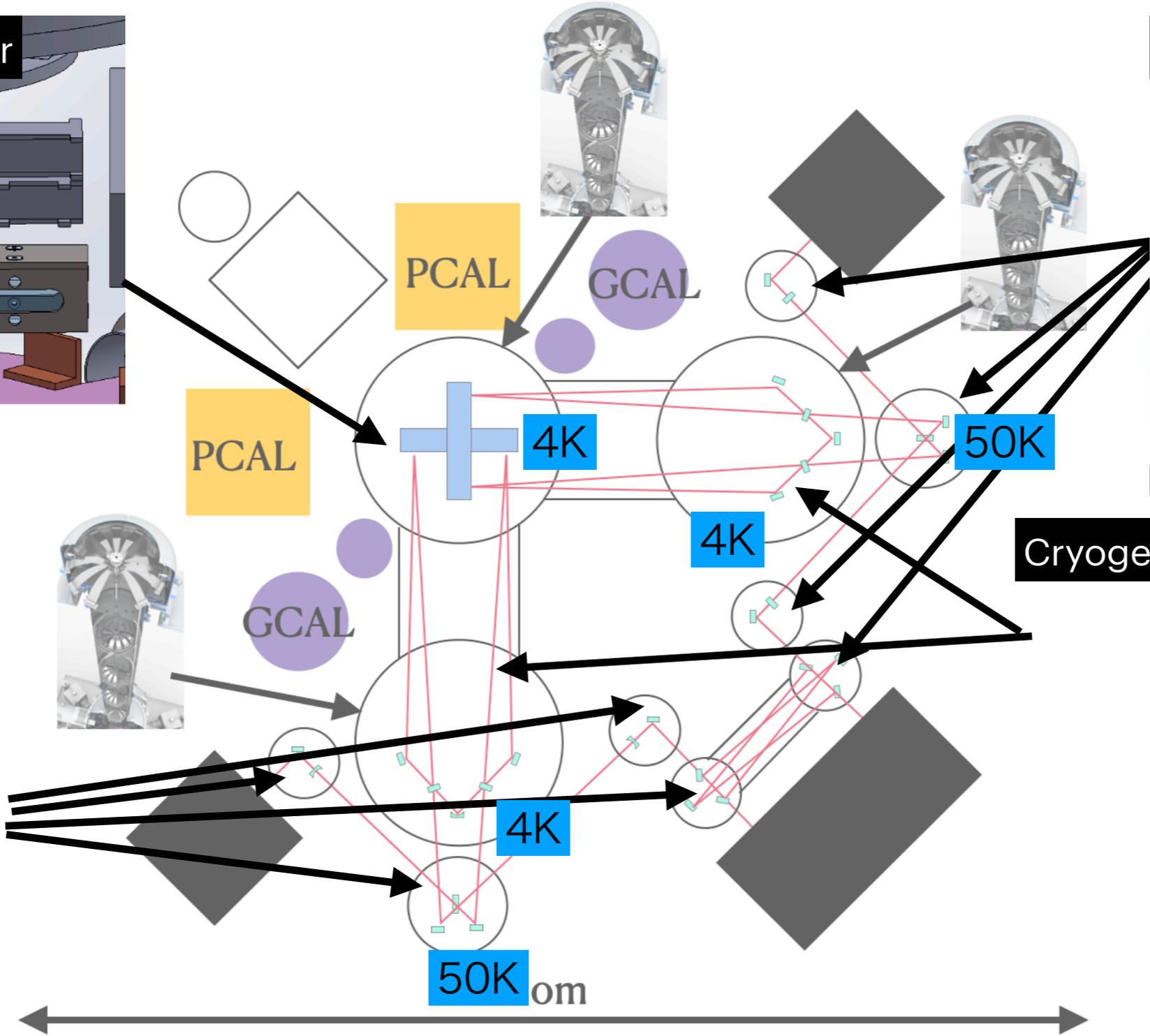
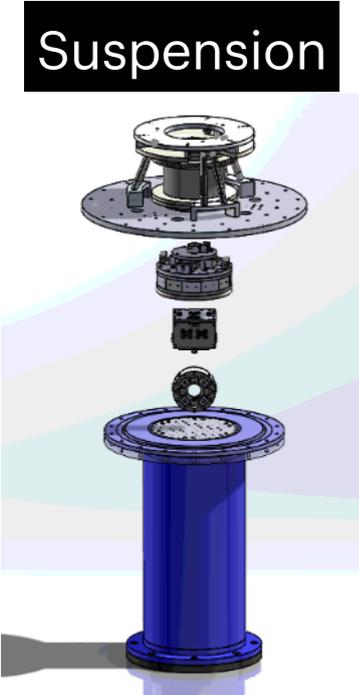
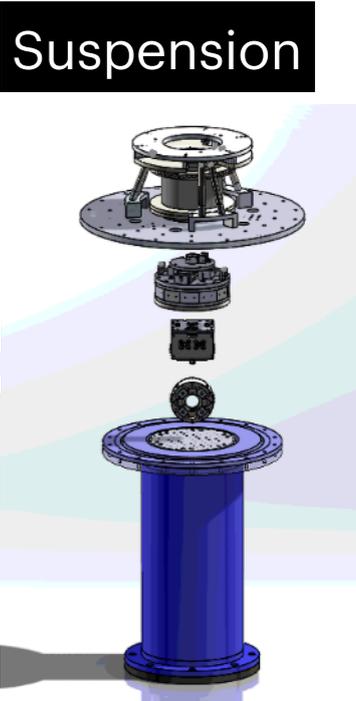
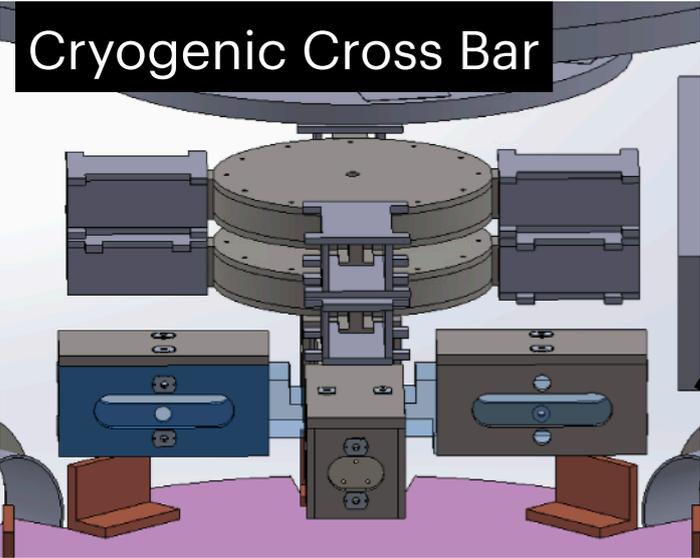


Brownian Motion

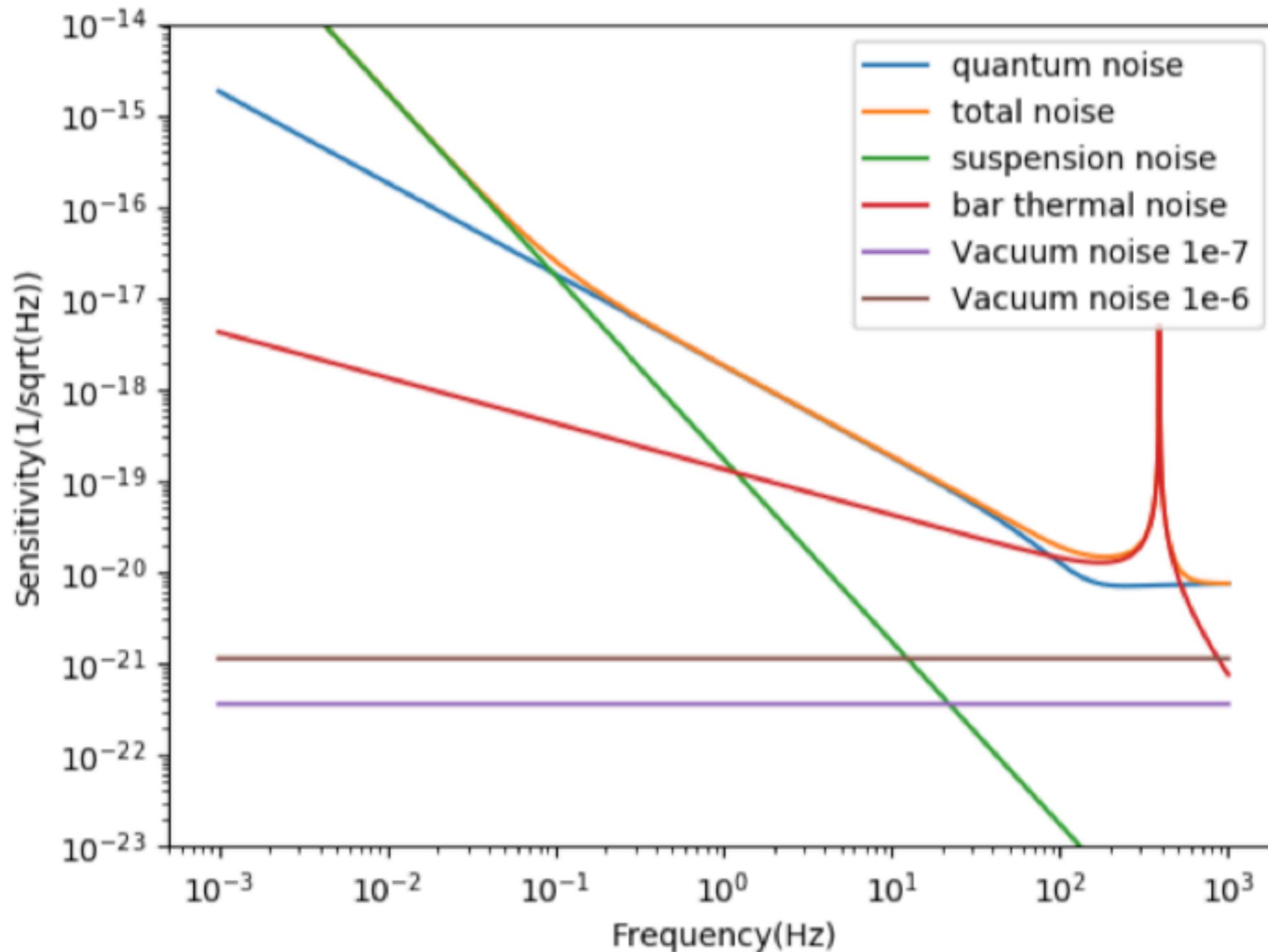


To attenuate the brownian motion, we cool down the suspension system

Overview of CHRONOS Cryogenic suspension system



Sensitivity





Progress of ASGRAF construction

Research team of CHRONOS

PI: Yuki Inoue Co-PI: Henry Wong

MAIN INTERFEROMETER

Leader: Daiki

Optics **Jeff**, Niko, Ko-Han

VIS **Daiki**, You-Ru, Hsiang-Chieh

Onsite Analysis **Hsiang-Yu**, Afif, Arif

ASGRAF

Leader: Yuki

Cryogenic **Hsiang-Chieh**,
Yung Ying

Coating **Chao Shiu**, Debby

Infrastructure **Feng-Kai**,
Cheng-I



THEORY

Leader: Henry

Sensitivity

Code A: **Jeff**, Hsiang-Chieh, Daiki

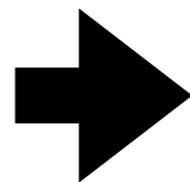
Code B: **Afif**, Arif, Chrisna, Hsiang-Yu

