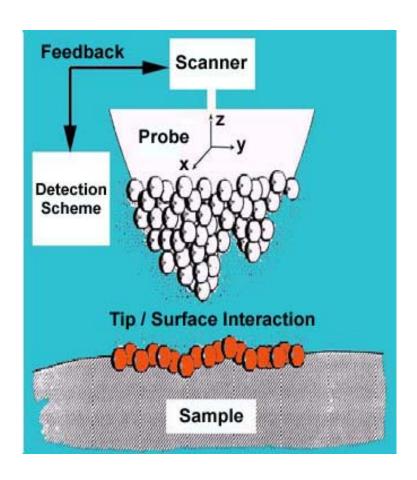
## Scanning Probe Microscopy (SPM)



#### **Scanning Tunneling Microscopy (STM)**

--- G. Binnig, H. Rohrer et al, (1982)

#### **Near-Field Scanning Optical Microscopy (NSOM)**

--- D. W. Pohl (1982)

#### **Atomic Force Microscopy (AFM)**

--- G. Binnig, C. F. Quate, C. Gerber (1986)

#### **Scanning Thermal Microscopy (SThM)**

--- C. C. Williams, H. Wickramasinghe (1986))

#### **Magnetic Force Microscopy (MFM)**

--- Y. Martin, H. K. Wickramasinghe (1987)

#### Friction Force Microscopy (FFM or LFM)

--- C. M. Mate et al (1987)

#### **Electrostatic Force Microscopy (EFM)**

--- Y. Martin, D. W. Abraham et al (1988)

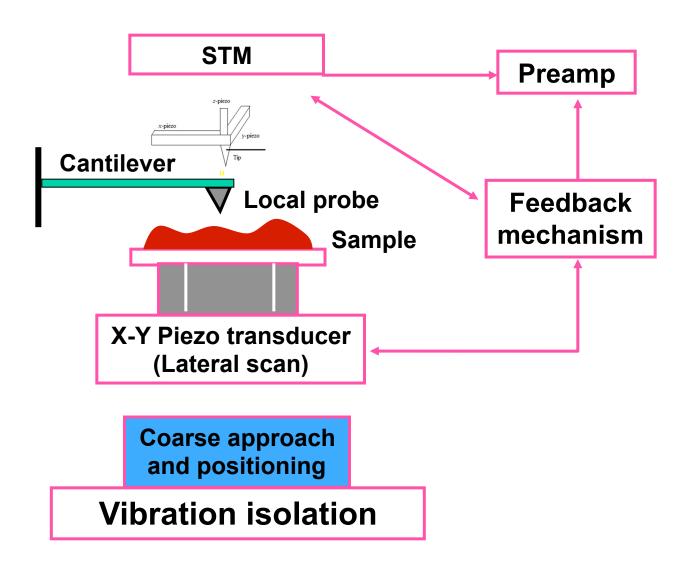
#### **Scanning Capacitance Microscopy (SCM)**

--- C. C. Williams, J. Slinkman et al (1989)

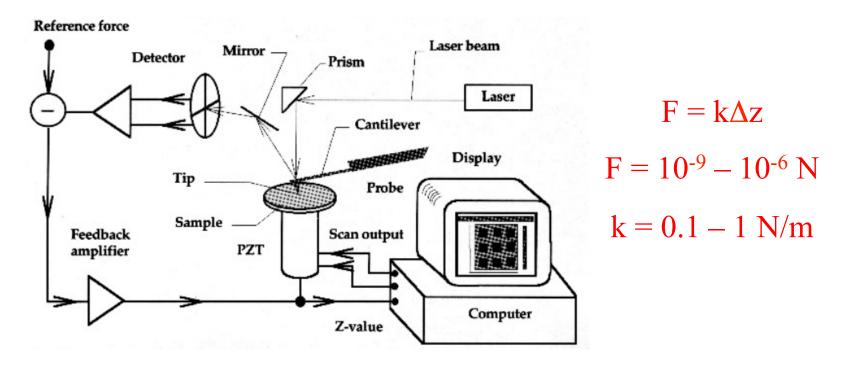
#### Force Modulation Microscopy (FMM)

--- P. Maivald et al (1991)

#### Original Structure of AFM



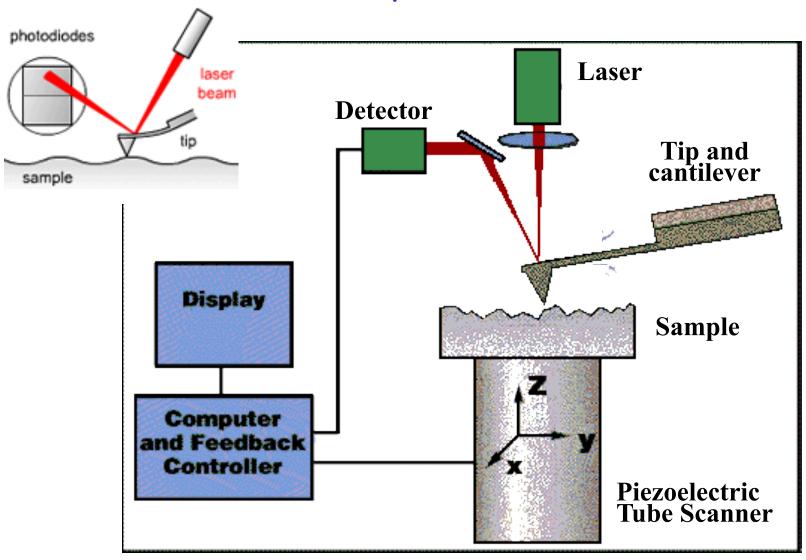
#### Atomic Force Microscopy (AFM)



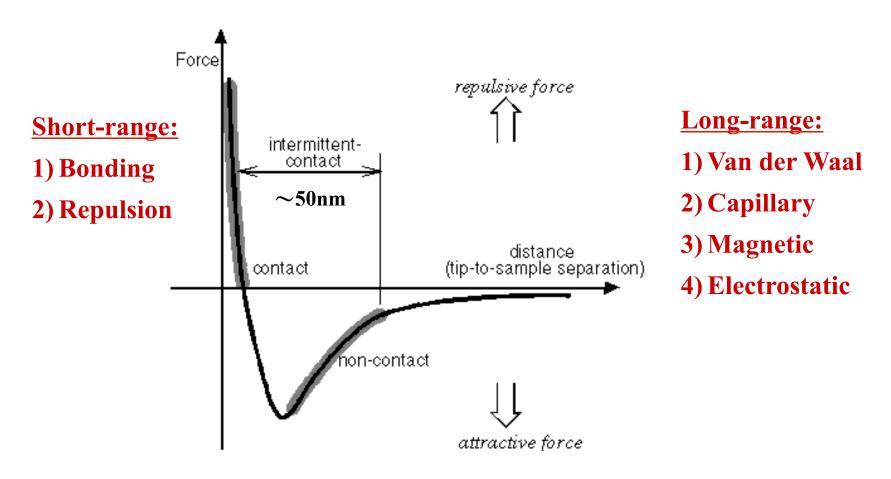
#### References:

- G. Binnig, C. F. Quate, and C. Gerber, Phys. Rev. Lett. 56, 930 (1986).
- C. Bustamante and D. Keller, Physics Today, 32, December (1995).
- R. Wiesendanger and H.J. Güntherodt, Scanning Tunneling Microscopy II, Springer-Verlag, (1992).