Exotic science Chrisna, Arif, Afif,
Martin

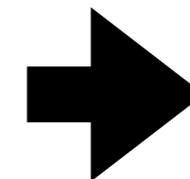
Earth quake Afif

Astronomy &
Cosmology Guo-Chin,
Hsiang-Yu

→ Demonstration of locking and onsite analysis tool for the observation

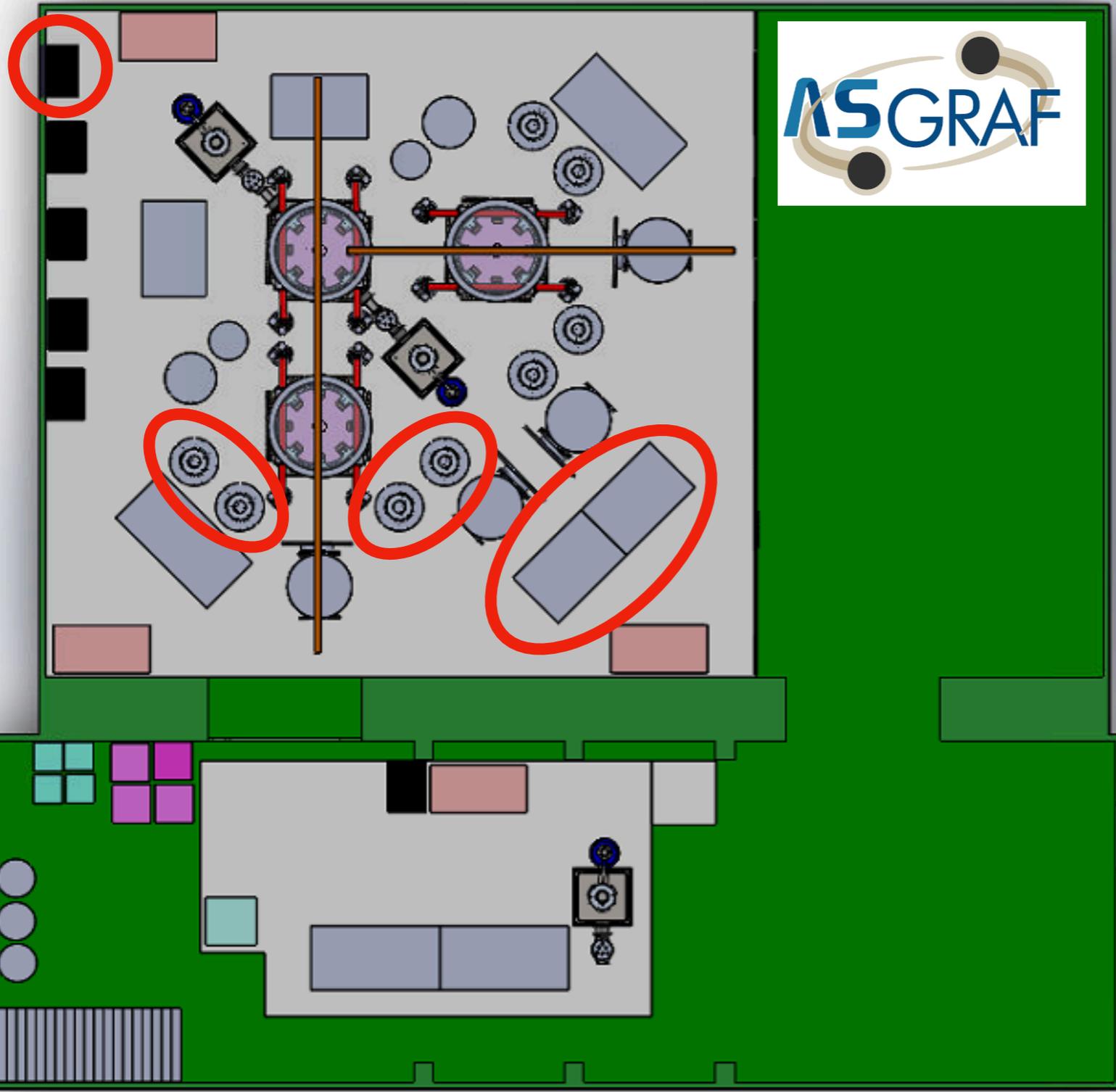


Preparation of Lab environment to accept main interferometer in 2023 June



Listing up the possible science of CHRONOS based on the expected sensitivity

Test in National Central University



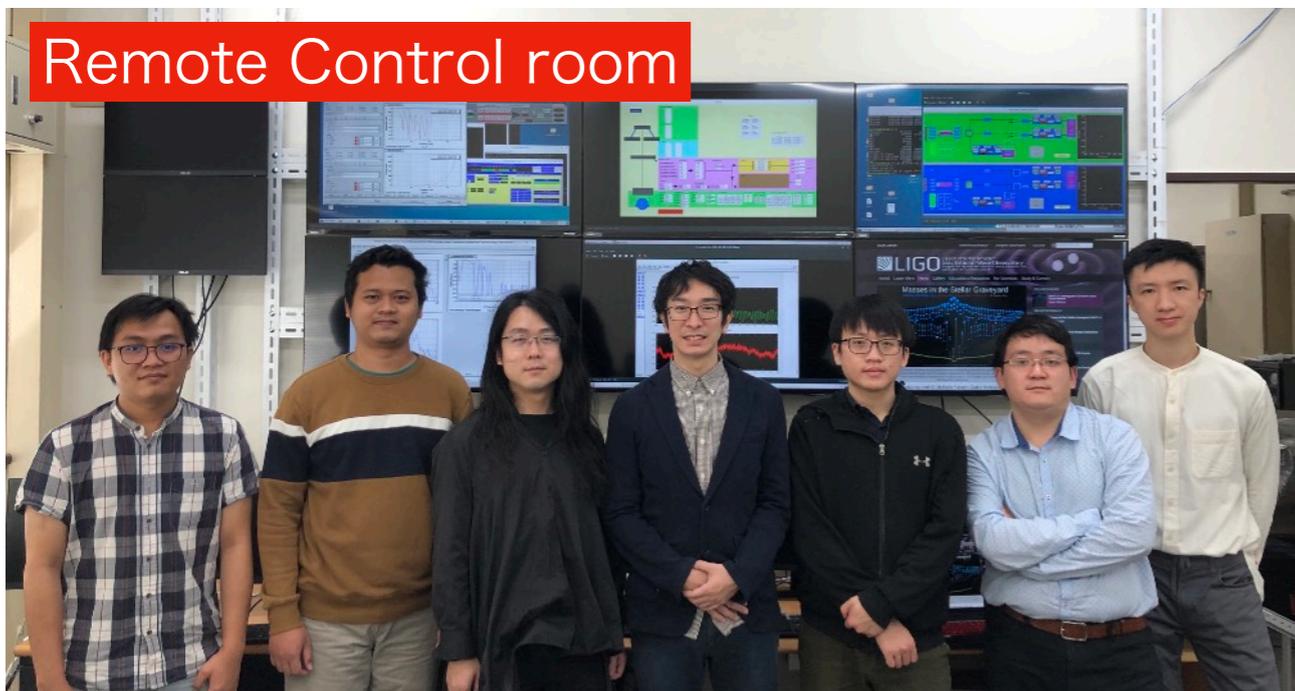
- R&D of interferometer control
- Establishment of procedure for digital feedback control and onsite analysis
- R&D for input optical system to provide high quality laser
- Training for staff and student for ASGRAF phase

NCU observatory (Physics department)

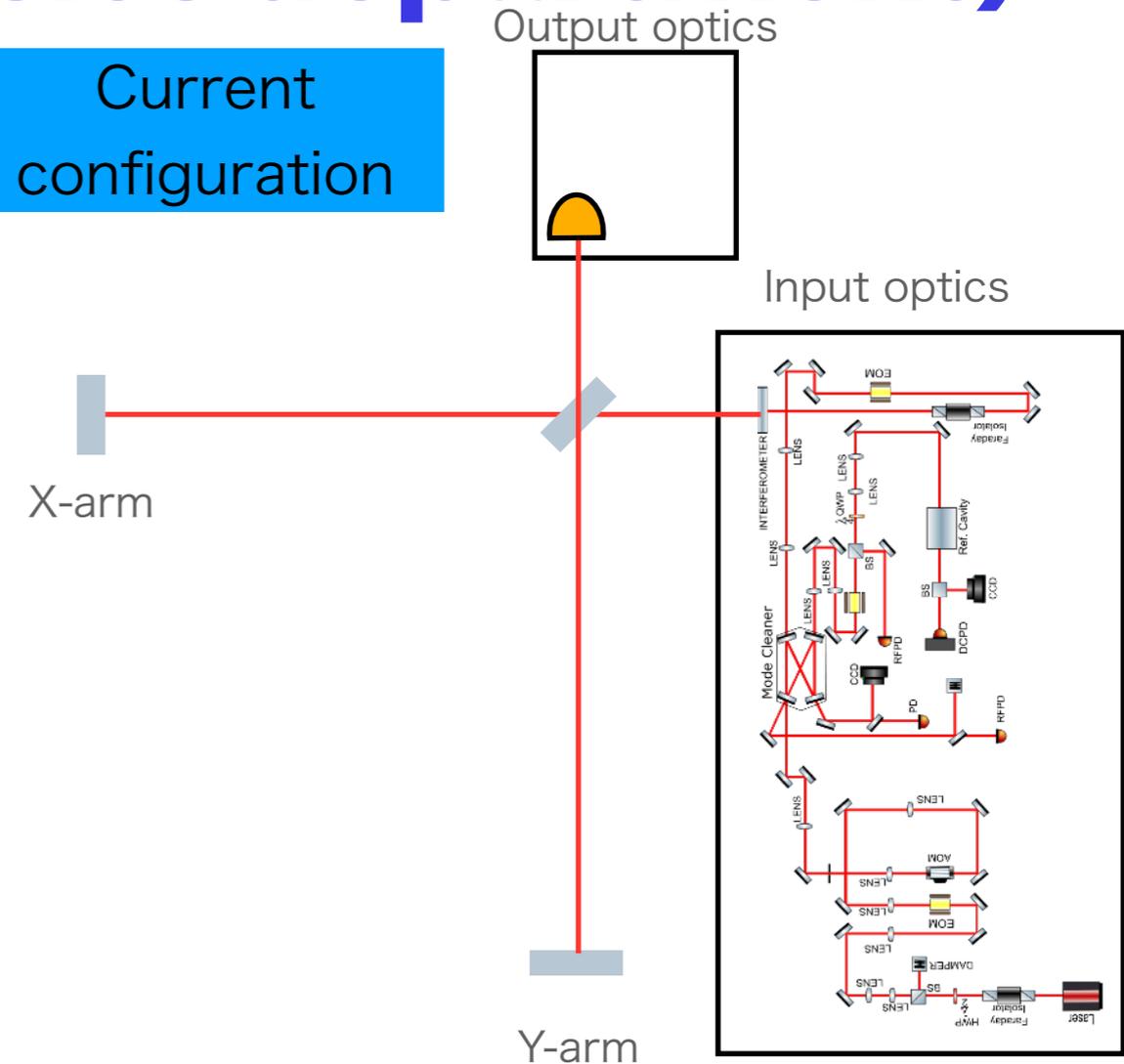
Interferometer



Remote Control room



Current configuration

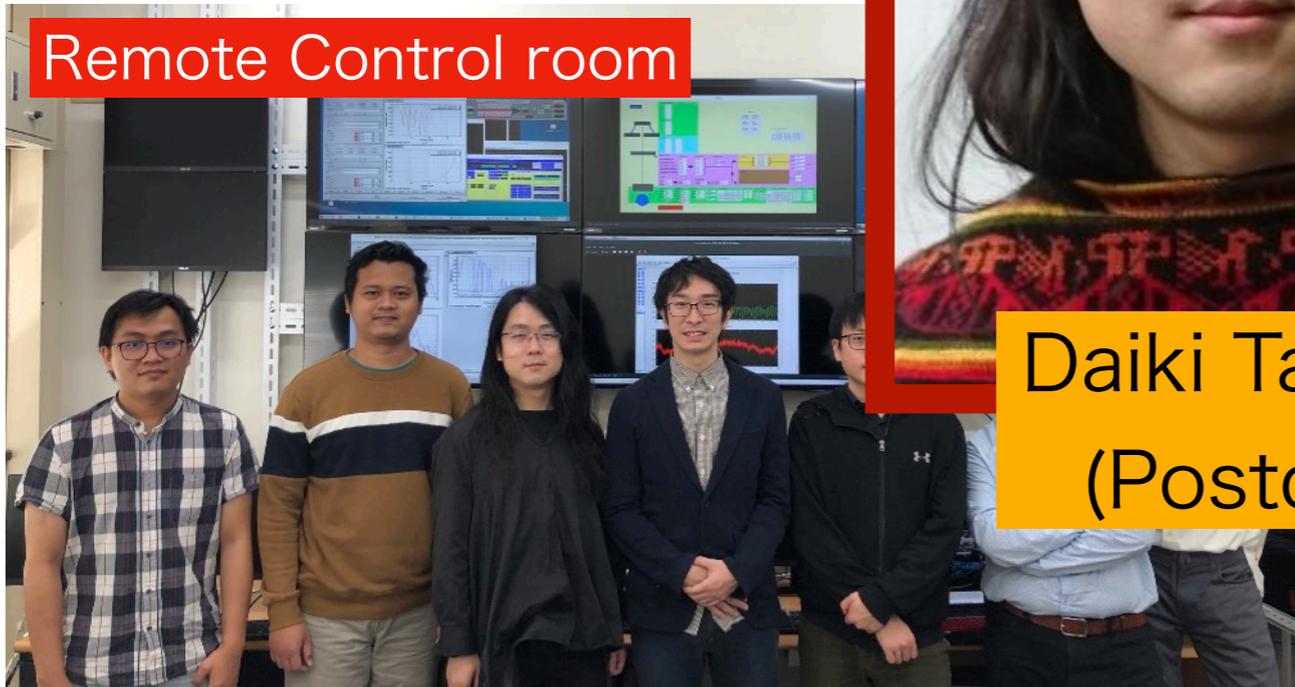


We develop the Michelson interferometer system for the test of the digital feedback control. We will test the Sagnac interferometer for the test of speed meter after Michelson test. Even if it is COVID-19, we can learn LIGO's interferometer system in Taiwan.

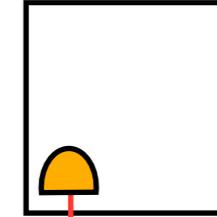
NCU observatory (Physics department)



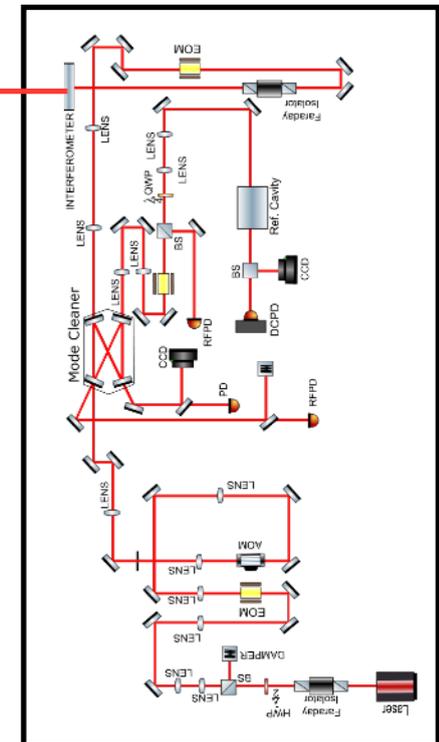
Current configuration



Output optics



Input optics



Y-arm

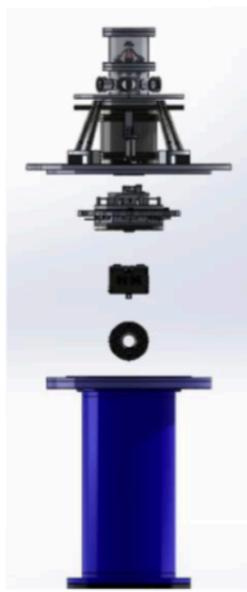
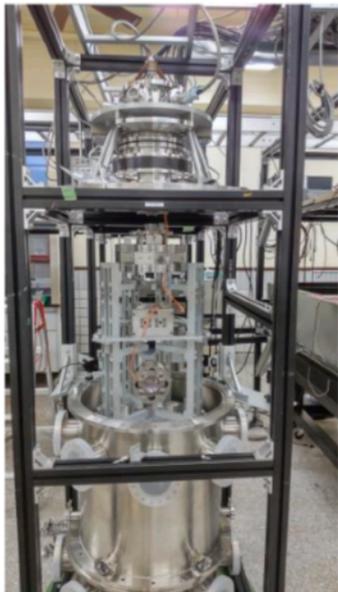
Daiki Tanabe
(Postdoc)

to support the Michelson interferometer system for the test of the digital feedback control. We will also test the Sagnac interferometer for the test of speed meter after Michelson test. Even if it is COVID-19, we can learn LIGO's interferometer system in Taiwan.

Studies of main interferometer

VIS (suspension)

- ✓ Two suspension
- ✓ Passive damping
- Active control
- Vacuum chamber



Optics

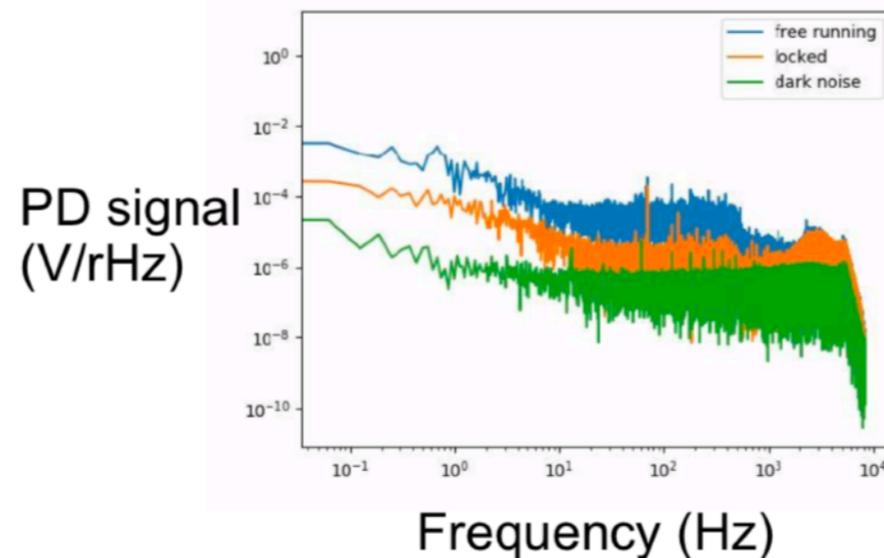
- ✓ Mode cleaner
- ✓ Intensity stabilization
- Frequency stabilization

DGS (digital system)

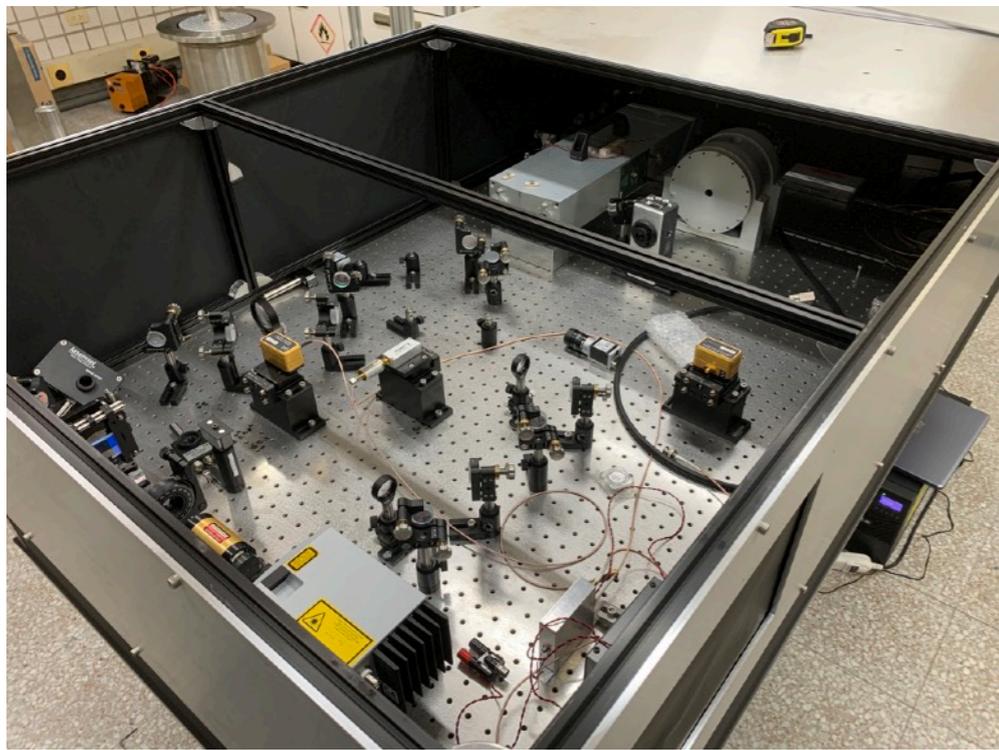
- ✓ Monitors
- ✓ Digital feedback
- ✓ Data storage
- Control GUI