## Core components of AFM

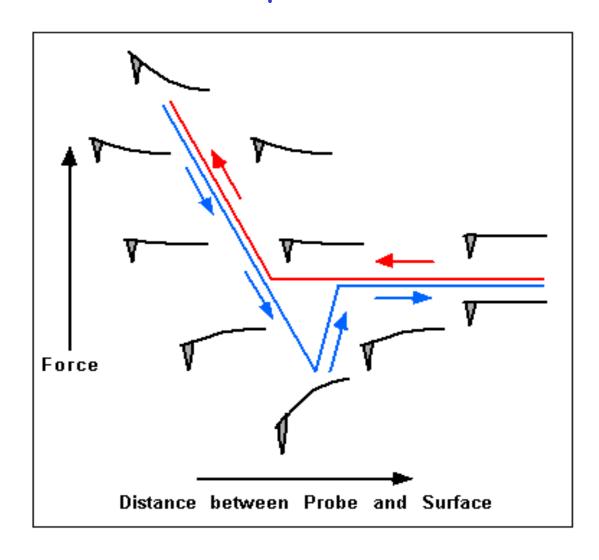


#### Interaction between the probe and sample

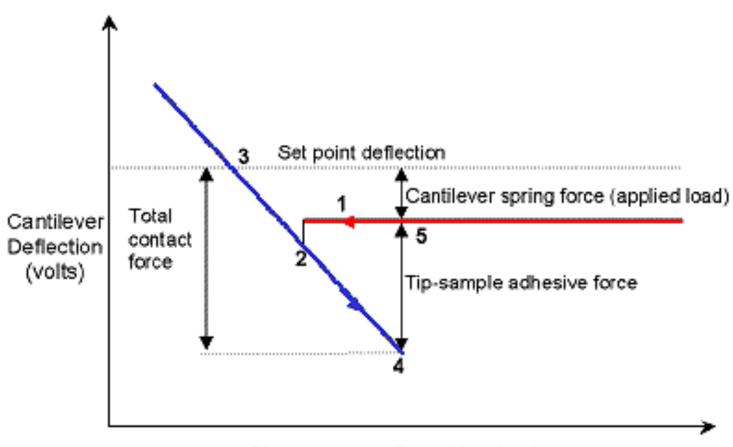


Lennard-Jones potential  $\phi(r) = -A/r^6 + B/r^{12}$ 

#### Reaction of the probe to the force

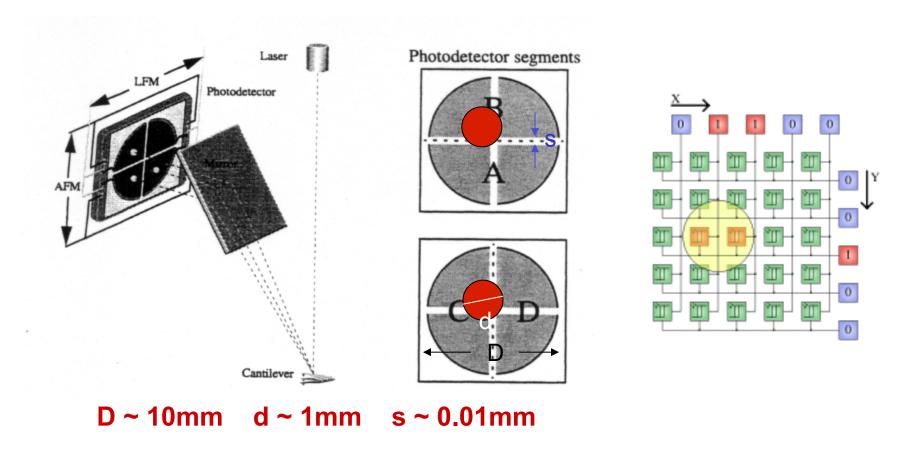


#### Deflection of Cantilever vs Piezo displacement

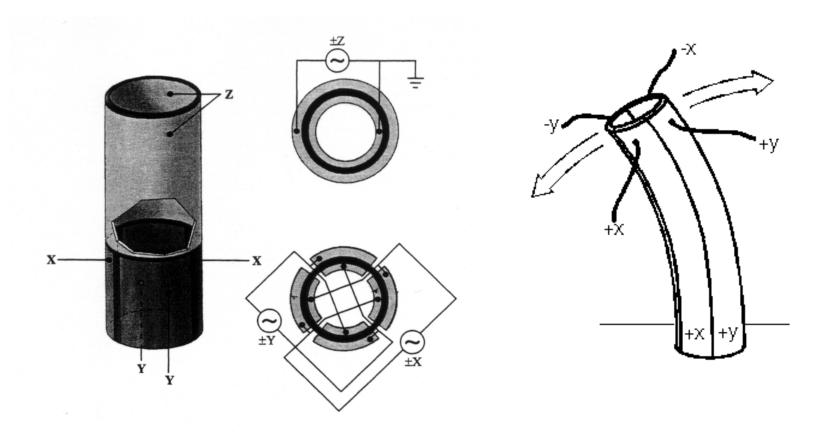


Piezo scanner Z-position (nm)

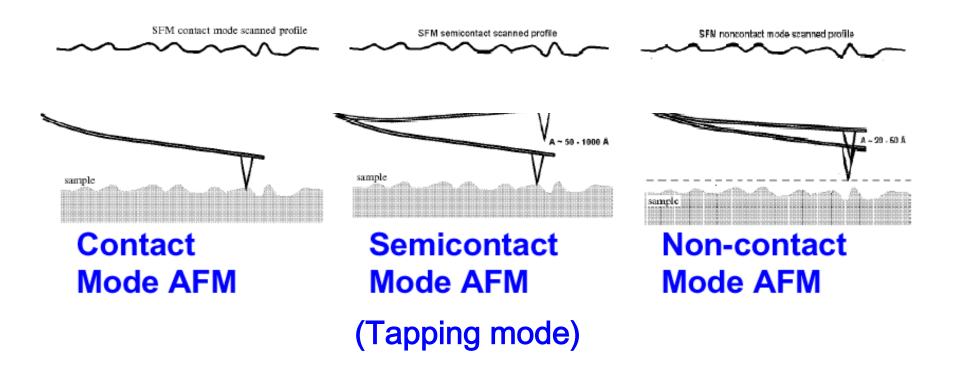
#### Position-sensitive Photo Diode (PSPD)



#### Piezo Scanner



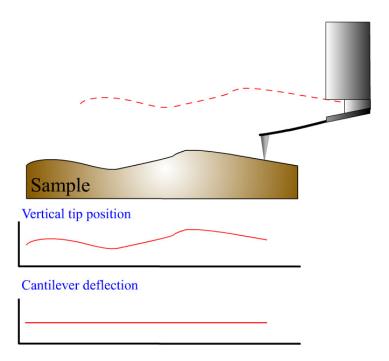
#### Three scanning modes of AFM



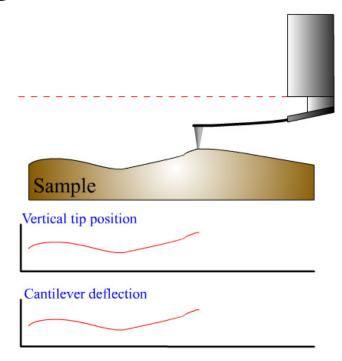
#### Two imaging methods in contact mode

- Constant force method: By using a feedback loop the tip is vertically adjusted in such a way that the force always stays constant. The tip then follows a contour of a constant contact force during scanning. A kind of a topographic image of the surface is generated by recording the vertical position of the tip.
- Constant height method: In this mode the vertical position of the tip is not changed, equivalent to a slow or disabled feedback. The displacement of the tip is measured directly by the laser beam deflection. One of its advantages is that it can be used at high scanning frequencies.