Noise improvement by
intensity stabilization



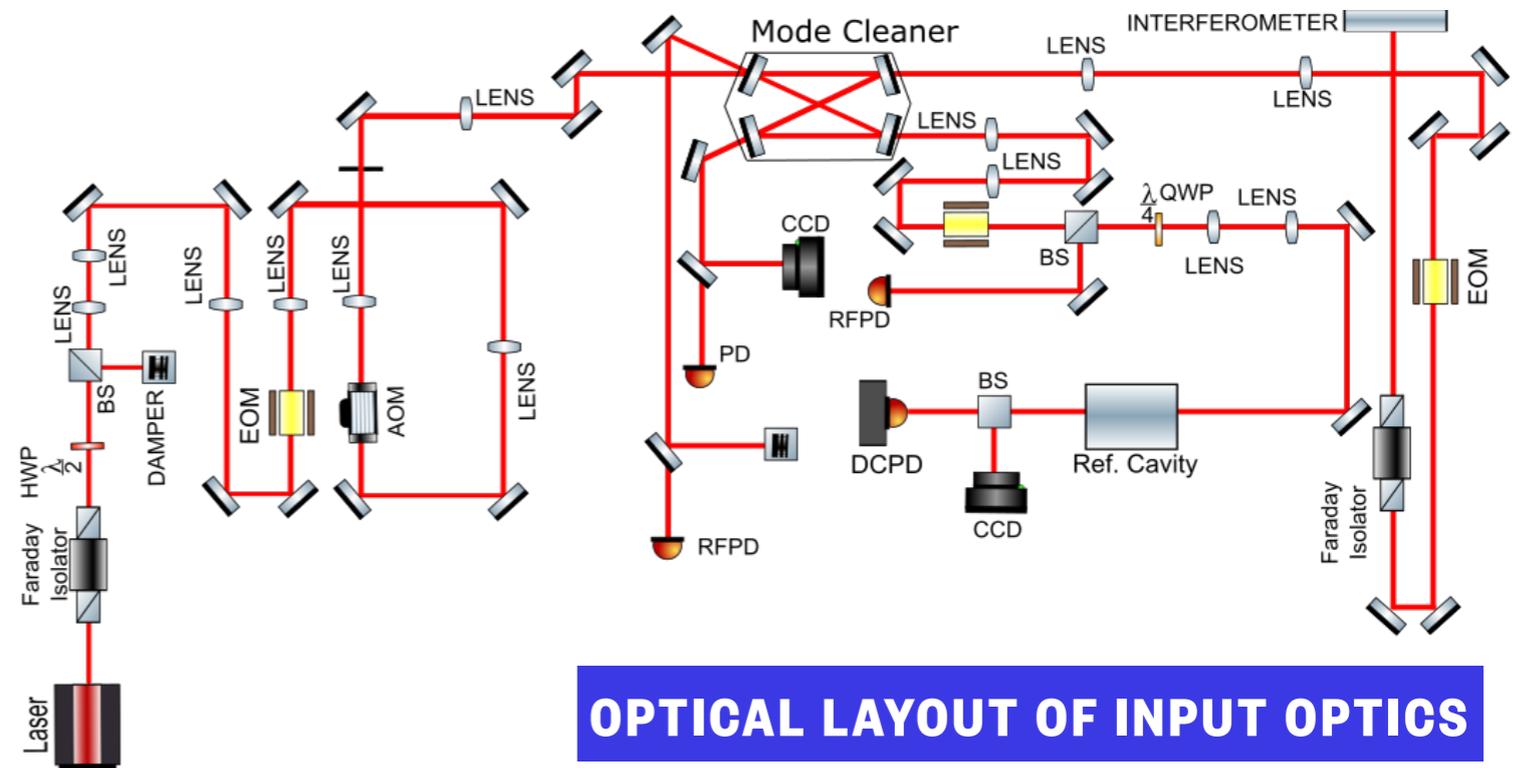
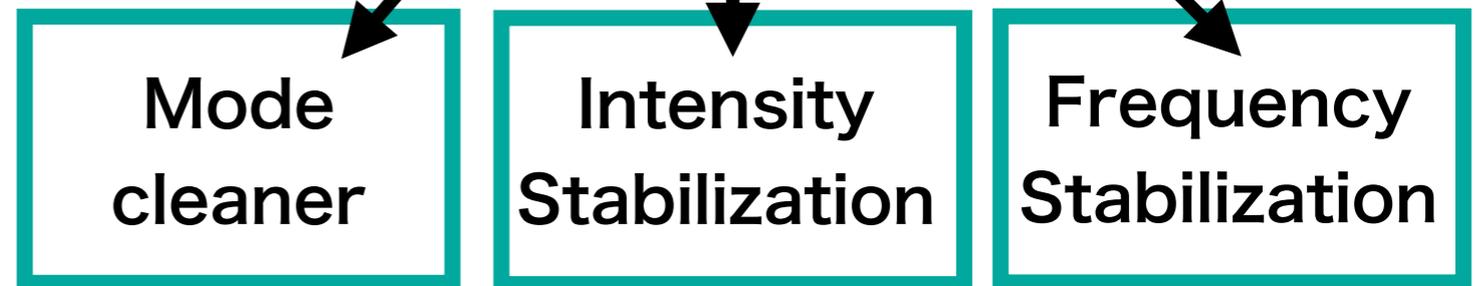
Input optical system



- To keep the lock acquisition state constantly, we need to provide high quality laser beam
- By using feedback control system, we stabilize the laser beam.