# Constant-force scan vs. constant-height scan



Constant-force mode



Constant-height mode

## Constant-force scan vs. constant-height scan

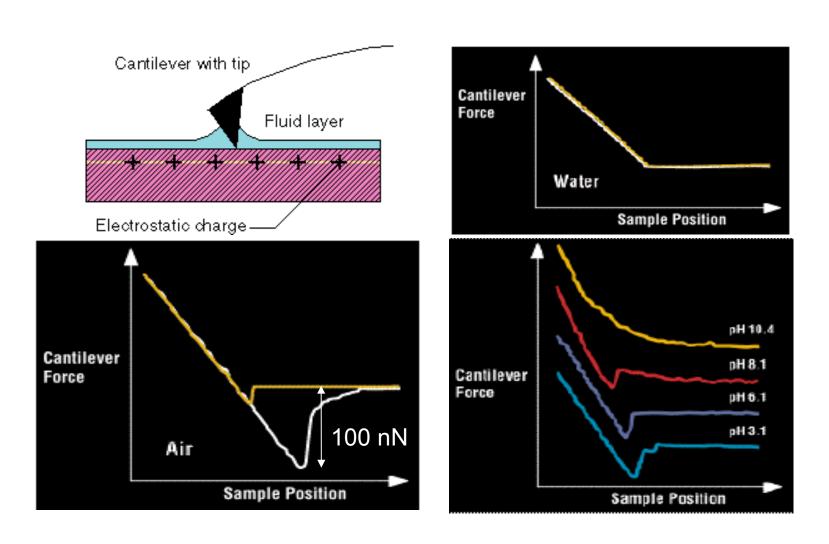
#### Constant-force

- Advantages:
  - Large vertical range
  - Constant force (can be optimized to the minimum)
- Disadvantages:
  - Requires feedback control
  - Slow response

#### Constant-height

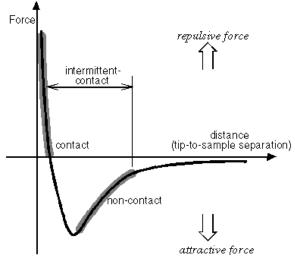
- Advantages:
  - Simple structure (no feedback control)
  - Fast response
- Disadvantages:
  - Limited vertical range (cantilever bending and detector dynamic range)
  - Varied force

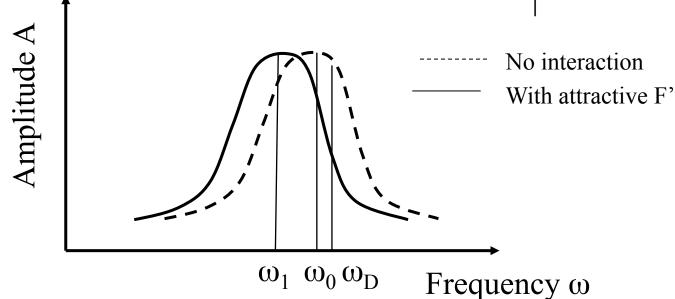
#### Problems with the contact mode



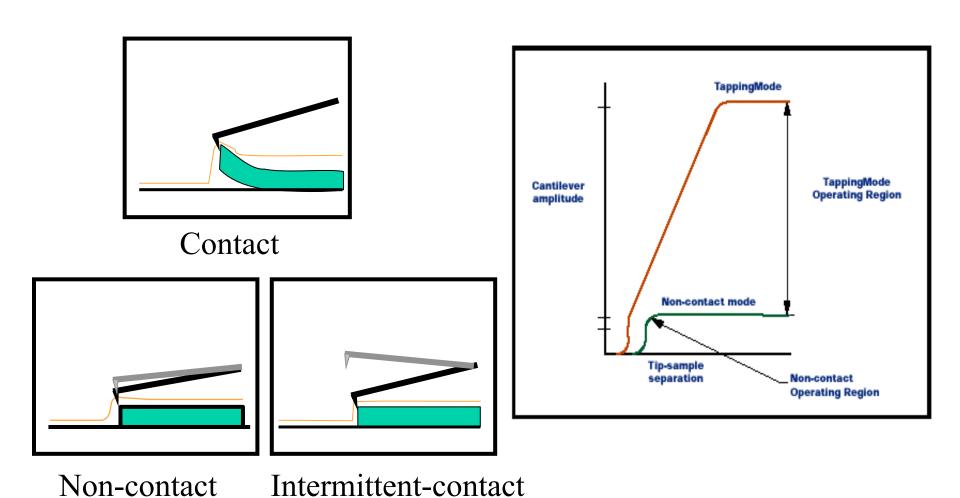
#### AC imaging mode

$$\omega_1 = \omega_0 (1 + F^2/2c)$$

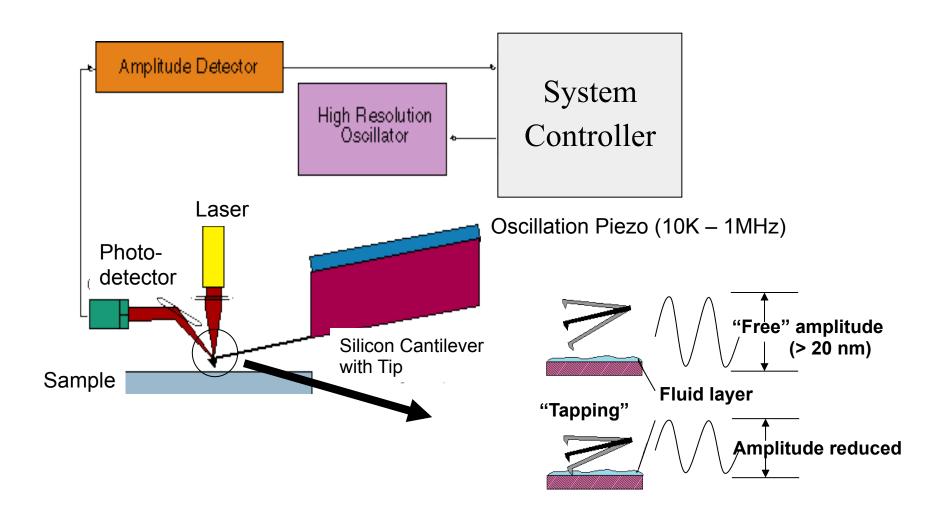




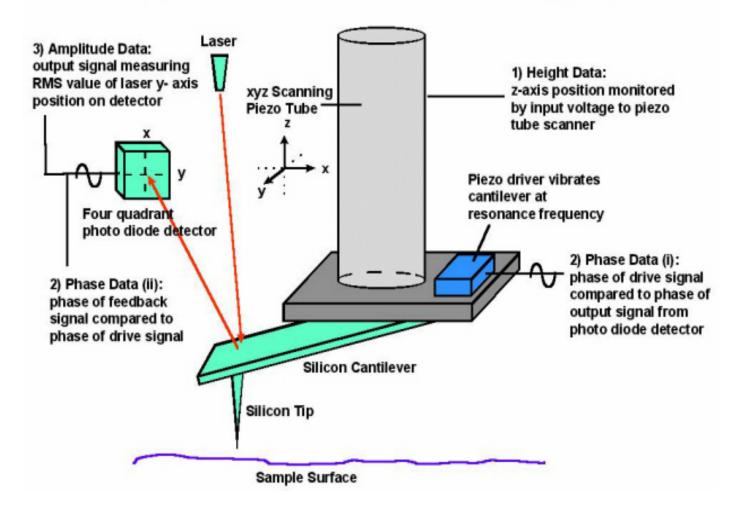
## Comparison of three scanning modes



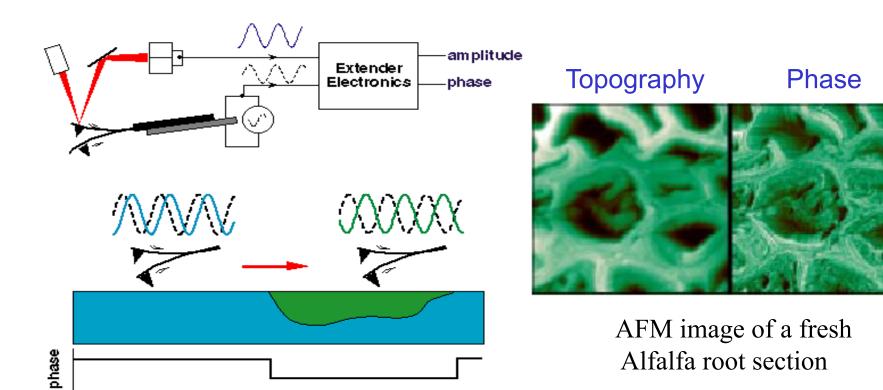
## Tapping mode



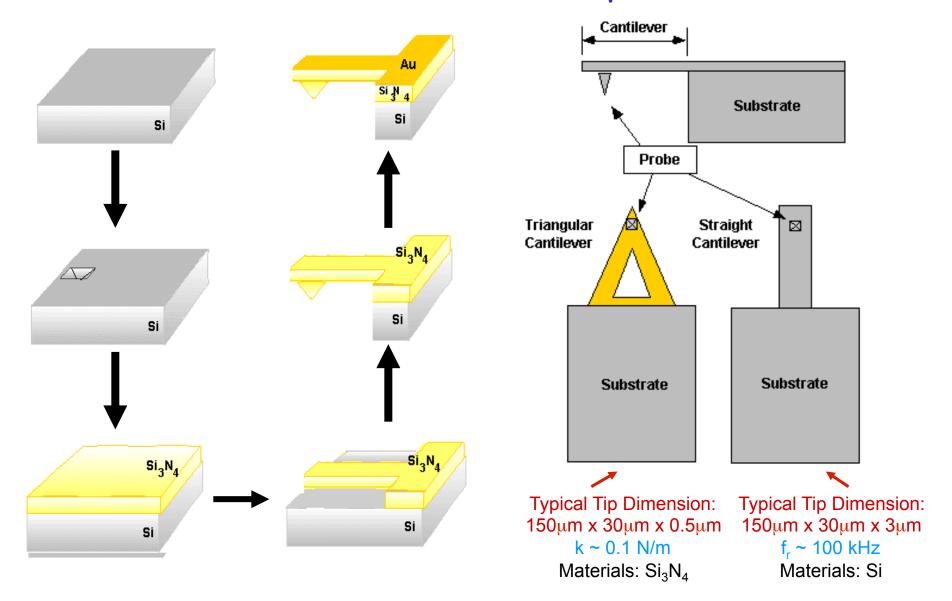
#### Three Types of Data Collected in Tapping Mode



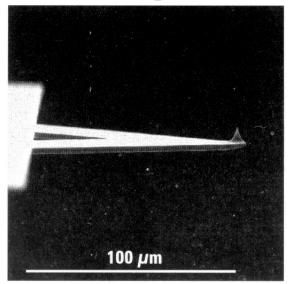
## Images by tapping mode



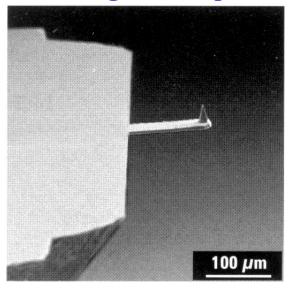
## Fabrication of AFM probes



#### V-shaped



Rectangular-shaped

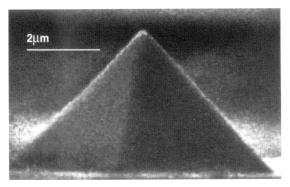


Materials: Si, SiO<sub>2</sub>, Si<sub>3</sub>N<sub>4</sub>

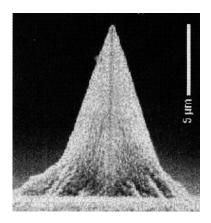
Ideal Tips: hard, small radius of curvature, high

aspect ratio

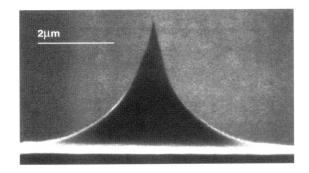
**Pyramid Tip** 

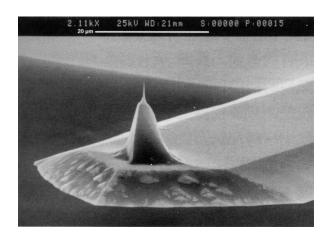


**Diamond-coated Tip** 



**Ultrasharp Tip** 





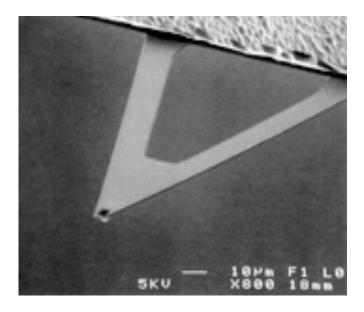
#### Criteria for AFM probe

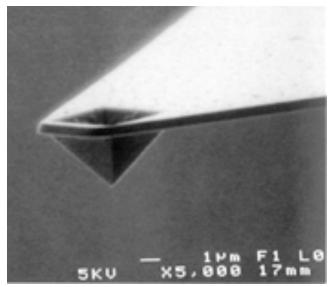
- 1) Small spring constant (k)  $F = k \Delta z$ To detect force of  $\sim nN$
- 2) High resonant frequency ( $f_r$ )  $f_r \propto (k/m)^{1/2}$ To enable scanning and other operations
- 3) Highly anisotropic stiffness

  Easy to bent and difficult to twist
- 4) Sharp protrusion at the apexTo better define the tip-sample interaction

#### Tip of small shear force

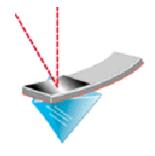
(for Contact mode)





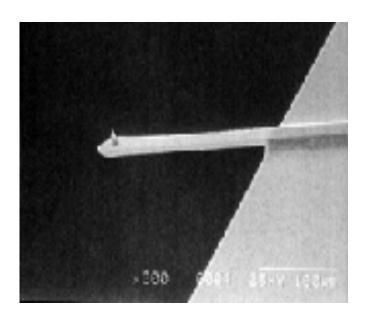
Typical Tip Dimension: 150μm x 30μm x 0.5μm  $k \sim 0.1$  N/m

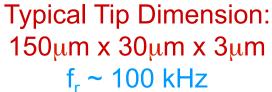
Materials: Si<sub>3</sub>N<sub>4</sub>



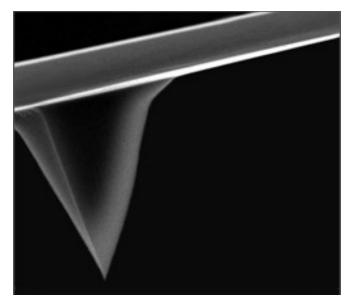
#### Tip of high resonant frequency

(for Tapping mode)





Materials: Si



#### AFM versus STM

- 1. Generally, STM has "better" resolution than AFM.
- 2. The force-distance dependence in AFM is much more complex when characteristics such as tip shape and contact force are considered.
- 3. STM is generally applicable only to conducting samples while AFM is applied to both conductors and insulators.
- 4. AFM offers the advantage that the writing voltage and tip-to-substrate spacing can be controlled independently, whereas with STM the two parameters are integrally linked.

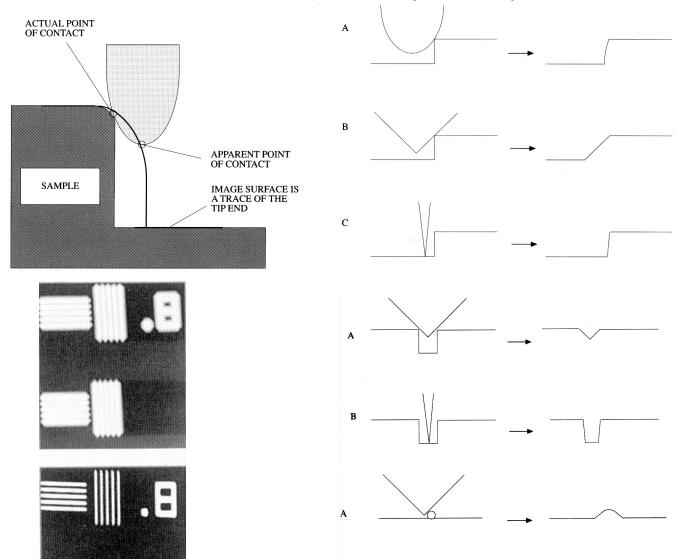
#### AFM versus EM

- 1. AFM only reveal the surface and EM can probe the interior structure of the sample with higher resolution.
- 2. AFM provides direct topographic measurements and EM provides only 2D projection of the sample structure.
- 3. No charging effect occurs in AFM. So, for insulating samples, no metallic coating is necessary.