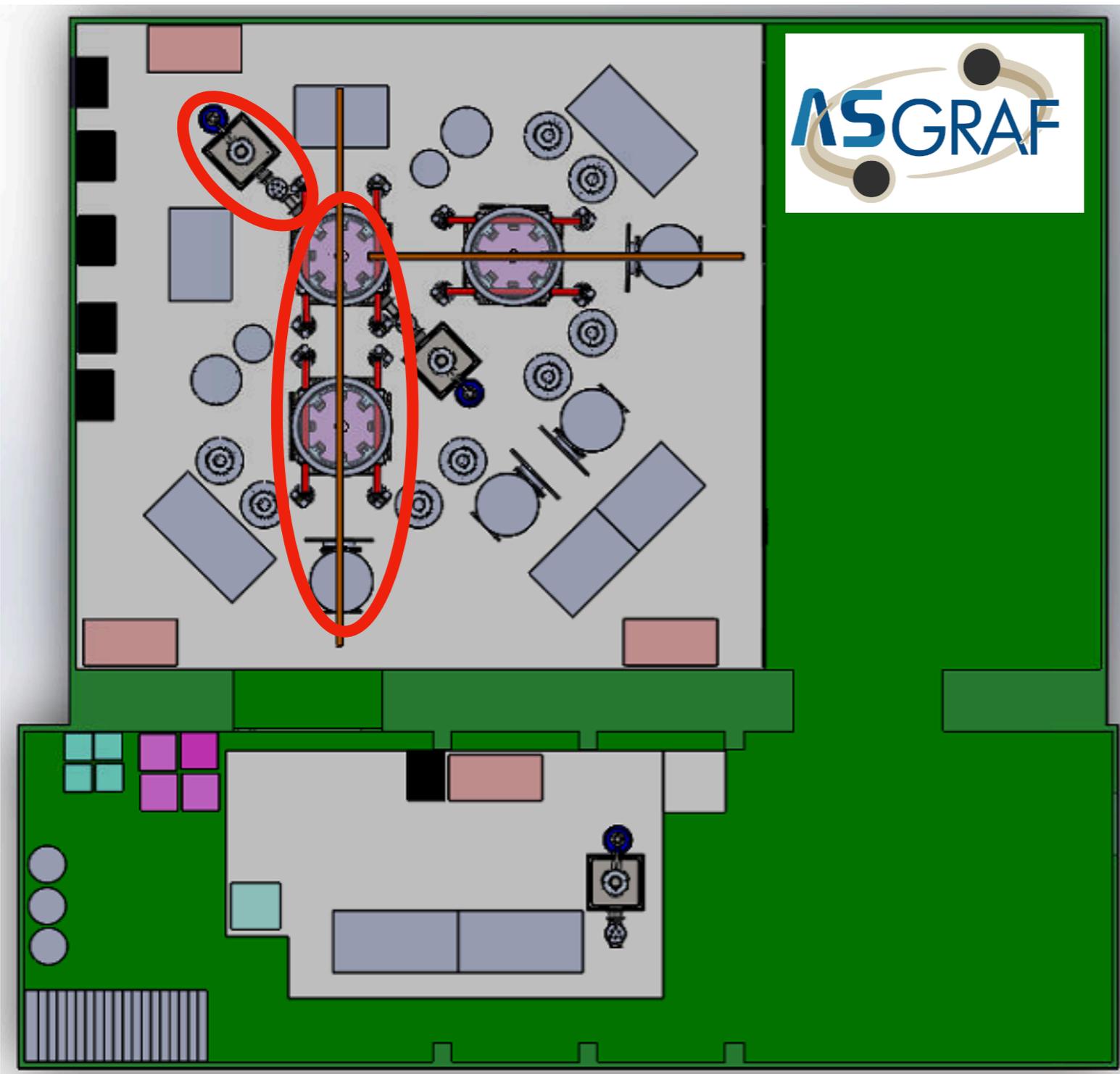
$$E(x,y) = A \exp(i\omega t)$$

Beam Intensity Phase



OPTICAL LAYOUT OF INPUT OPTICS

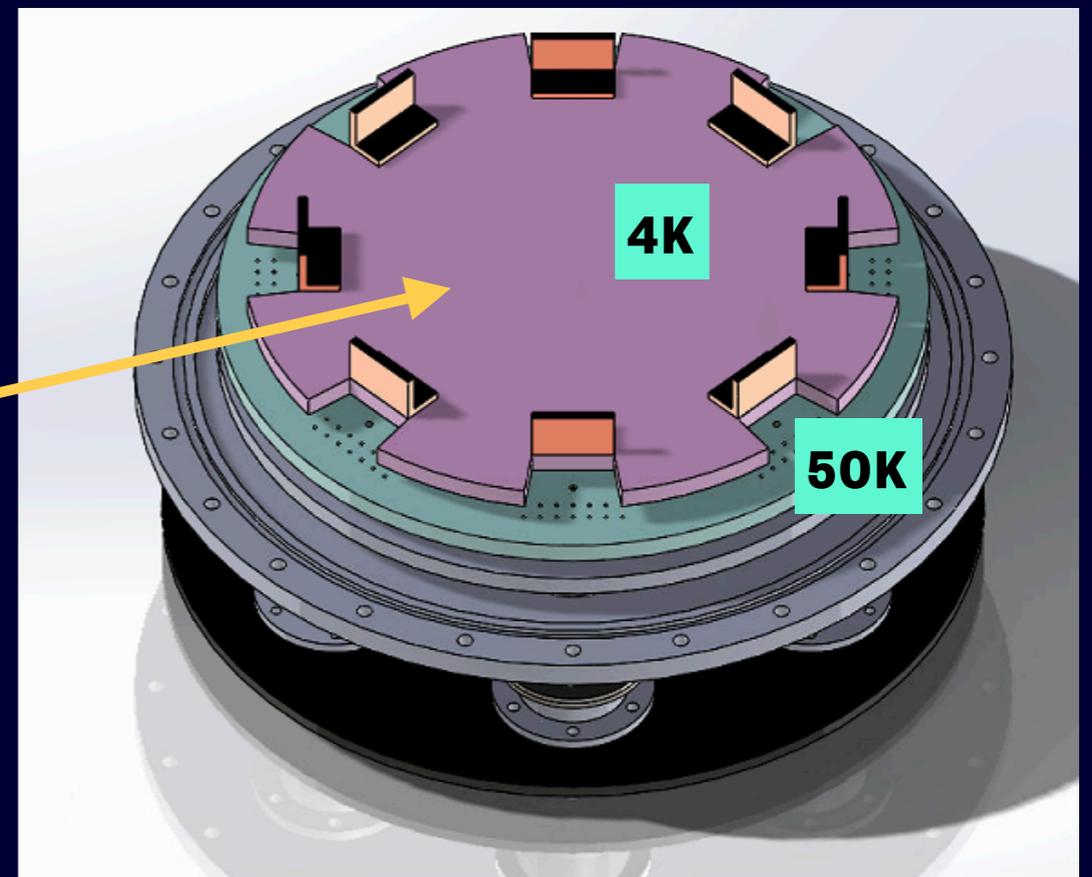
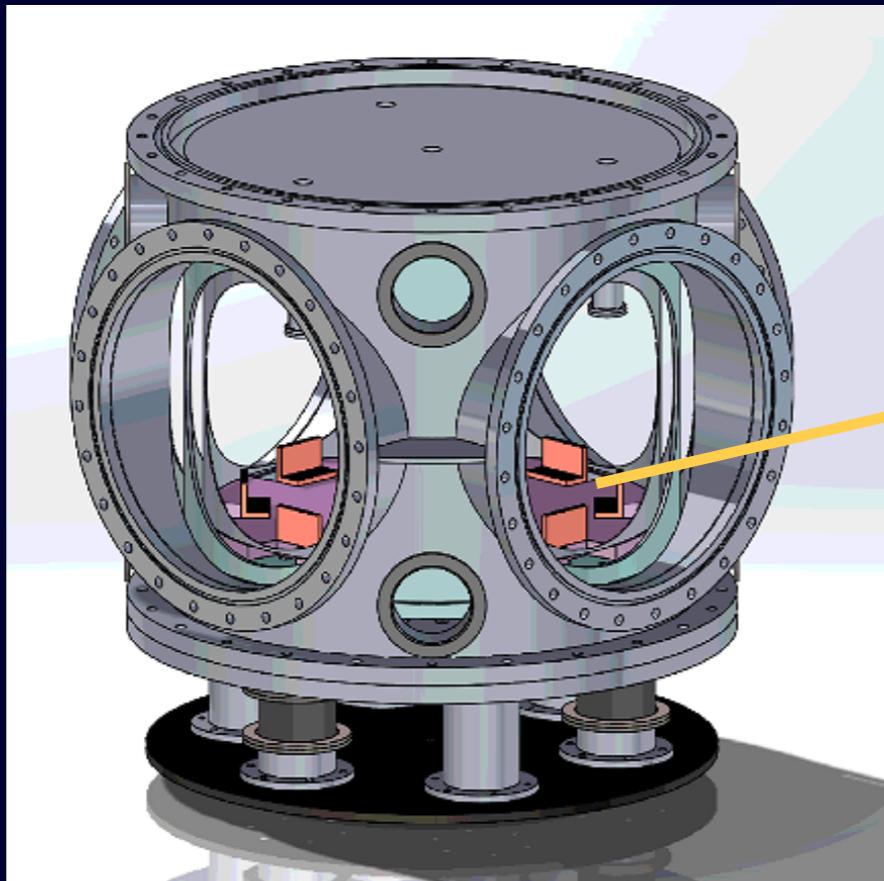
Test in Academia Sinica



- Preparation of infrastructure to accept NCU interferometer at early 2023
- Development of cryogenic measurement environment with large chamber

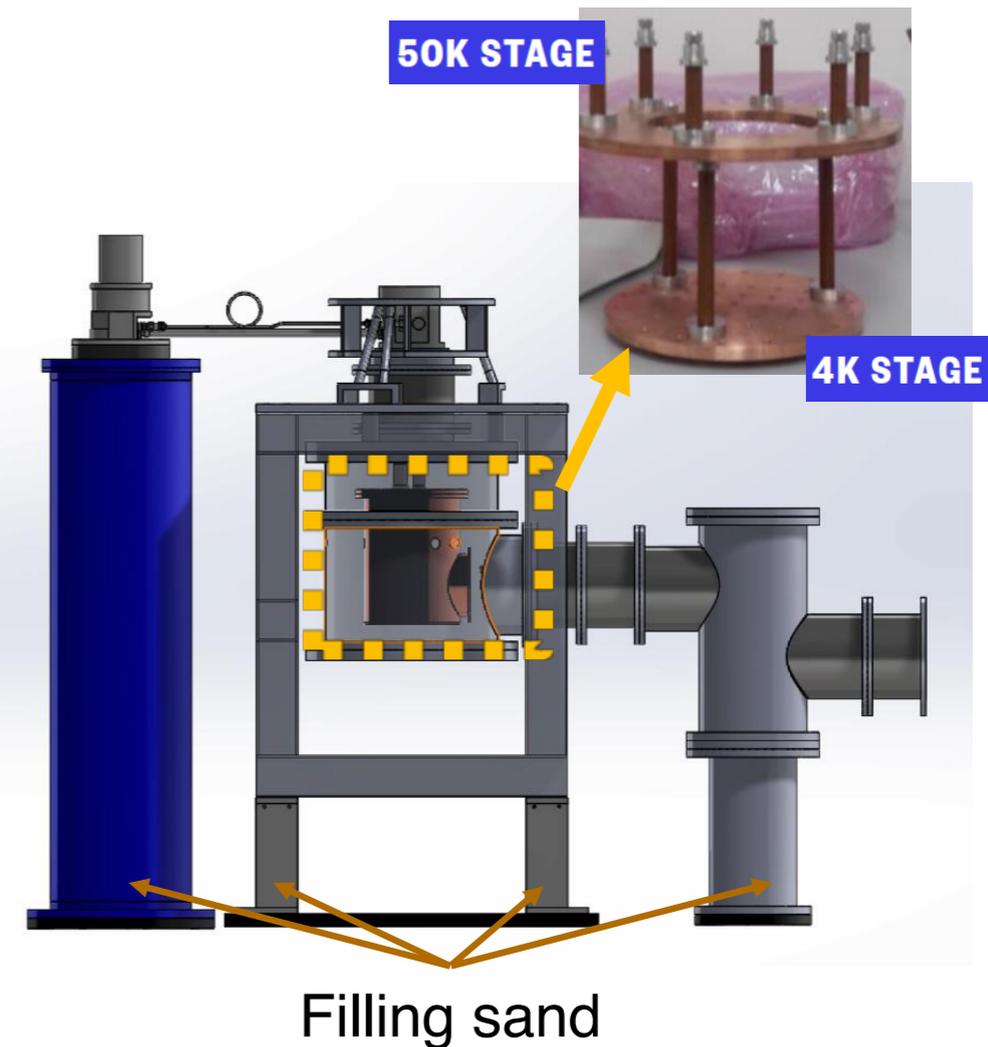
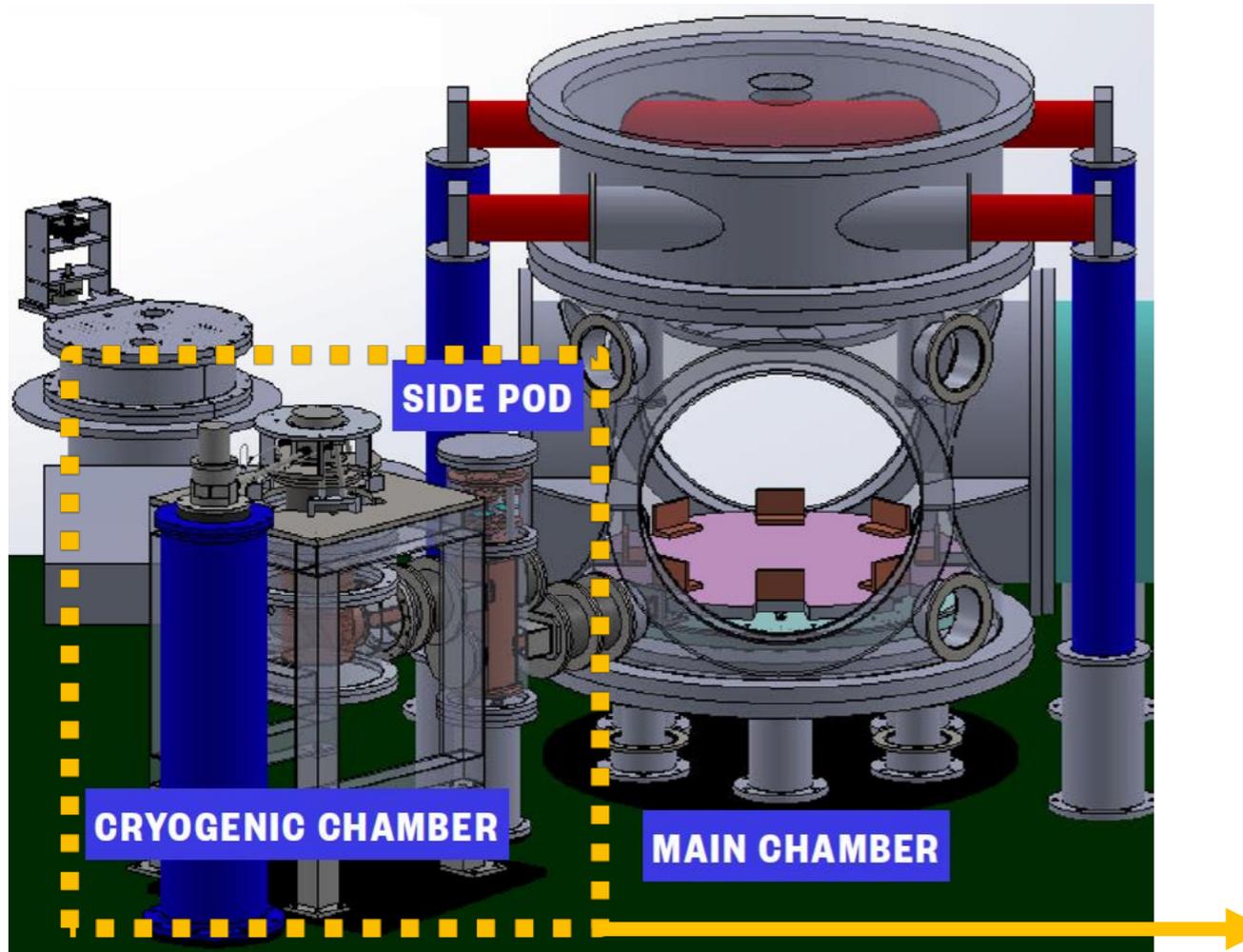
Temperature of large chamber

We need to achieve the 4K temperature at main stages. We need to reduce the thermal loading and establish the heatlink technology with pure aluminum wire.