#### AFM versus Optical Microscope

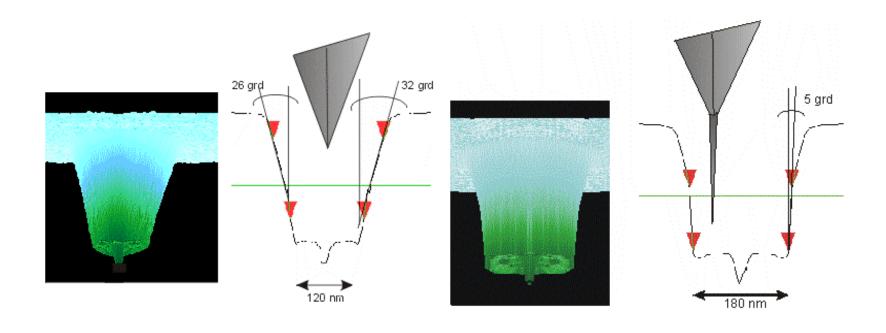
- 1. AFM has much better resolution than Optical Microscope (OM).
- 2. AFM provides unambiguous measurement of step heights, independent of reflectivity differences between materials.
- 3. OM can be applied to much faster dynamic studies with the pump-probe method.

## Effects of the Tip Shape

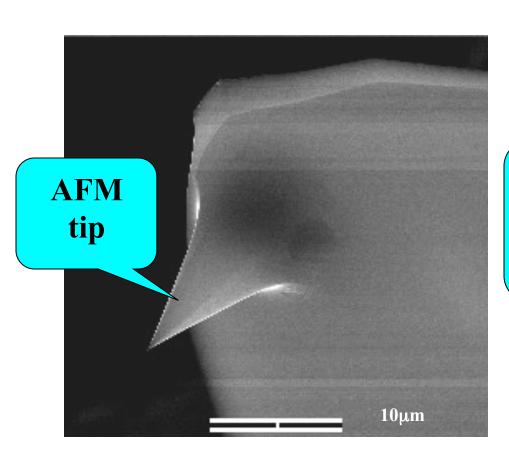


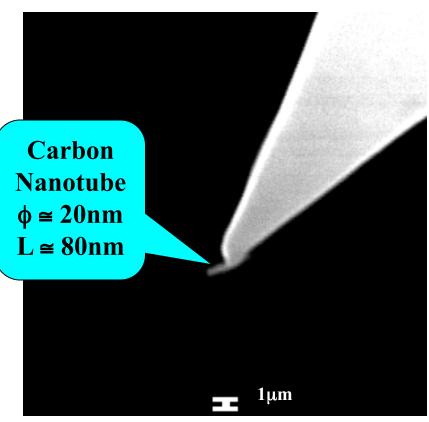
В

## Ultra-sharp tip

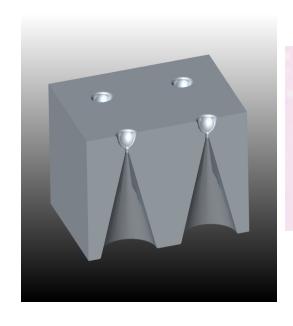


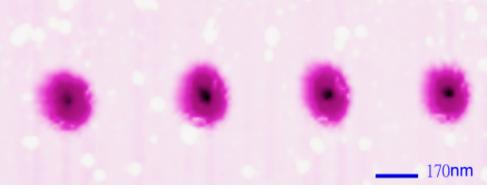
## AFM Tip + Carbon Nanotube





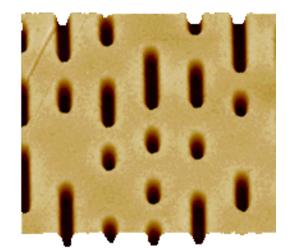
## Image of high aspect ratio



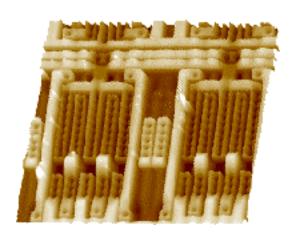


## AFM images

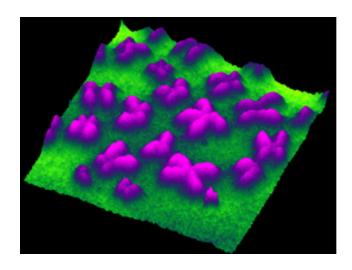
**CD** pits



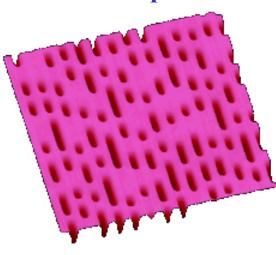
**Integrated circuit** 



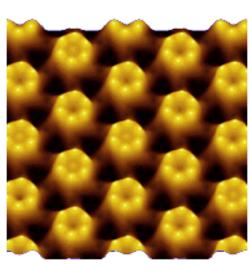
**Chromosomes** 



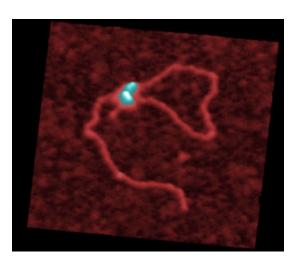
**DVD** pits



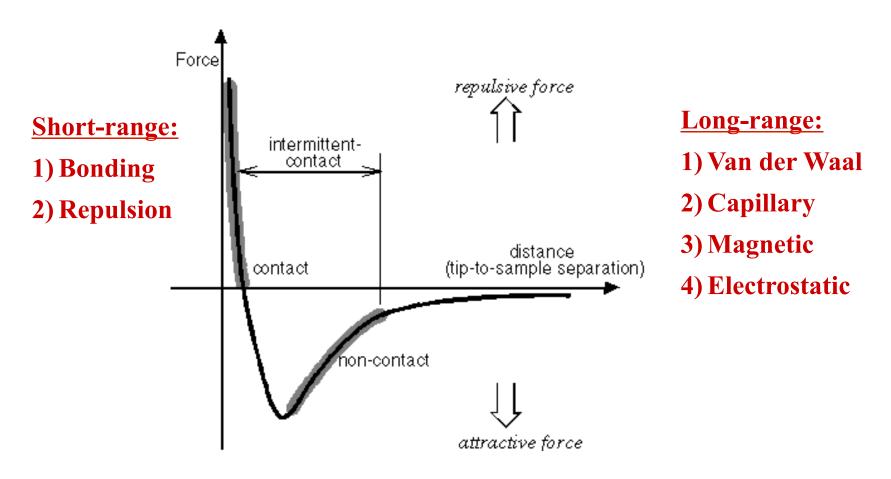
**Bacteria** 



**DNA** 

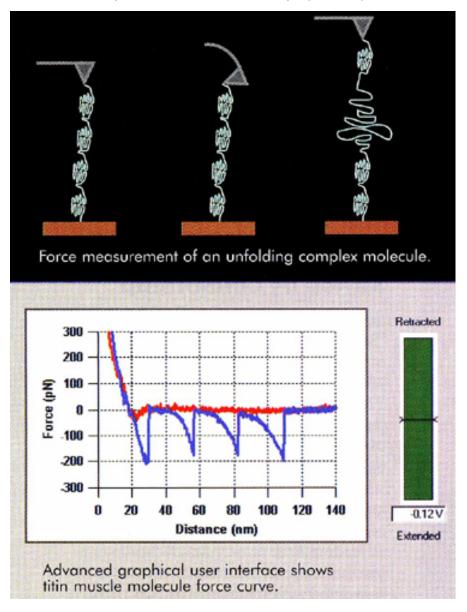


#### Interaction between the probe and sample

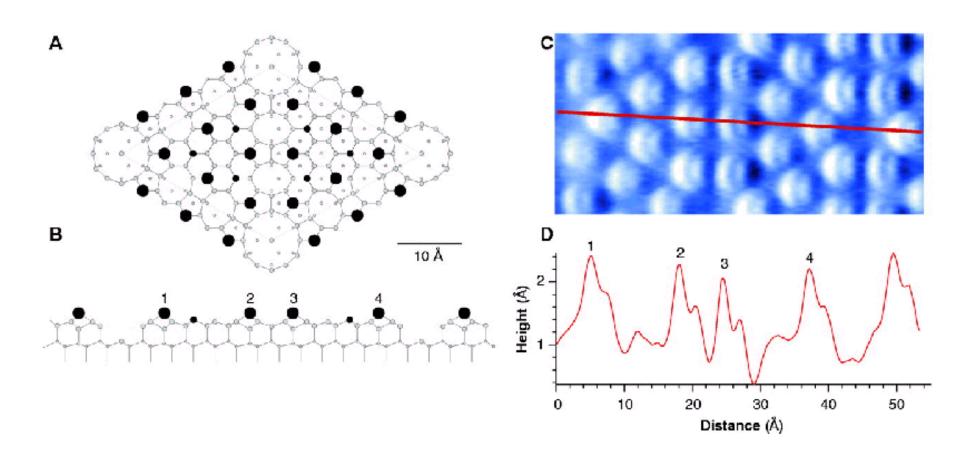


Lennard-Jones potential  $\phi(r) = -A/r^6 + B/r^{12}$ 

## Force spectroscopy by AFM

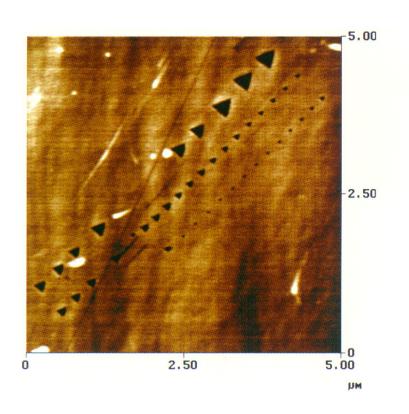


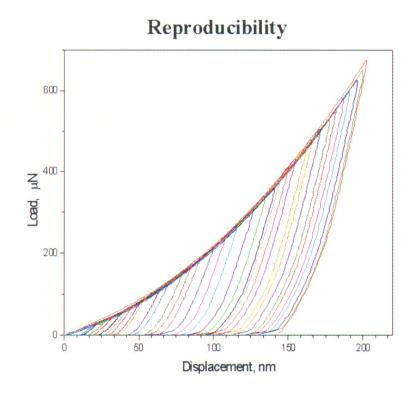
## Atomic Image of Si(111)-(7×7) Taken with AFM



F.J. Giessibl et al., Science 289, 422 (2000)

#### **Measurement of Mechanical Properties**





- 1. The load-displacement curves provide a "mechanical fingerprint" of material's response to deformation, from which parameters such as hardness and young's modulus of elasticity can be determined.
- 2. In measuring the mechanical properties of thin coated system, the size of contact impression should be kept small relative to the film thickness.

# Nanolithography of Tapping-Mode AFM

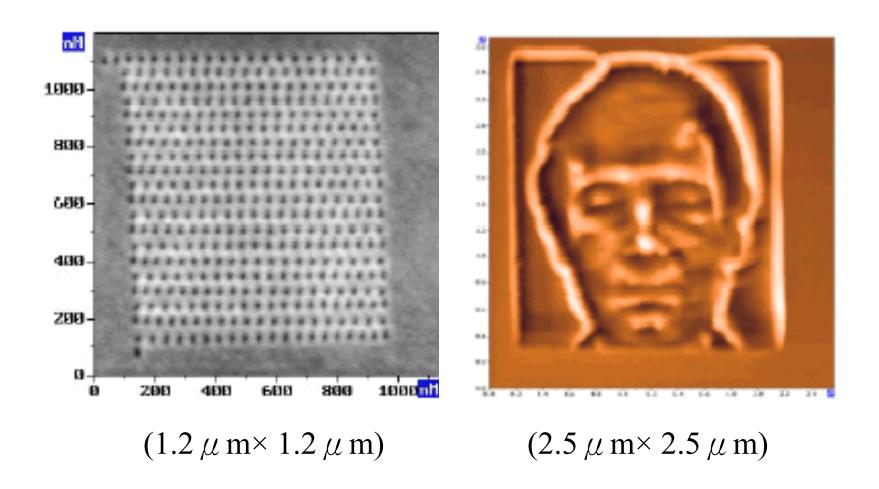
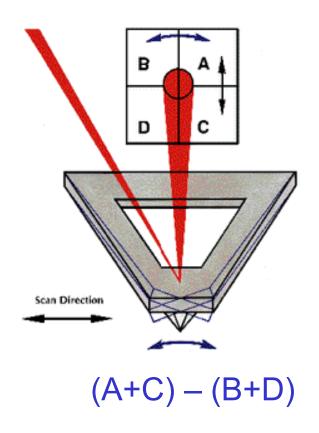
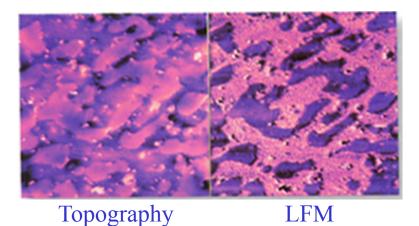


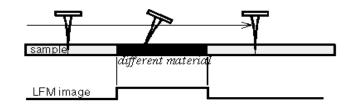
Image of polycarbonate film on silicon surface

#### Lateral Force Microscopy

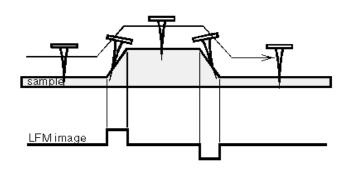




Nature rubber/EDPM blend



- LFM is sensitive to friction and chemical forces.
- Image contrast depends on the scanning direction.
- Surface roughness will contribute to the contrast.

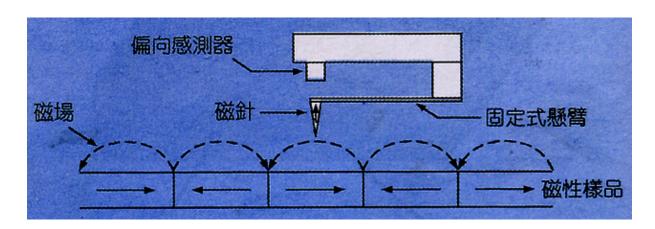


# Chemical Force Microscopy



CFM scan of well-defined regions that terminate in either methyl or carboxylic acid groups. When a carboxylic acid-terminated tip is used for imaging (left), the carboxylic acidterminated regions exhibit greater frictional force (lighter color) than the methyl-terminated regions. When a methylterminated tip is used (right), the friction contrast is reversed. No differences are revealed by the topographic AFM scan (not shown) since the functional groups are structurally quite similar. Image courtesy of Dr. C. Lieber, Harvard University.

# Magnetic Force Microscopy (MFM)



$$\mathbf{F} = \nabla(\mathbf{m} \cdot \mathbf{H})$$

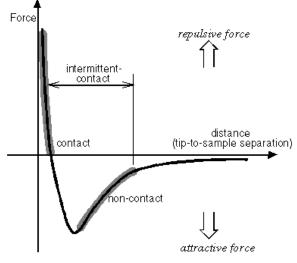
Tips: silicon probes are magnetically sensitized by sputter coating with a ferromagnetic material.

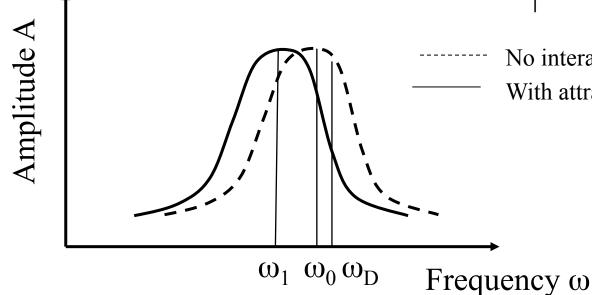
Resolution: 10 ~ 25 nm.

Applications: hard disks, magnetic thin film materials, micromagnetism.