Overview of Cryogenic system

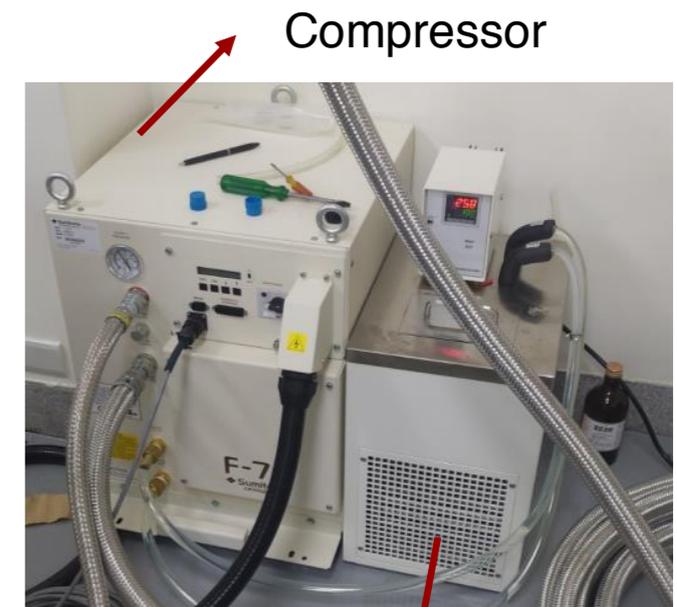
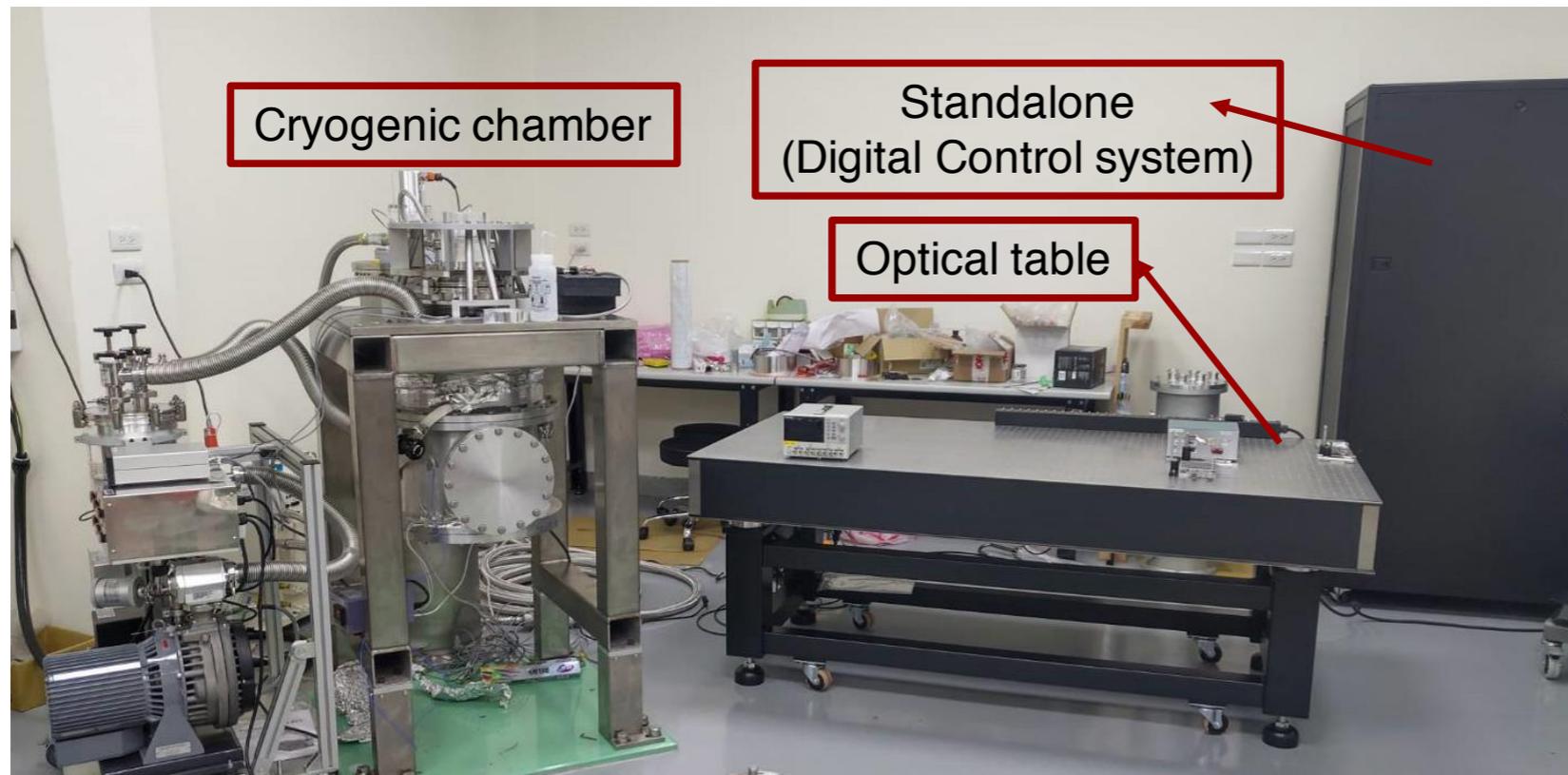
- Multiple Applications cryocooler system with Realtime feedbacked Low Environmental background (MARLE) consists of 3 chambers



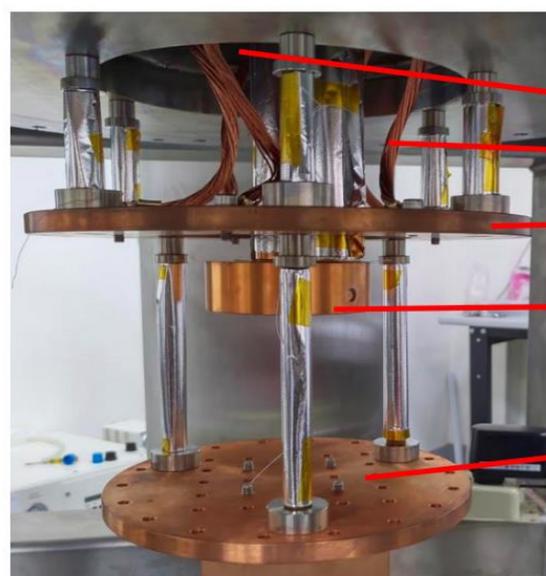
- Cryocooler : 2-**Stages** pulse tube cooler
- Stages temp. : 50 K, 4 K
- CHRONOS requirement : 4K

Setup of cryogenic system

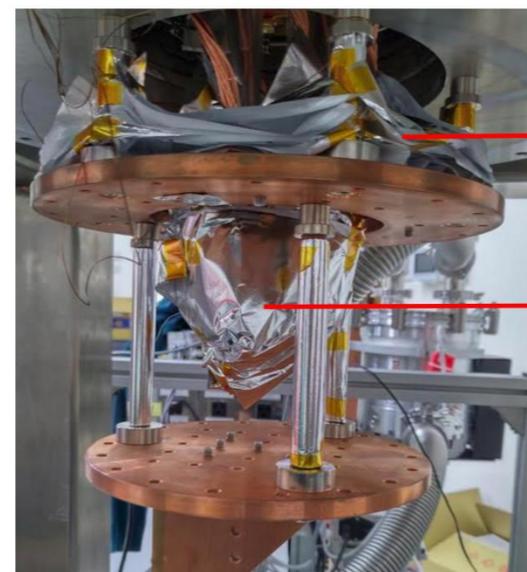
- Optical table and standalone server are prepared



Chiller(to be upgraded to be more powerful)



50K cooling head
heat links (50K)
Stage of 50K for testing
4K cooling head
Stage of 50K for testing (in Run002, we do not install the heat links for 4K)



50 layers MLI cover the 50K stage
MLI cover the 4K cooling head



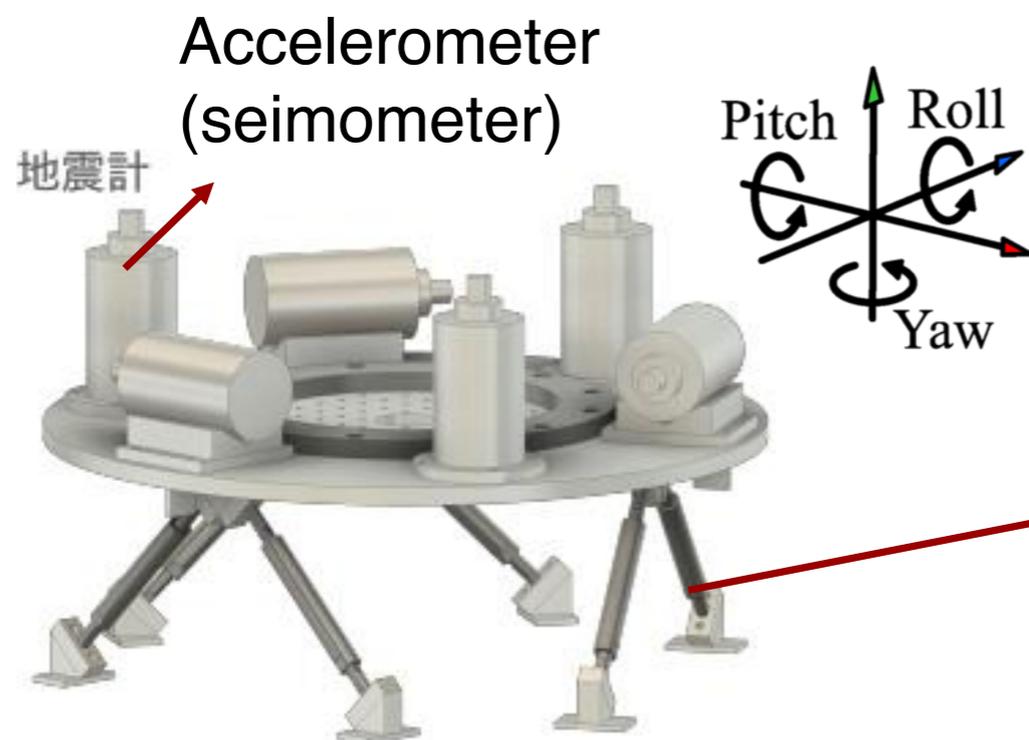
Feedback control system

■ Feedback control :

- Vibration **noise** almost large enough **to swamp** the **signal** we are looking for
- Do more than barely make the instrument work : use feedback to control the relevant angles and positions

■ 6 degree of freedom?