# AC imaging mode

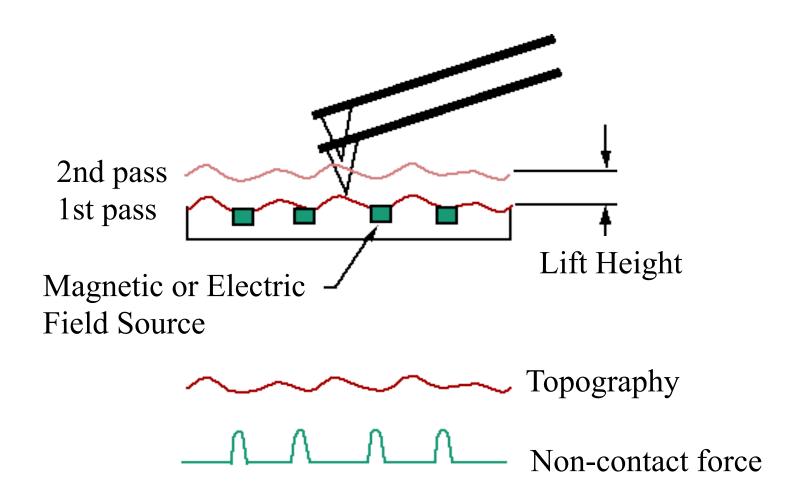
$$\omega_1 = \omega_0 (1 + F^2/2k)$$



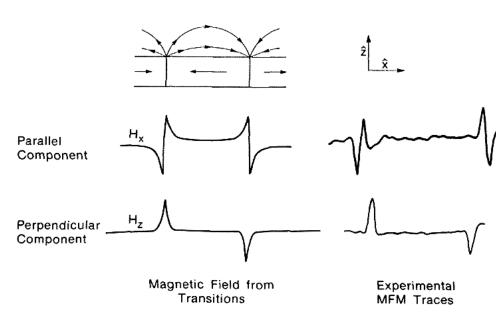


No interaction With attractive F'

#### Lift mode of AFM



#### MFM Images

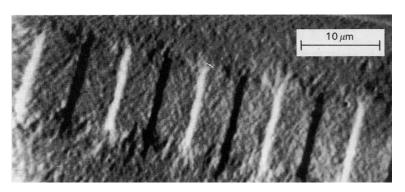


Tip as a point dipole

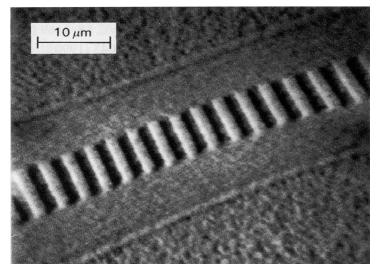
$$F_z = \partial (m_x H_x + m_y H_y + m_z H_z)/\partial z$$

Tip as a long rod

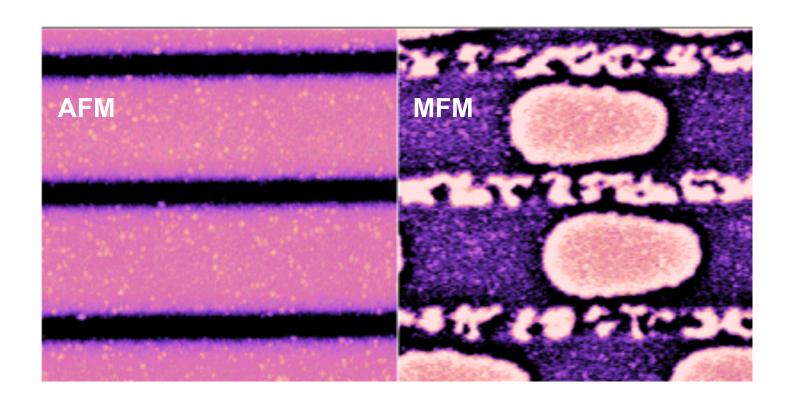
$$F_z = m_z H_z$$



$$\mathbf{m}^{\mathrm{T}} = \mathbf{m}_{\mathrm{Z}}$$

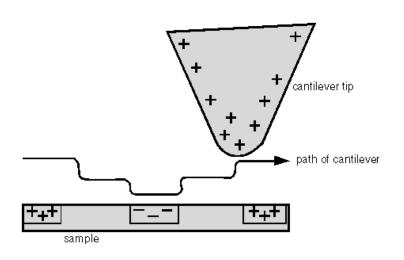


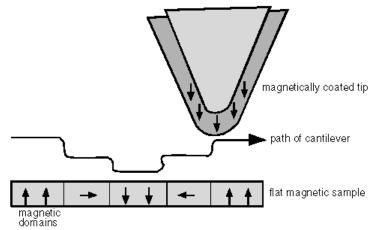
$$\mathbf{m}^{\mathrm{T}} = \mathbf{m}_{\mathrm{x}} + \mathbf{m}_{\mathrm{z}}$$

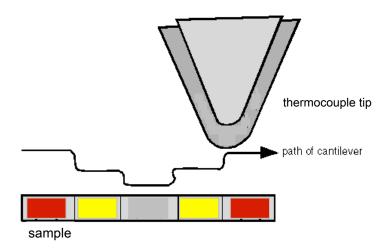


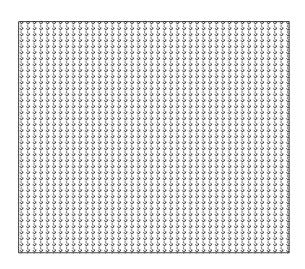
Bits (50 nm) on a magneto-optical disk Scan area (5µm× 5µm)

#### Probes of various functions

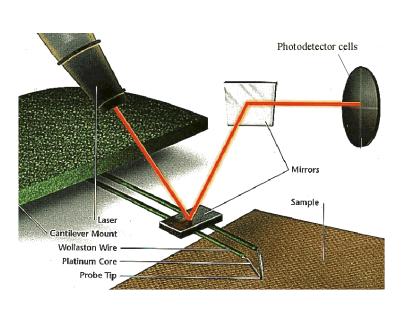


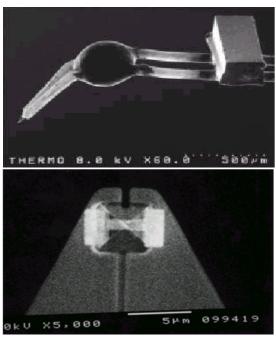


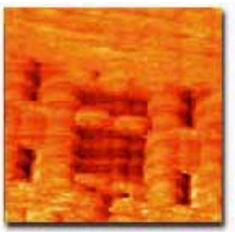


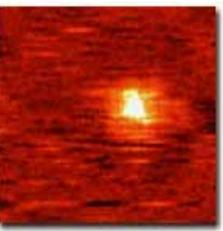


# Scanning Thermal Microscopy (SThM)



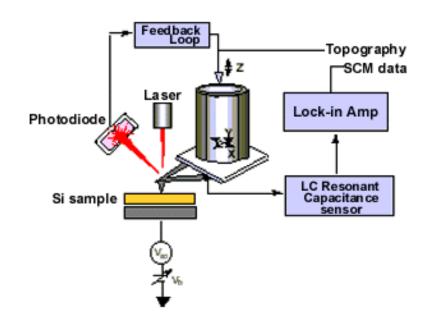


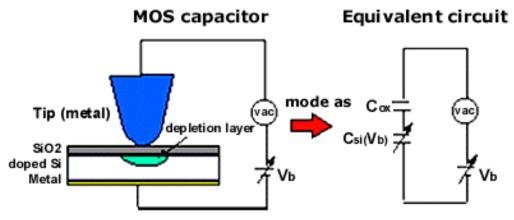




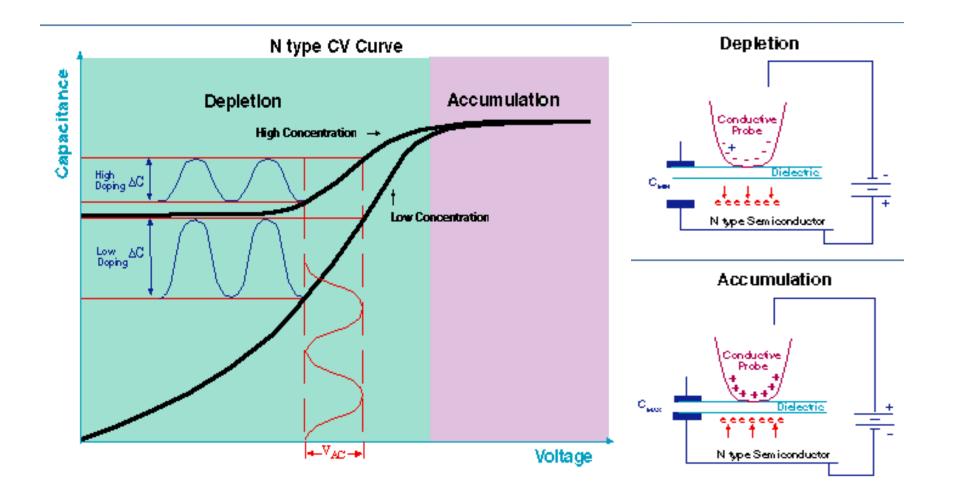
# Scanning Capacitance Microscopy (SCM)

#### Operational principle of the SCM

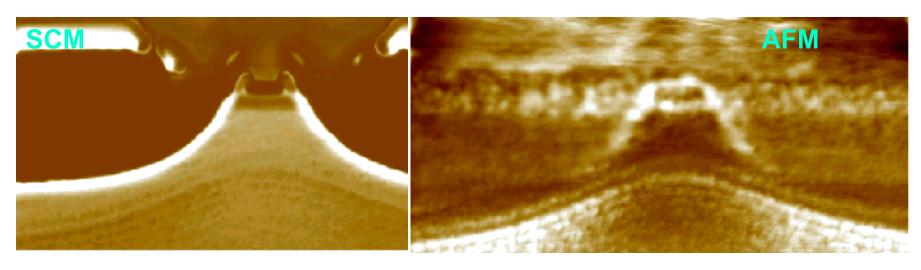


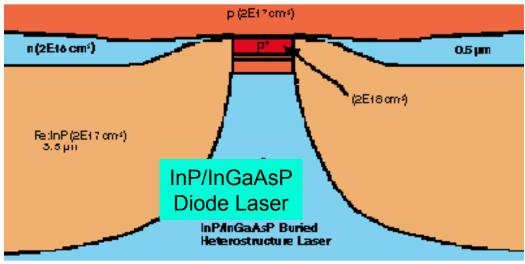


#### SCM CV Curve

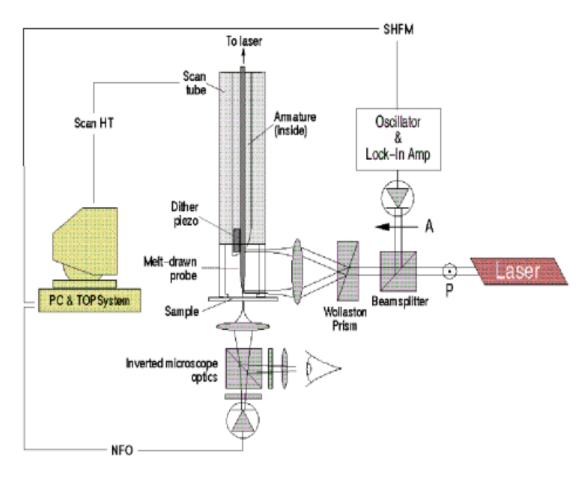


# Scanning Capacitance Microscopy



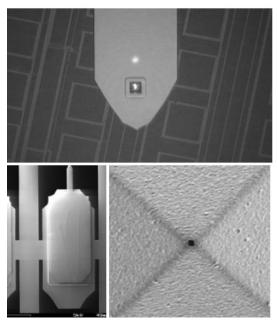


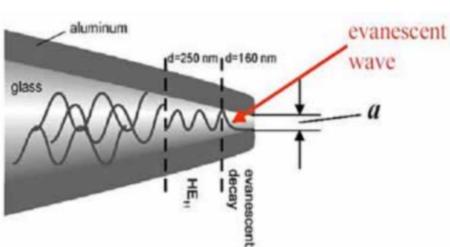
# Near-field Scanning Optical Microscopy (NSOM)

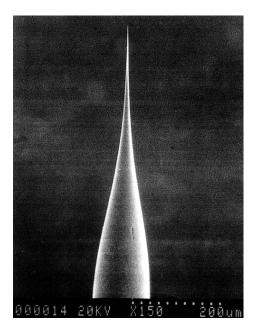


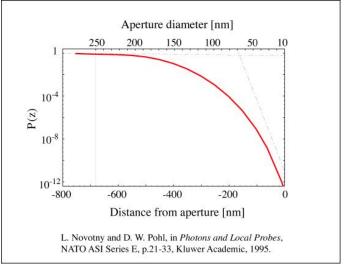
Shear force detection is used to regulate the tip/sample separation

#### Probes for NSOM

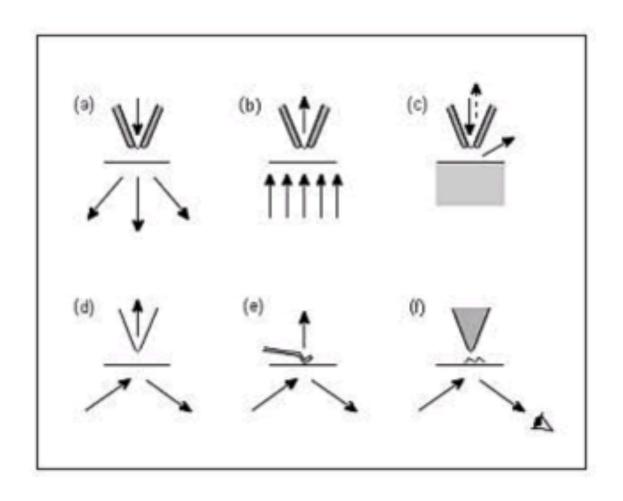






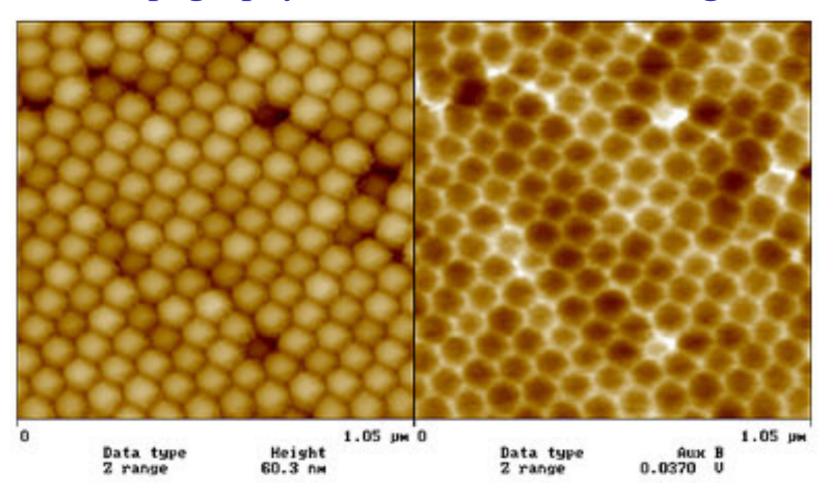


# Imaging modes for NSOM



#### **Topography**

#### **NSOM Image**



Polystyrenes of 100 nm on glass

- 1. All SPMs are based on the ability to position various types of probes in very close proximity with extremely high precision to the sample under investigation.
- 2. These probes can detect electrical current, atomic and molecular forces, electrostatic forces, or other types of interactions with the sample.
- 3. By scanning the probe laterally over the sample surface and performing measurements at different locations, detailed maps of surface topography, electronic properties, magnetic or electrostatic forces, optical characteristics, thermal properties, or other properties can be obtained.
- 4. The spatial resolution is limited by the sharpness of the probe tip, the accuracy with which the probe can be positioned, the condition of the surface under study, and the nature of the force being detected.