- Translational vibration couples to the rotational motion

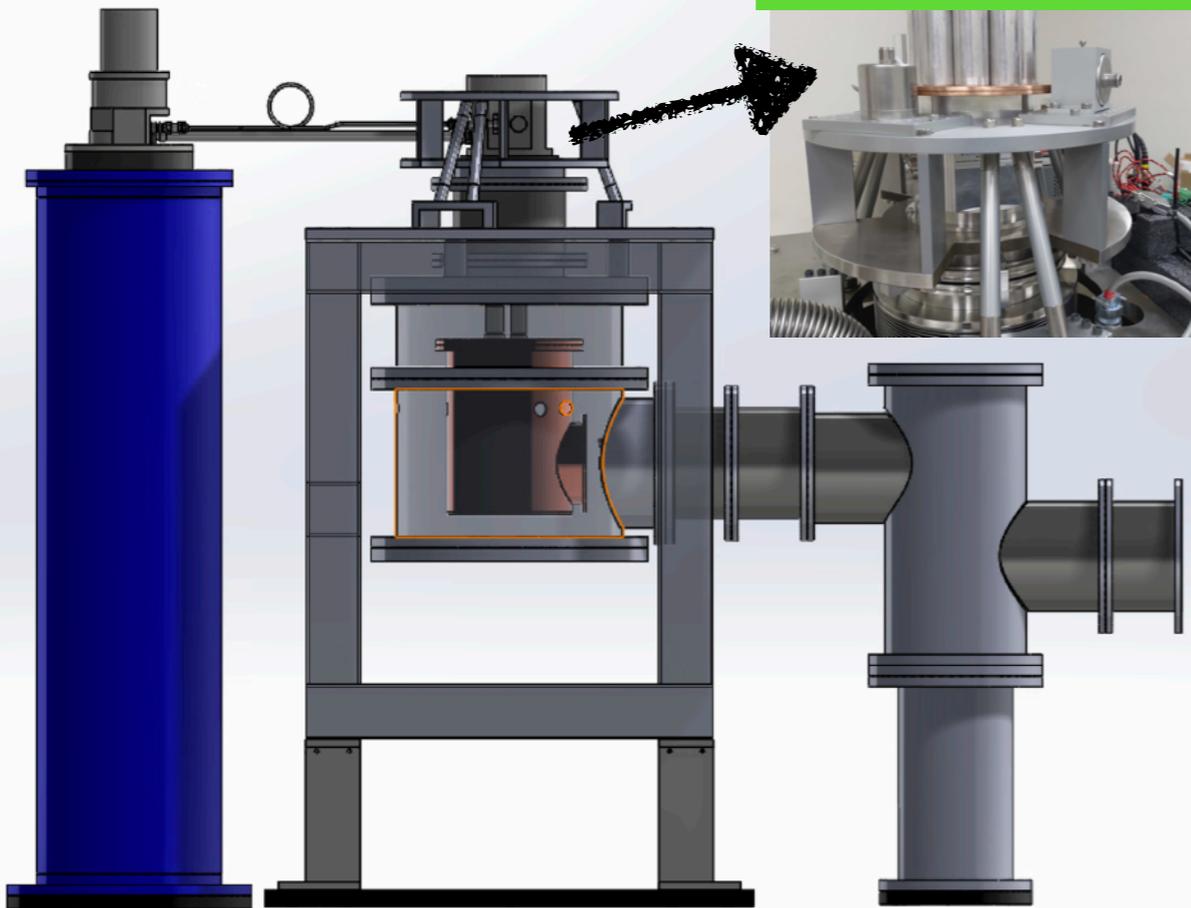


Piezo Flexure Actuator
P-844 Preloaded Piezo Actuators

Development of loss measurement system

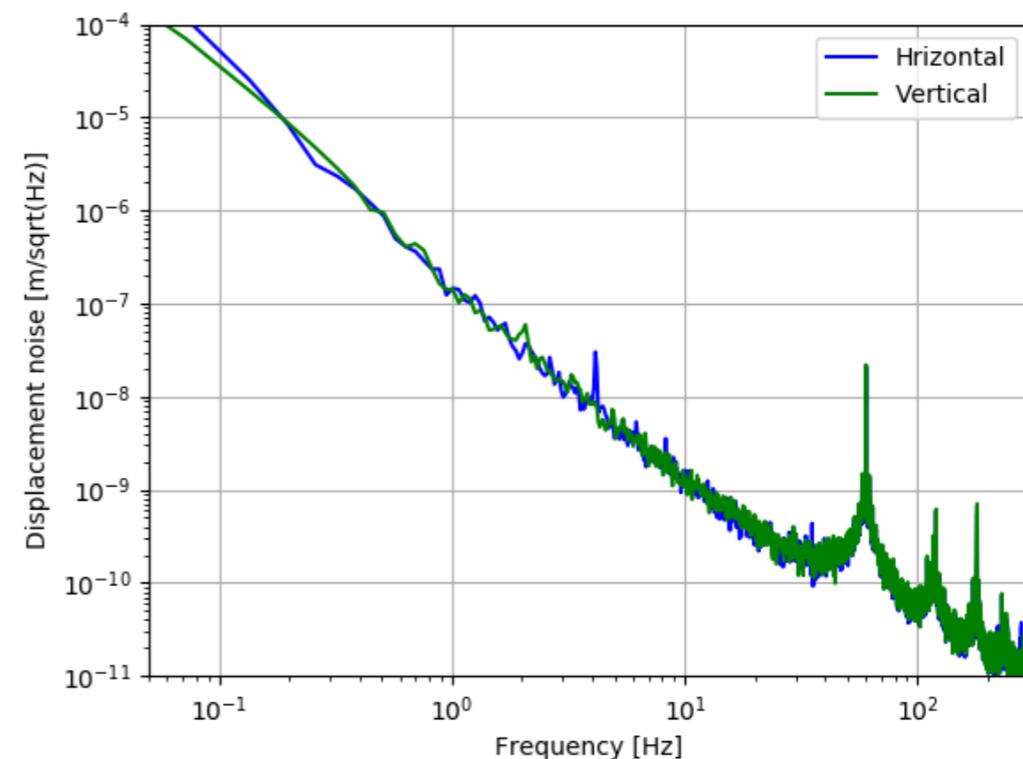
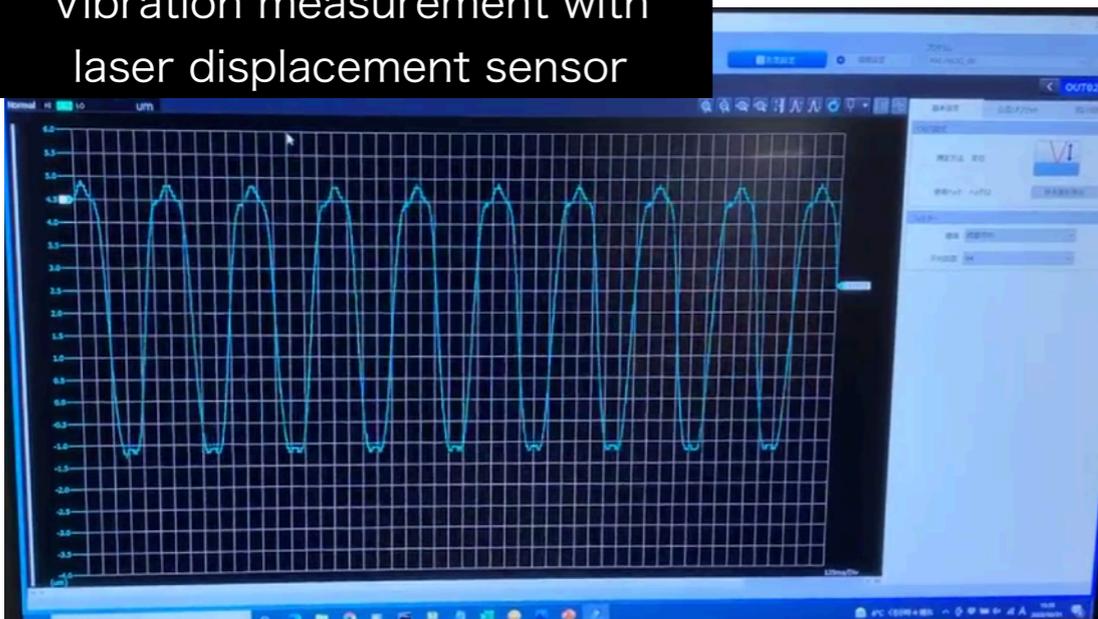
- Characterization of Vibration-

Accelerometer



- We measured the vibration from PTC
- To mitigate the periodic vibration from PTC (~10um), we are developing active damping vibration isolation system
- To make error signal for feedback, we start to install the accelerometer and photo sensors.
- We plan to finish the initial test within 1.5 month
- From May, we will start the optical test for loss characterization system with mv students

Vibration measurement with laser displacement sensor



3. Listing up the science and sensitivity



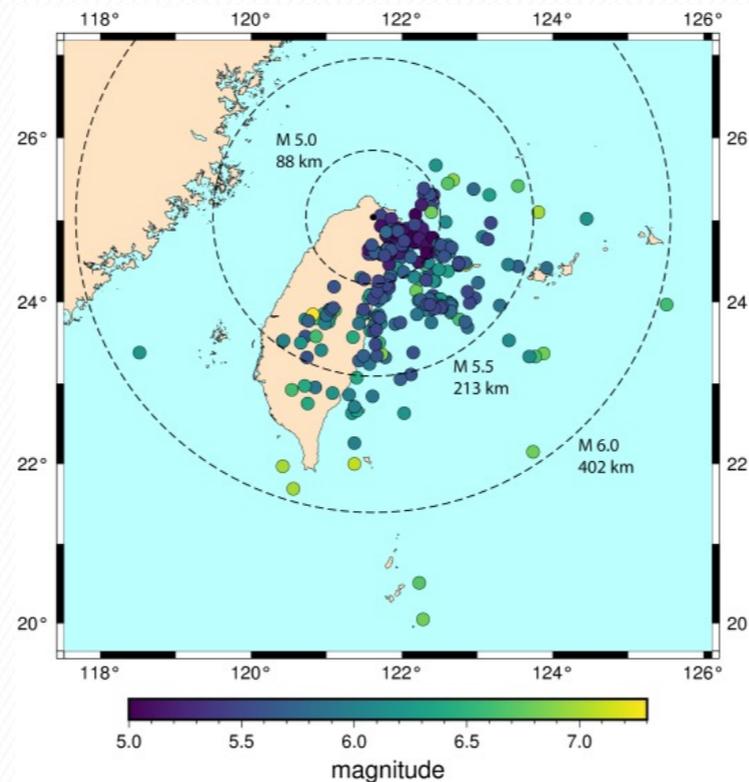
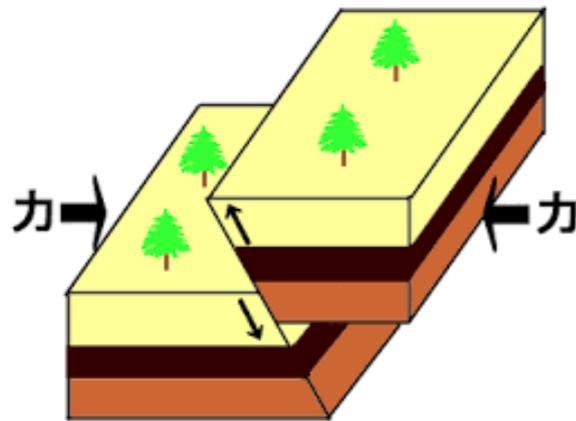
By collaborating with theorist, we need to list up all science possibility with sensitivity curves. We will discuss it in Theory session.

Earthquake measurement in Taiwan

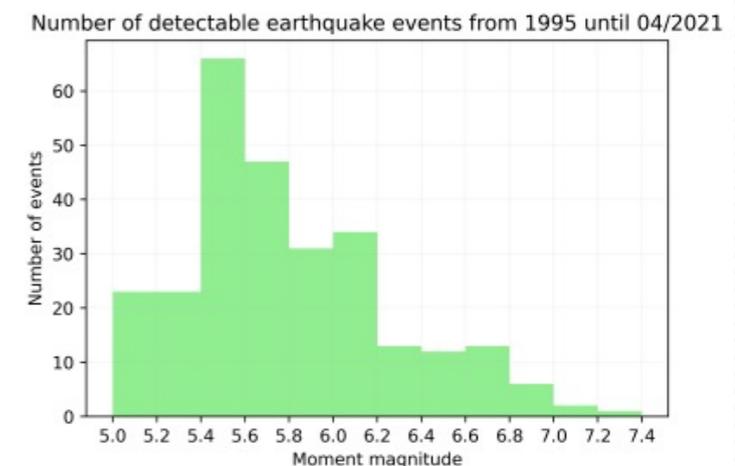
- Dynamical of mass inside the earth surface can generate a perturbation to gravitational potential on the surface of the earth
- It can be observed by strainmeter through **gravity strain**

$$\mathbf{h}(\mathbf{r}, t) = \int_0^t d\tau' \int_0^{\tau'} d\tau \nabla \otimes \delta\mathbf{g}[\mathbf{r}, \tau].$$

- Harms (2016) provided a numerical calculation method to **compute the gravity strain signal** by solving the equation with double-couple source (symmetric **moment tensor**) in homogeneous half-space (the signal is sourced from the underground).

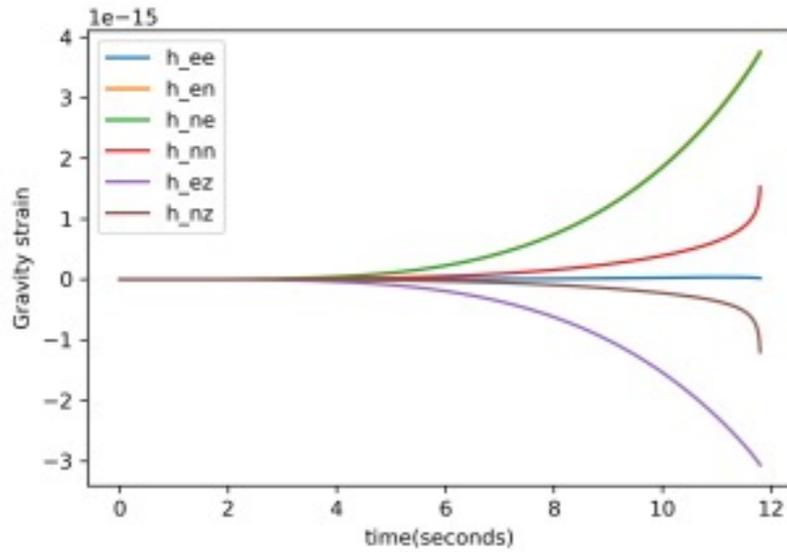


We can cover all Taiwan region for detecting earthquake around M 6.0

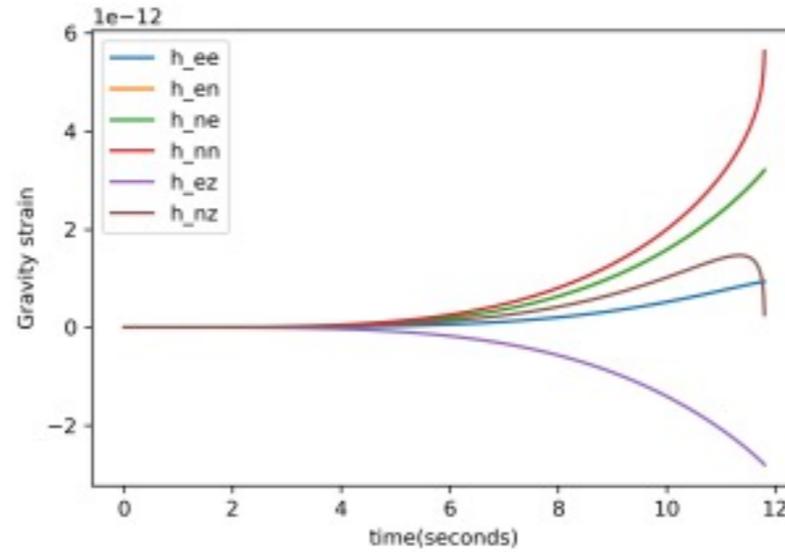


Simulation and Sensitivity

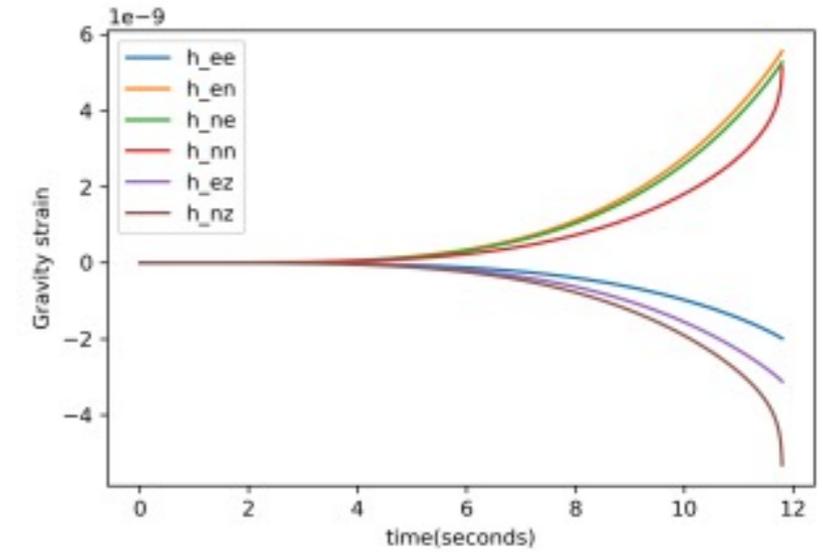
SIMULATED GRAVITY STRAIN FROM MOMENT TENSOR DATA IN TAIWAN



(a) M 5.0

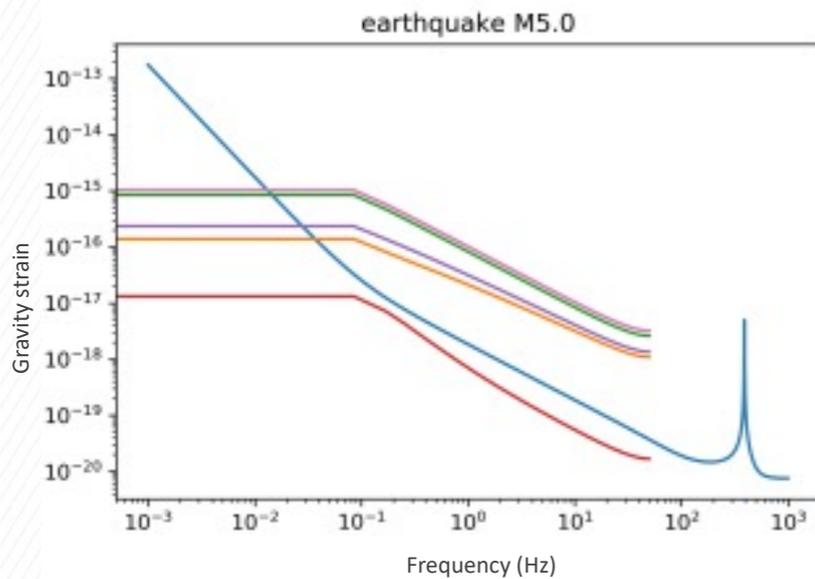


(b) M 7.1

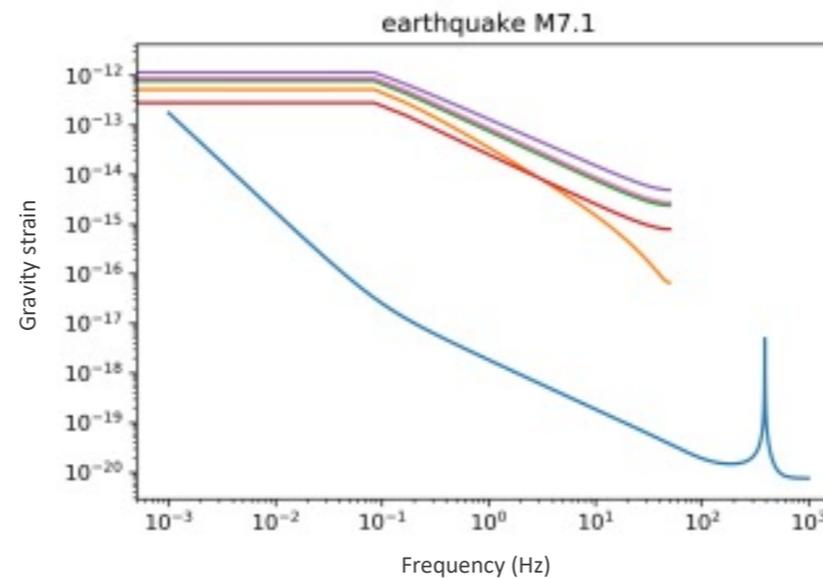


(c) M 9.1

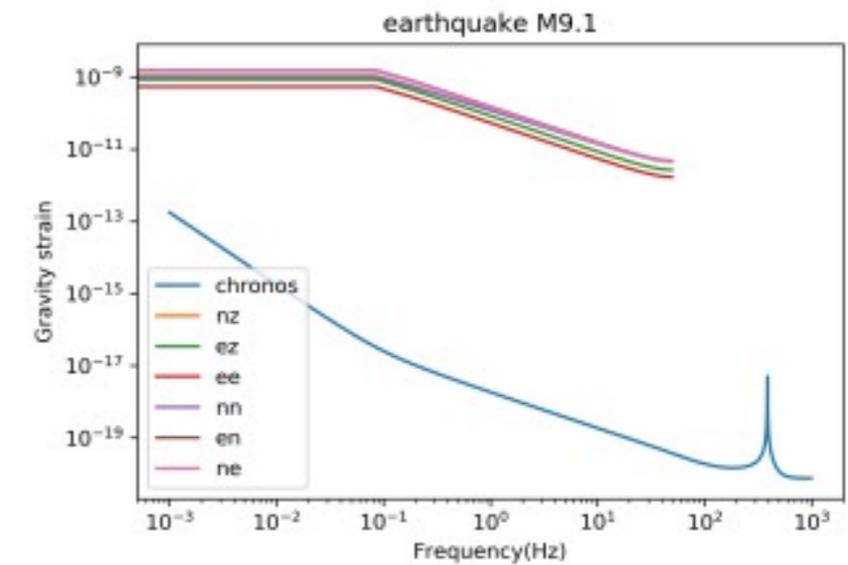
SENSITIVITY OF CHRONOS AND TYPICAL SIGNAL



(a) M 5.0



(b) M 7.1



(c) M 9.1

Collaboration is very welcome!!

- Development of ASGRAF (Software / Hardware)
 - Vacuum, Electronics, Machining, and Cryogenic
- Application of active damping cryogenic system for other experiment (CMB, Dark matter, ..)
- Astronomical research for Intermediate black hole generation process
- Study for Stochastic back ground
- GEO science and analysis with ASGRAF data

Summary

- Gravitational wave was detected by LIGO. Nowadays, we can observe gravitational wave every ten days.
 - AS-NCU-NRHU group start the LIGO study from 2021. We focus on calibration and coating study.
 - Construction of ASGRAF is ongoing. We will test the new technology for future R&D. We would like to apply our facility as one of the test facility of LIGO in the future.
 - R&D of Taiwanese GW experiment, CHRONOS, is ongoing. We are testing key technology in NCU and Academia Sinica.
-